

Service Manual

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IMPORTANT NOTICE

Equipment improvement is an on-going process and, as such, changes may be made to the equipment after this manual is printed. Accordingly, Alcon makes no warranties, expressed or implied, that the information contained in this service manual is complete or accurate. It is understood that if this manual is used to perform service on the equipment by other than trained personnel, the user assumes all risks in the use of this manual.

In order to protect the goodwill associated with Alcon, and its products, maintain Alcon's standards, and provide its customers with a high quality of service, Alcon strongly recommends that all servicing of this equipment be performed by Alcon-trained service personnel. Such personnel receive in-depth, extensive training in the servicing of the equipment, including training in the diagnosis and correction of problems that may arise with the equipment. Any servicing of this equipment by persons other than Alcon-trained service personnel may expose those persons, subsequent users of this equipment, patients, and other third parties to significant risk of serious injury and/or death. Alcon will not assume responsibility for the effect of the repairs, damages, or personal injuries arising from repairs by any third party.

CAUTION

Federal law restricts this device to sale by or on the order of a physician.

WARNINGS AND CAUTIONS

Pay close attention to warnings and cautions in this manual. Warnings are written to protect individuals from bodily injury. Cautions are written to protect the instrument from damage.

UNIVERSAL PRECAUTIONS

Universal precautions shall be observed by all people who come in contact with the instrument and/or accessories to help prevent their exposure to blood-borne pathogens and/or other potentially infectious materials. In any circumstance, wherein the exact status of blood or body fluids/tissues encountered are unknown, it shall be uniformly considered potentially infectious and handled accordingly. This is in accordance with OSHA guidelines.

Comments or corrections concerning this manual should be addressed to:

Alcon Laboratories, Inc. Technical Services Group PO BOX 19587 Irvine, CA, USA 92623-9587

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SECTION ONE GENERAL INFORMATION

Introduction

The *Constellation*® Vision System is a multifunctional surgical tool for use in anterior and posterior segment ophthalmic surgeries. The product's capabilities include driving a variety of handpieces that provide the ability to cut vitreous and tissues, emulsify the lens, illuminate the posterior segment of the eye, and apply diathermy to stop bleeding. Vacuum is used to remove ocular matter from the eye and is provided by connecting tubing from the handpiece to a port on the fluidics cassette. Irrigation/infusion capability is provided to replace fluid in the eye, and enters the eye directly via either an infusion cannula or flows through a handpiece. The graphical operator interface is menu driven. The operator provides inputs using the touchscreen panel, the remote control, voice commands, and the footswitch.

The *Constellation®* Vision System is a multi microprocessor-controlled ophthalmic surgical instrument with associated memory and input/output (I/O) circuitry. The system communicates with the user via its Front Panel display, with voice confirmations, and with tones. An automatic self-test is initiated each time the system power is turned on.

This test performs a variety of functions including the following:

- Tests the Central Processing Unit (CPU)
- Tests the RAM and ROM memory, and the I/O circuits
- Initializes the system

When the system successfully completes the self-test, it automatically goes into the Setup mode. If the system fails the self-test, an error message is displayed.



Figure 1-1 The Constellation® Vision System - The Constellation® Vision System is a multifunctional surgical tool is used in anterior and posterior segment ophthalmic surgeries.



About This Manual

This manual is divided into seven sections as follows:

Section One - General Information

This section gives a general description of the *Constellation*® Vision System features and components. Cautions and Warnings, specifications, icons used with the system, and labels are also included.

Section Two - Theory of Operation

This section gives a detailed description of how the *Constellation*® Vision System operates starting at the system level and working down to the PCB (Printed Circuit Board) level. Detailed block diagrams are provided at the end of this section.

Section Three - Parts Location and Disassembly

This section contains parts location diagrams along with field level disassembly procedures.

Section Four - Maintenance & Troubleshooting

This section contains system maintenace procedures and troubleshooting information.

Section Five - Schematics

This section contains system interconnect diagrams, fluidic diagrams, pneumatic diagrams, and cabling schematics.

Section Six - Parts Lists and Drawings

This section contains parts lists and exploded drawings for each major assembly.

Section Seven - Additional Information

This section contains information on accessories or optional equipment that may require service.

Reference Documents

Although this manual provides the necessary information for maintaining optimum performance of the *Constellation®* Vision System, it does not contain all of the operating procedures or functional descriptions contained in the operator's manual. In addition, the Warnings and Cautions in the operator's manual also apply for this service manual. The operator's manual supplements information provided in this manual, and should be available onsite with the system.

If you have any questions or require additional information, please contact your local service representative or the Technical Services Department at:

Alcon Laboratories 15800 Alton Parkway Irvine, CA 92618 (949) 753-1393 (800) 832-7827

If you are located outside the United States, please contact your local authorized Alcon distributor.

CAUTION

Federal Law restricts this device to sale by or on the order of a physician.



Receiving Inspection

The system was inspected mechanically and electrically prior to shipment. If the shipping container appears damaged, ask that the carrier's agent be present when the system is unpacked. The system should be inspected for external damage (i.e. scratches, dents, or broken parts). If damage is discovered or if the system fails any of the functional tests notify the carrier and an Alcon representative. Retain the shipping container and packing material for the carrier's inspection. As necessary, file a claim with the carrier or, if insured separately, with the insurance company.

Table 1-1 **CONSTELLATION® VISION SYSTEM SPECIFICATIONS**

CONSOLE

DIMENSIONS:

Tabletop: Heiaht: 63.5 cm (25.0 inches)

> Width: 53.3 cm (21.0 inches) Depth: 57.2 cm (22.5 inches)

160.0 cm (63.0 inches) Base: Height:

> Width: 76.2 cm (30.0 inches) Depth: 77.5 cm (30.5 inches)

WEIGHT: Tabletop: 61.2 kg (135 pounds)

> Base: 72.6 kg (160 pounds)

Note: If a base other than the optional Alcon base is used, it must be able to hold up to 250 pounds.

ENVIRONMENTAL LIMITATIONS:

Operating Non-Operating Altitude: -125 to 2000 m -125 to 3000 m

(-410 to 6562 feet) (-410 to 9843 feet)

Temperature: 10° C to 35° C -10 to 55°C

(50° F to 95° F) (14° F to 131° F)

Relative Humidity: 10% to 95% 10% to 95% without without

condensation condensation

ELECTRICAL REQUIREMENTS: The console accepts the following ranges or input commercial power voltages and frequencies and meets the leakage currents specified in IEC 60601-1. Protection against electrical shock is Class I.

100-120 Vac 50/60 Hz 12 A max. 220-240 Vac 50/60 Hz 6 A max.

FOOTSWITCH

DIMENSIONS:

Height: 14.0 cm (5.50 inches) 22.9 cm (9.00 inches) Width: Depth: 43.2 cm (17.0 inches)

WEIGHT: 5.4 kg (12 pounds)

ENVIRONMENTAL: The footswitch construction is water tight in compliance with IEC

60601-1 and IEC 60601-2-2, subclause 44.6 aa.

ELECTRICAL: The footswitch is connected to the console via electrical cable. All power and communications enter/exit the footswitch from this cable.

PERFORMANCE SPECIFICATIONS

PRESSURIZED INFUSION/IRRIGATION @SEA LEVEL:

Range: 0 to 120 mmHa

Accuracy: ±(2% of setpoint +5 mmHa) Flow Rate: 0 - 20 cc/min. for infusion (20 Ga) 0 - 60 cc/min. for irrigation

Setpoint Transient: 500 ms maximum

IOP CONTROLLED INFUSION:

Setpoint Range: 0-120 mmHa Repeatability1: ± 2 mmHq² Setpoint Response Time: <500 ms (20 Ga)

Transient Disturbance

Response Time: <500 ms³ Flow Range: 0-20 cc/min

1 BSS Dual chamber mode.

² BSS medium, ²⁰ gauge high flow Cannula, steady state condition at rated flow range

³ Transient condition from no flow state to 10cc/min

ASPIRATION/SUCTION @SEA LEVEL:

Standard & Reduced

Pressure Range: 0-650 mmHa Vacuum Minimal Pressure Range: 0-600 mmHg Vacuum Pressure Accuracy: ±(2% of Setpoint +5 mmHq)

Flow Range:

Posterior Modalities: 0-20 cc/min Anterior Modalities: 0-60 cc/min

Transient Response Time

(Standard Pressure Range): From 0 to -400 mmHg @0 cc/min

10-90% Rise Time: 300 msec max 90-10% Fall Time: 300 msec max

VACUUM @ SEA LEVEL:

Vitrectomy: 0 to 650 mmHg Fragmentation: 0 to 650 mmHa Extrusion: 0 to 650 mmHg 0 to 650 mmHg Extraction: Irrigation/Aspiration: 0 to 650 mmHa Phacoemulsification: 0 to 650 mmHq

LOW PRESSURE AIR SOURCE (LPAS) @SEA LEVEL:

Pressure Range: 0 - 120 mmHg at rated flow Pressure Accuracy: ±3% of setpoint +3 mmHg Flow Rate: 1.2 slpm minimum at 120 mmHg

VITRECTOMY:

Submodes: 3D, Momentary, PropVac, VitWet

Cut Rate: UltraVit™ 5000 Probe:

100 to 5000 cpm UltraVit™ 2500 Probe: 100 to 2500 cpm

Table 1-1 CONSTELLATION® VISION SYSTEM SPECIFICATIONS...continued

PERFORMANCE SPECIFICATIONS...continued

DIATHERMY:

Frequency: 1.5 Mhz ± 10%. Waveshape: Sinusoidal

Output power 10 Watts maximum at 100% setting

with 75 ± 10% ohm non-inductive load 0 - 100% of maximum output power

ILLUMINATION:

Power range

Light Output through

20GA Fiber Probe: 0-200 hrs: 16 ± 6 lumens

at 115% set point 1

201-400 hrs:16 ± 6 lumens

at 115% set point 1

Light Output through

23GA Fiber Probe: 0-200 hrs: 23 ± 13 lumens

at 115% set point 1

201-400 hrs: 23 ± 13 lumens

at 115% set point 1

Light Output through

25GA Fiber Probe: 0-200 hrs: 18 ± 8 lumens

at 115% set point 1

201-400 hrs: 18 ± 8 lumens

at 115% set point 1

¹ Based on a representative nominal UFR fiber.

FRAGMENTATION:

Submodes: Linear, Fixed, Momentary
Tip Stroke @ 100%: 3.1 ± 0.5 mils at 100% power

Resonant Frequency: 39.0 ± 1.9 KHz Pulse Rate Range: 0 – 100 pps

SCISSORS:

Submodes: Proportional, Multi-Cut
Proportional Pressure: 0-50 psi @sea level
Multi Cut Rate: single cut to 450 cpm

PROPORTIONAL AND CONTINUOUS REFLUX @SEA LEVEL:

Pressure Range: 0 to 120 mmHg

Pressure Accuracy: $\pm (2\% \text{ of Setpoint } +5 \text{ mmHg})$

MICRO REFLUX:

Pressure Range: 100 ± 50 mmHg¹ Volume: 15 ± 10 µL¹

¹ measured with unoccluded 20 Ga *UltraVit*™ probe and aspiration tubing

VISCOUS FLUID CONTROL:

Submodes: Inject, Extract

Injection Pressure: 0 to 551.6 KPascal (0 to 80 psi)

0 to 482.7 KPascal

@ Reduced (0 to 70 psi)

Extract Vacuum

at Sea Level: 0 to 650 mmHg

AUTO-GAS FILLING (AGF):

Maximum Gas Pressure: 10 psig

Fill Purity: 97.1% gas concentration following 3 purges & 1 fill

AUTO-STOPCOCK:

Response Time:

Pressure (Liquid):

Rated Flow (Liquid):

Pressure (LPAS):

Rated Flow (LPAS):

0.5 seconds minimum
0-120 mmHg
20 cc/min
0-120 mmHg
1.2 slpm

PHACOEMULSIFICATION:

Submodes: Burst, Pulsed, Continuous

Tip Stroke @ 100%: 3.5 ± 0.5 mils

Resonant Frequency: 34khz – 42Khz ± 10%.
Pulse Rate Range: 0-100 pulses per second
Burst Length: 2.5 sec – user adjustable

Burst Pulse durations: 5 ms to 500 ms

ANTERIOR VITRECTOMY:

Submodes: Wet, Dry

Cut Rate: 0 to probe maximum

LASER (optional):

Treatment beam:

Class:

Power: 30 mW to 2 W (maximum)

Wavelength: 532 nm

Aiming beam:

Class:

Power: less than 1 mW Wavelength: 635 nm ± 5 nm

DOCTOR MEMORIES:

Storage Capacity: No hard limit; advisory displayed when

less than 15% of disk space is

available.

TIMER:

Range: 0 to 99:99:99

Resolution: 1 s

TONE VOLUMES @ 1 Meter:

Errors/Faults/Invalid Key: 40 to 65 dB, short tones
Diathermy: 40 to 65 dB, continuous tone
Advisory/Timer Expire/Elev Infusion: 0 to 65 dB, short tones

Frag/Phaco/Vacuum: 0 to 65 dB, continuous tone

Valid Key: Factory set and not adjustable Volume Accuracy: 6 dB

ŕ

VOICE CONFIRMATION: 0 to 65 dB

REMOTE CONTROL:

Method: Infrared Channels: 4



Table 1-2 TERMS AND ABBREVIATIONS

| Term or Abbreviation | Description |
|----------------------|---|
| ACMI connector | The type of connector used on fiber optic probes. |
| AGF | Auto-Gas Filling |
| BSS PLUS® | Sterile intraocular irrigating solution enriched with bicarbonate, dextrose, and glutathione. |
| CE | A mandatory conformity mark on many products placed on the single market in the European Economic Area (EEA) |
| cmH ₂ O | Centimeters of water |
| cpm | Cuts Per Minute |
| CSA | Mark indicate that a product, process or service has been tested to a Canadian or U.S. standard and it meets the requirements of an applicable CSA standard or another recognized document used as a basis for certification. |
| Detent | A discrete footpedal position at which more force is required to depress the footpedal to the next position. |
| Diathermy | The production of heat in body tissues by electric current for therapeutic purposes. |
| Extrusion | A mode where vacuum is available to remove fluid/matter. |
| F/AX | Fluid Air Exchange |
| Frag | Fragmentation |
| GA | Gauge |
| Global Function | A function whose status and controls are independent of the current footpedal position and surgery mode. |
| I/A | Irrigation/Aspiration |
| I/O | Input/Output |
| IOP | Intraocular Pressure |
| IEC | International Electromechanical Commission |

| Term or Abbreviation | Description |
|----------------------|--|
| ISO | International Standards Organization |
| IV | Intravenous |
| LCD | Liquid Crystal Display |
| mmHg | Millimeter of Mercury. A unit of vacuum. |
| Monolith | System configuration in which the <i>Constellation</i> ® tabletop and base are paired together. |
| N/A | Not Applicable |
| PEL | Patient Eye Level. A difference in height between the cassette and the patient eye level. |
| PIN | Personal Identification Number |
| psi | Pressure per Square Inch. A unit of pressure. |
| pps | Pulses Per Second |
| RS-232 | A standard for serial binary data signals commonly used in computer serial ports. |
| slpm | Standard Liters Per Minute |
| Type BF | A classification for devices that have conductive contact with the patient, or have applied parts that are fixed in medium or long term contact with the patient |
| U/S | Ultrasound |
| USB | Universal Serial Bus |
| VFC | Viscous Fluid Control |
| VGA | Video Graphics Array |
| Vit | Vitrectomy. Extraction of the vitreous from the vitreous cavity. |

Figure 1-2 ICONS USED WITH THE CONSTELLATION® VISION SYSTEM

| | Extrusion | | Modify | Hl | Dr. Filter | ((\psi)) | Non-ionizing Radiation |
|------------|---------------------------|------------------------|---|-------------|-----------------------------------|-------------------|--|
| | Forceps | 0 | Power | | Eject | 0 | Off |
| | | | Save | \Diamond | Equipotentiality | | On Consult Operator's |
| | Fragmentation | AC ◀ | AC In AC Out | <u>></u> | Footswitch | <u>^!\</u> | Manual, or System Error, or Advisory Opens |
| | Irrigation/ Aspiration | \$ | Aiming Beam | Y | Forceps | | Operator's Manual |
| | | * | Air Pressure Input | | Hot | • | Ready |
| | Laser | Ā | Suto Gas Filling (AGF) | | Illuminator | -\ \ \ | Remote Door Lamp Laser Status |
| | Phaco | \sim | Alternating Current | \supset | I/O Data Key Switch | | Remote Interlock |
| | Scissors | (€/ (€ ① | CE mark to RTTE directive | ÷ | Laser | X | Scissors Connector |
| | Viscous | C E 0123 | CE mark to MD directive | STOP | Connection Laser Emergency Stop | ♦ | Serial In/Out |
| | Fluid Control (VFC) | € | CSA Mark in accordance to CSA C22.2 No. 601.1 and UL 60601-1 | <u> </u> | Switch Laser Port 1 | O | Standby State System Fault |
| | Vitrectomy | c ® us | (LR 103168) IEC 60601-1-2, IEC 60601-2-2, & | * | Tethered Laser | SYSTEM | System System Information |
| | | • | IEC 60601-2-22 Coagulation Connector | *** | Manufacture Date | Ţ. | Type BF Equipment |
| | Expand Window | | Connection Indicator | | Multi-Function Port Network | | U/S Handpiece Connecor |
| Help Video | Help Video | | Dangerous Voltage | 윰 | Connection | • √• | USB Connector |

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Figure 1-2 ICONS USED WITH THE CONSTELLATION® VISION SYSTEM. . . continued

| X | Use appropriate take-back system |
|-----------|---------------------------------------|
| REC | Video Recorder Control |
| | Viscous Fluid Control Connector |
| ○○ | VGA Out |
| •00 | Video In |
| ○○ | Video Out |
| 3 | Vitreous Cutter Connection |





DANGER: RISK OF EXPLOSION IF USED IN THE PRESENCE OF FLAMMABLE ANESTHETICS.

DANGER: RISQUE D'EXPLOSION. NE PAS EMPLOYER EN PRESENCE D'ANESTHESIQUES INFLAMMABLES.

CAUTION: GROUNDING RELIABILITY CAN ONLY BE ACHIEVED

WHEN EQUIPMENT IS CONNECTED TO AN EQUIVALENT RECEPTACLE MARKED HOSPITAL GRADE.

CAUTION: RISK OF BURNS AND FIRE - DO NOT USE NEAR CONDUCTIVE MATERIALS. RENEW ELECTRODE

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CABLES UPON EVIDENCE OF DETERIORATION.

FCC ID: VMC212-1 IC: 7345A-2121

This device complies with part 15 of the FCC rules. Operation is subject to the following two conditions: (1) This device may not cause harmful interference, and (2) this device must accept any interference received, including interference that may cause undesired operation.

CE

Contains:
FCC ID: VMC212WIFI
10 70454 242WIFI
10 70454 242WIFI Contains:

| | 10.7 | 0 10/1 |
|-----------|-------------------|-----------------|
| DIATHERMY | $\Lambda \Lambda$ | ∼ MED |
| 10 | CAUTION | |





ALCON LABORATORIES, INC. 6201 SOUTH FREEWAY FORT WORTH, TX 76134-2099 USA MADE IN USA

For applicable patents, please see the ABOUT screen on the monitor during operation.

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OUTPUT

POWER

(W)

IMPEDANCE

 (Ω)

FREQUENCY

(MHz)



212-3019-001 REV P0



400-825 kPa



103-107 kPa





Labels for gas containers

USA - THIS SYSTEM CONFORMS TO ALL APPLICABLE STANDARDS OF THE RADIATION CONTROL FOR HEALTH AND SAFETY ACT OF 1988. COMPLIES WITH 21 CFR 1040.10 AND 1040.11 EXCEPT FOR DEVIATIONS PURSUANT TO LASER NOTICE NO. 50 DATED JULY 26, 2001.

Figure 1-3 LABELING ON CONSTELLATION® VISION SYSTEM

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Figure 1-4 The Startup Screen





Figure 1-5 The Main Screen



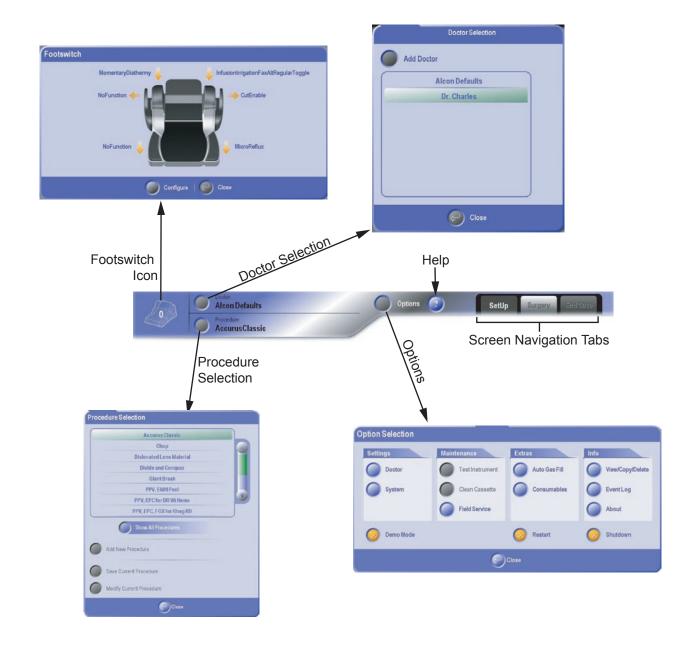


Figure 1-6 The Menu Bar





Figure 1-7 The Procedure Modify Screen (Menu Bar/Procedure button/Modify Procedure)



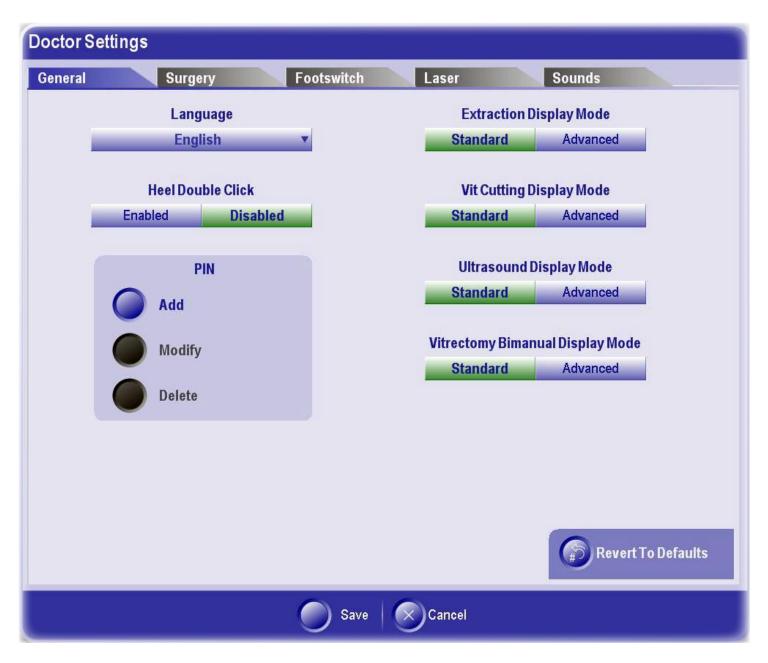


Figure 1-8 Doctor Settings Popup - General Tab (Options/Doctor Settings/General tab)





Figure 1-9 Doctor Settings Popup - Surgery / Inf / Irr Tab (Options/Doctor Settings/Surgery/Inf/Irr tab)





Figure 1-10 Doctor Settings Popup - Surgery / Reflux Tab (Options/Doctor Settings/Surgery/Reflux tab)



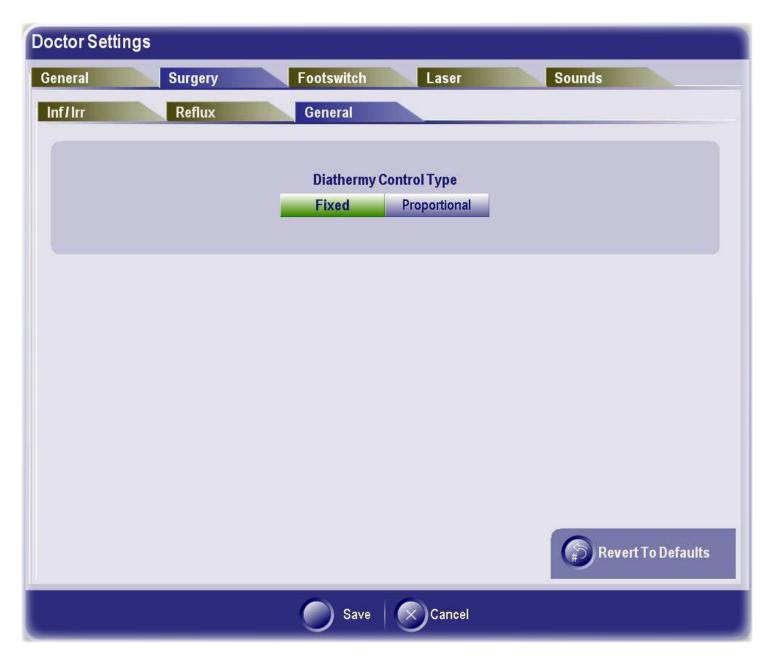


Figure 1-11 Doctor Settings Popup - Surgery / General Tab (Options/Doctor Settings/Surgery/General tab)





Figure 1-12 Doctor Settings - Footswitch Buttons Screen (Options/Doctor Settings/Footswitch/Buttons tab)





Figure 1-13 Footswitch Action Selection Popup



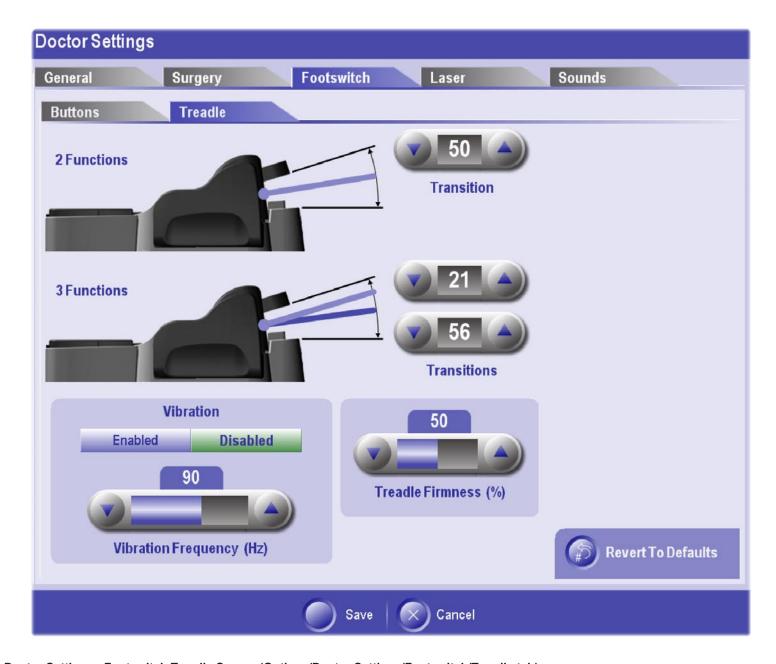


Figure 1-14 Doctor Settings - Footswitch Treadle Screen (Options/Doctor Settings/Footswitch/Treadle tab)





Figure 1-15 Doctor Settings - Laser Screen (Options/Doctor Settings/Laser tab)





Figure 1-16 Doctor Settings - Sound Screen (Options/Doctor Settings/Sound tab)





Figure 1-17 System Settings - Settings Screen (Options/System Settings/Settings tab)





Figure 1-18 System Settings - Connection Screen (Options/System Settings/Connection tab)





Figure 1-19 System Settings - Remote Control Screen (Options/System Settings/Remote Control tab)



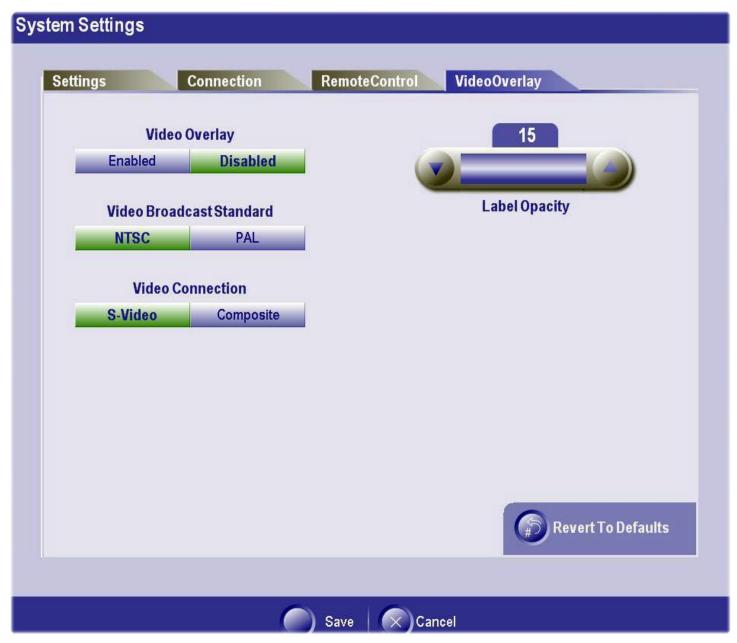


Figure 1-20 System Settings - VideOverlay Screen (Options/System Settings/VideoOverlay tab)





Figure 1-21 Auto Gas Fill Popup (Options\Settings-System\Extras\Auto Gas Fill)



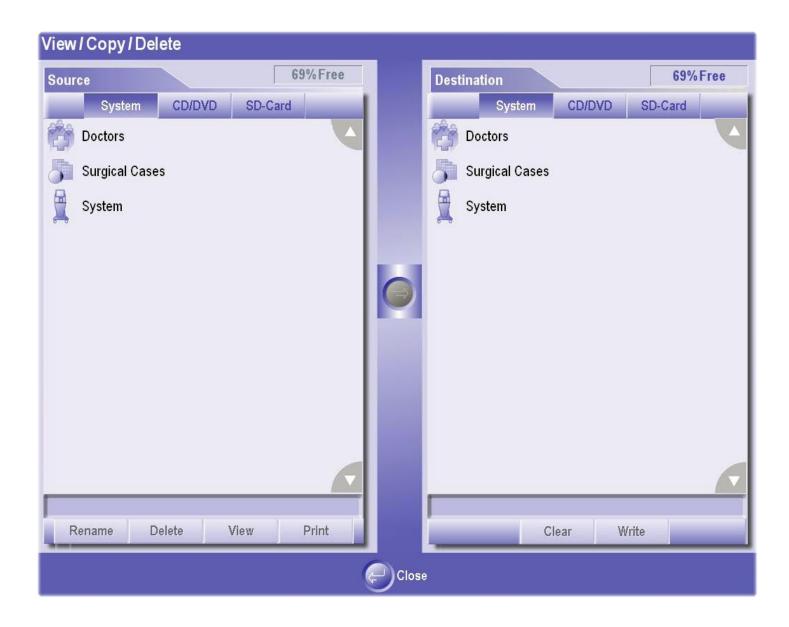


Figure 1-22 View / Copy / Delete Screen (Options\Settings-System\Info)



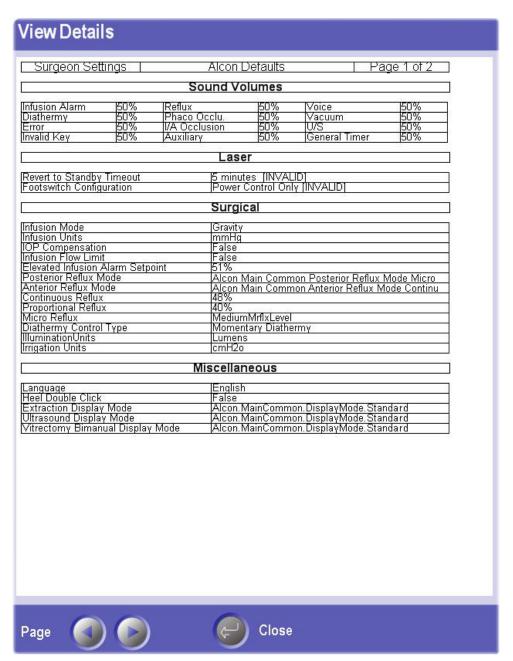


Figure 1-23 Sample View of a Doctor Settings Report





Figure 1-24 Event Log (Options\Settings-System\Info)





Figure 1-25 About Constellation (Options\Settings-System\Info)



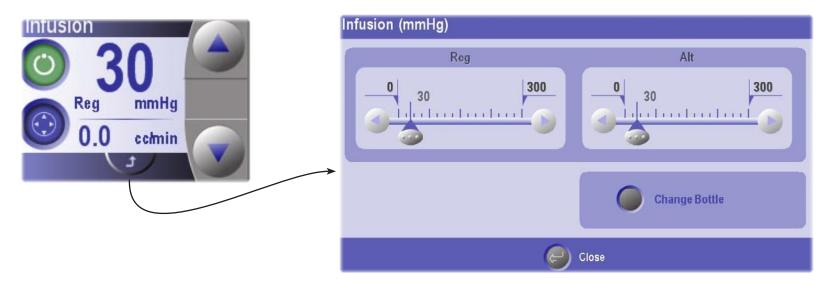


Figure 1-26 Infusion Global Control and More Information Popup

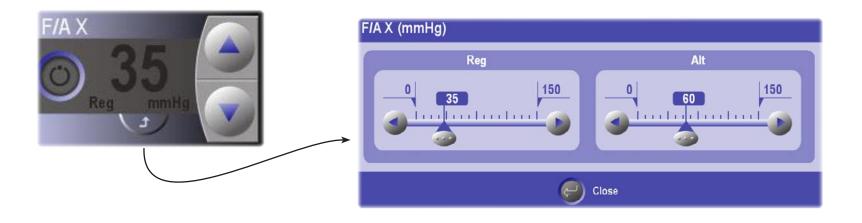


Figure 1-27 F/AX Global Control and More Information Popup



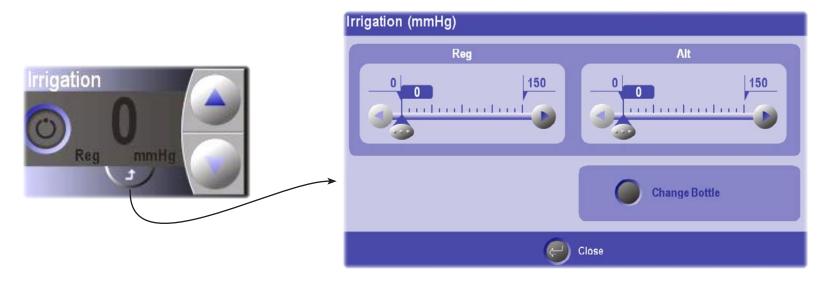


Figure 1-28 Irrigation Global Control and More Information Popup

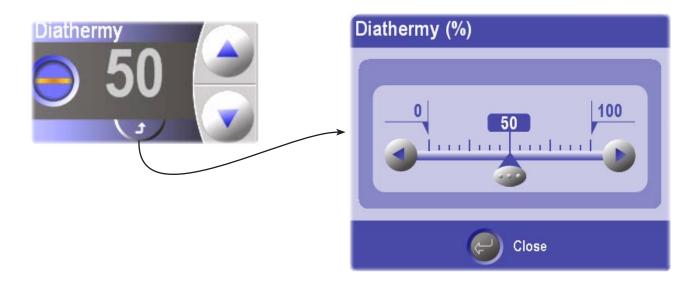


Figure 1-29 Diathermy Global Control and More Information Popup



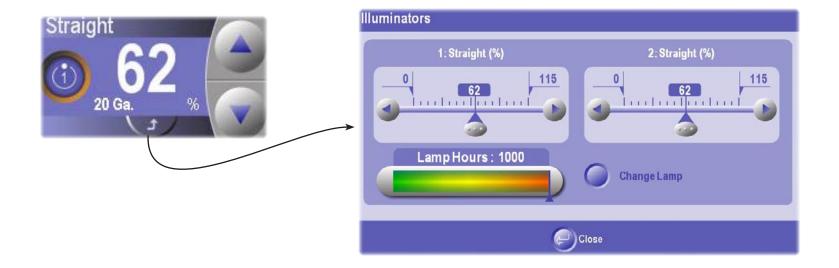


Figure 1-30 Illuminator Global Control and More Information Popup





Figure 1-31 The Setup Screen



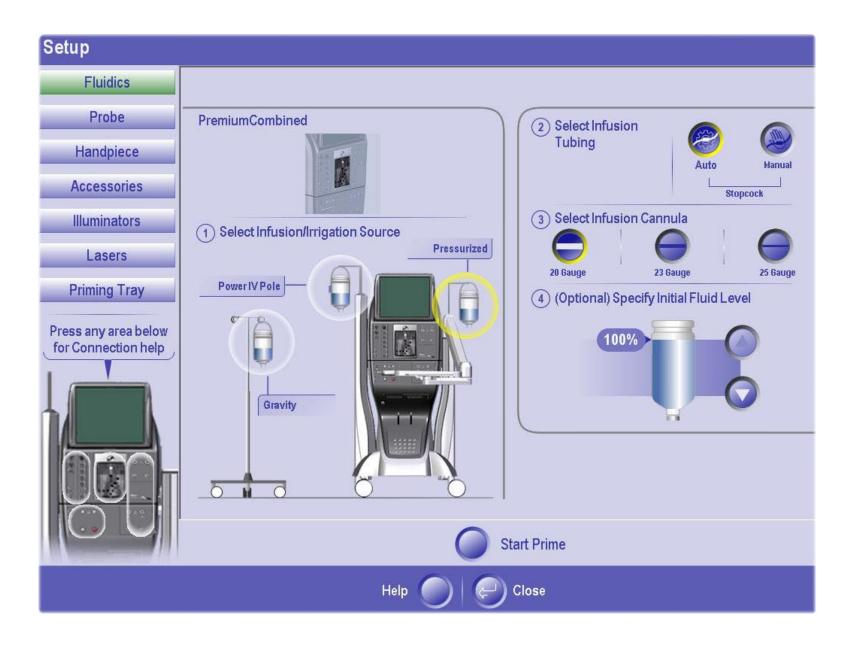


Figure 1-32 The Detailed Fluidic Setup Panel



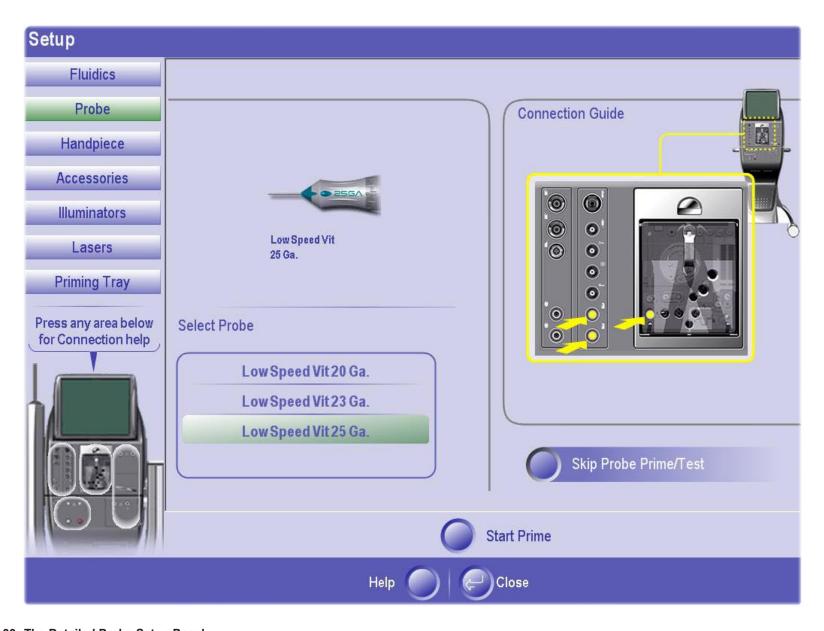


Figure 1-33 The Detailed Probe Setup Panel



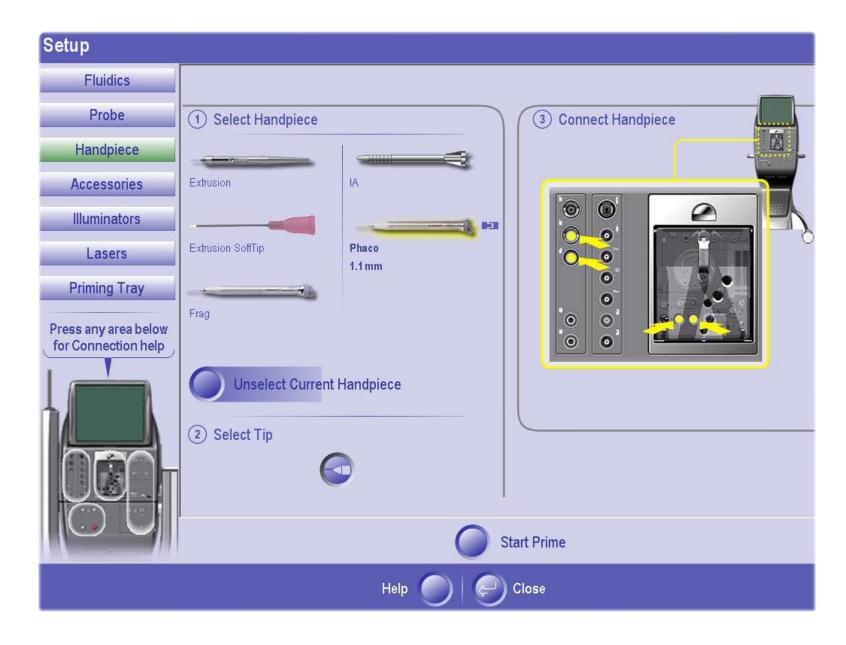


Figure 1-34 The Detailed Handpiece Setup Panel





Figure 1-35 The Detailed Accessory Setup Panel





Figure 1-36 The Detailed Illuminator Setup Panel





Figure 1-37 The Detailed Laser Setup Panel



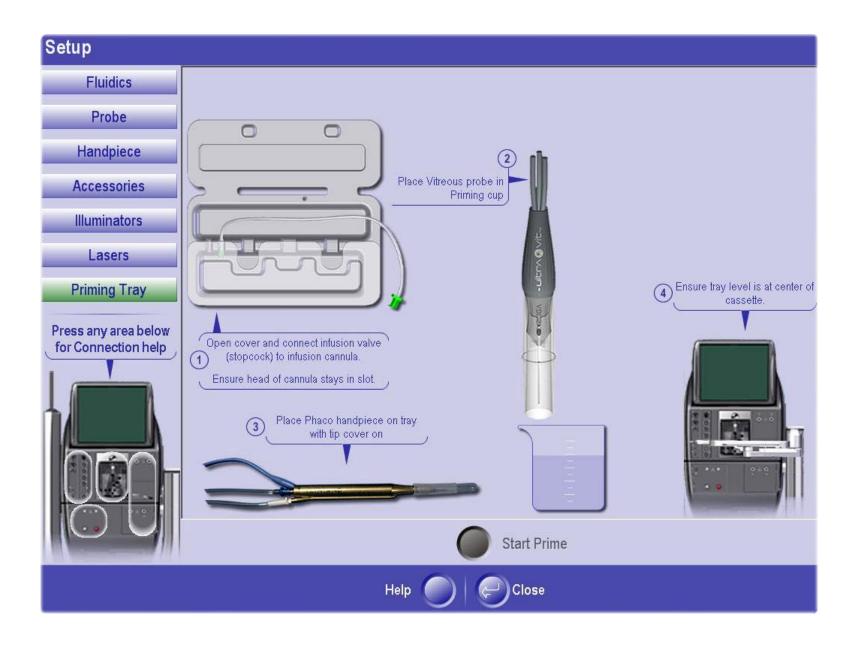


Figure 1-38 The Detailed Priming Tray Setup Panel









Figure 1-39 Video Help Popups



Figure 1-40 Prime & Test Status Bar

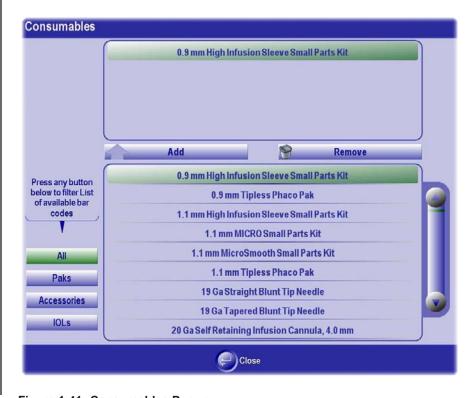


Figure 1-41 Consumables Popup





Figure 1-42 The Surgery Panel





Figure 1-43 Timer Popup





Figure 1-44 Accurus® Classic Surgery Screen





Figure 1-45 Vitrectomy Surgery Screen: 3D Submode





Figure 1-46 Vitrectomy Surgery Screen: Momentary Submode





Figure 1-47 Vitrectomy Surgery Screen: PropVac Submode





Figure 1-48 Vitrectomy Surgery Screen: VitWet Submode





Figure 1-49 Phaco Surgery Screen: Burst Submode





Figure 1-50 Phaco Surgery Screen: Custom Submode





Figure 1-51 Phaco Surgery Screen: Pulsed Submode





Figure 1-52 Phaco Surgery Screen: Continuous Submode





Figure 1-53 Fragmentation Surgery Screen: Fixed Submode





Figure 1-54 Fragmentation Surgery Screen: Linear Submode





Figure 1-55 Fragmentation Surgery Screen: Momentary Submode





Figure 1-56 Irrigation/Aspiration Surgery Screen





Figure 1-57 Extrusion Surgery Screen





Figure 1-58 Laser Surgery Screen





Figure 1-59 Forceps Surgery Screen





Figure 1-60 Scissors Surgery Screen: Multicut Submode





Figure 1-61 Scissors Surgery Screen: Proportional Submode





Figure 1-62 VFC Surgery Screen: Extract Submode





Figure 1-63 VFC Surgery Screen: Inject Submode



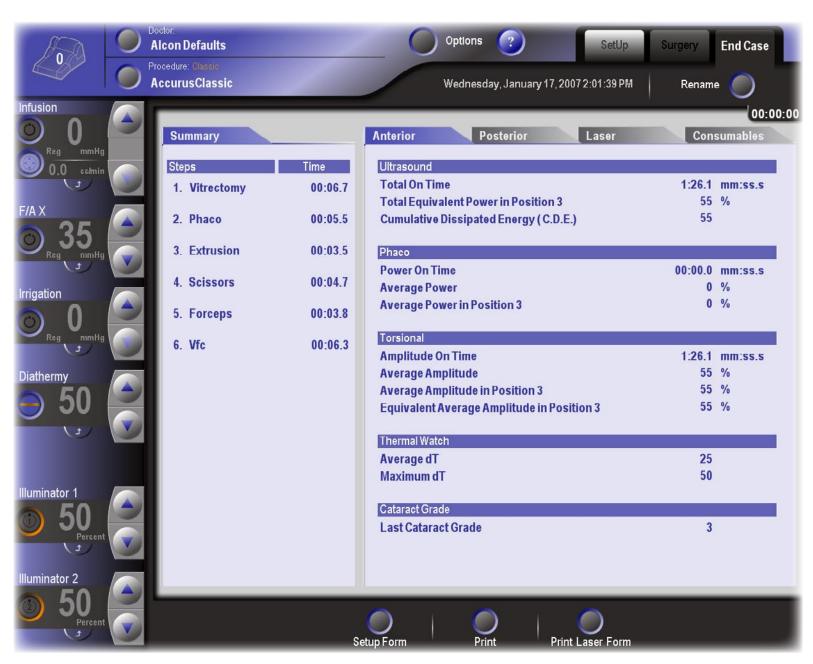


Figure 1-64 End Case Screen: Anterior Tab

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End Case Form Settings EditForm OPERATIVE RECORD Alcon Research, Ltd. (Patient Label) 15800 Alton Parkway Irvine, California 92618 Case Surgeon Scrub Nurse Thursday, July 12, 2007 3:31:00 PM Alcon Defaults 7/12/2007 Start Time End Time PROCEDURE SUMMARY: Data Field Procedure Name AccurusClassic Text Step Name Step Time (mm:ss.s) 1. Phaco 00:12.7 IrrigationAspiration Vitrectomy 00:04.5 00:05.2 Arial 4. Extrusion 00:05.3 5. Laser 6. Scissors 7. Forceps 00:02.7 Style Size 00:03.6 00:04.1 Regular V 8. Vfc 00:07.1 ANTERIOR METRICS: Ultrasound Value Units Total On Time 00:00.0 mm:ss.s Borders Total Equivalent Power in Position 3 0 R В Cumulative Dissipated Energy (C.D.E.) 0 n/a Phaco Power On Time 00:00.0 mm:ss.s Table -Average Power Average Power in Position 3 0 % Table Ins Del Cataract Grade Last Cataract Grade Column Row 1 W Height% 5 🔻 Width% Ins Del Ins Del Revert to Defaults Form 129873 Rev 12/06 Page 1 of 2 Page Close Cancel

Figure 1-65 End Case Screen: Setup Form



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SECTION TWO THEORY OF OPERATION

Constellation® Vision System Overview

The *Constellation*® Vision System can be used as a standalone tabletop system, or as a single monolith system when combined with the *Constellation*® base.

The Console and Base are fastened together mechanically and electrically to create the monolith assembly. The Console and Base are connected together electrically (power, communication, power supply) with cables between each component's rear panel connectors, completing the monolith assembly. Optional modules are connected through the appropriate connector on either the Console or Base.

Following is a general overview of all the modules that make up the *Constellation*[®] Vision System.

Console Power Module

The console power module distributes power through a single 24 VDC power bus. The power system as a whole is comprised of five major functional blocks:

- AC input
- Power conversion
- Power distribution
- Host battery backup including charger
- Dedicated host DC power converter module

The five blocks work together to convert a universal 90-264 VAC 50/60Hz input into a 24 VDC regulated power buss that meets the system's total power requirements.

Host Module

The host module provides the computing platform for the host software and Graphical User Interface (GUI). It is responsible for communicating configuration control to subsystems, and displaying subsystem real-time parameter data within context on the GUI. The host module is comprised of a PC motherboard, CPU, memory, peripheral devices, host power interface, and I/O expansion panel. The following features are part of the host module.

- Video Output Provides video output for the front panel display and expansion panel VGA output.
- USB interface Provides communication bus for touch screen, IR receiver, bluetooth transceiver, and external keyboard used for some maintenance functions.
- Expansion Connectors These connectors provide external interfaces for video input, overlayed video output, VGA output, serial interface, tethered laser interface, USB, video recorder control, ethernet, and MP3 input.
- DVD R/W The primary means to download software to the host. It is also used to write data on CD or DVD format disks.
- IR Receiver Provides the means by which signals from the remote control are received and sent to the host via USB.
- WiFi Transceiver Provides the means to communicate to the host via IEEE 802.11.

- Bluetooth Transceiver Provides the means to communicate to the host via USB.
- Bar Code Scanner Used to scan pak and consumable codes to pre-configure the machine for use.
- VideOverlay Provides a means to overlay real time console settings over surgical video data, then view and record it on external video.
- Stereo Speakers Emit tones and voice confirmation. Speakers are housed in the console and controlled via the host sound card.

Display Module

The display module is the main user interface. The display module contains the LCD (display), and the touch screen which is the primary user input device. The display module's major components are the display assembly and pivot mechanism.

Supervisor Module

The supervisor module controls, arbitrates, and coordinates communications with all of the system's modules via an ethernet backbone and individual reset lines. The supervisor module provides:

- The means to receive input from the attached footswitch.
- Communication with the power system to control the power up sequence.
- The means to directly control the illuminator module via an electrical interface.



Illuminator Module

The illuminator module is a bright light source which couples to an endo-illuminator probe to illuminate tissues in the eye. The illuminator module is equipped with fixed UV and IR filters to remove unwanted ultraviolet and infrared light energy. The module is controlled by the supervisor module.

Fluidics Module

The fluidics module is comprised of two major functional blocks: the individual fluidics cassette and the receiver mechanism. The receiver

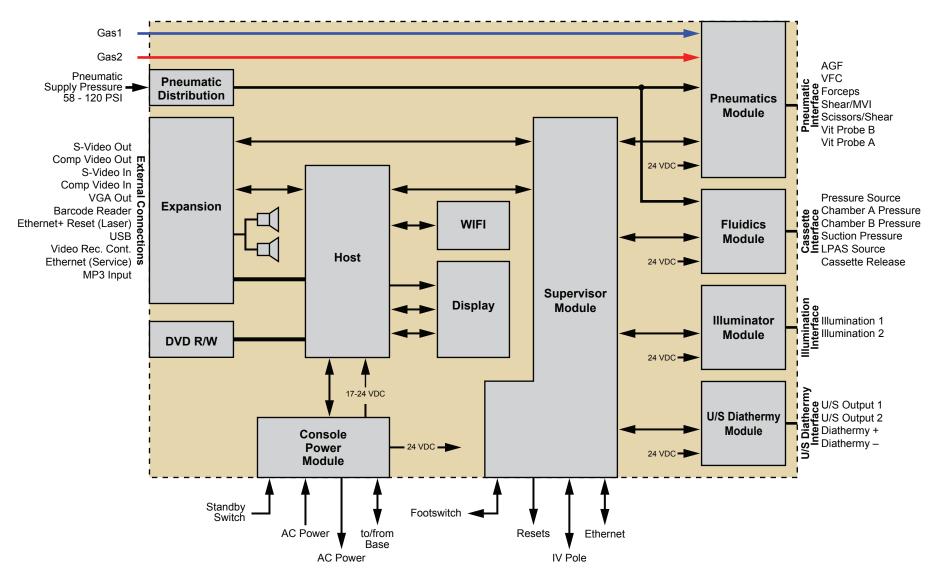


Figure 2-1 Tabletop Console Block Diagram

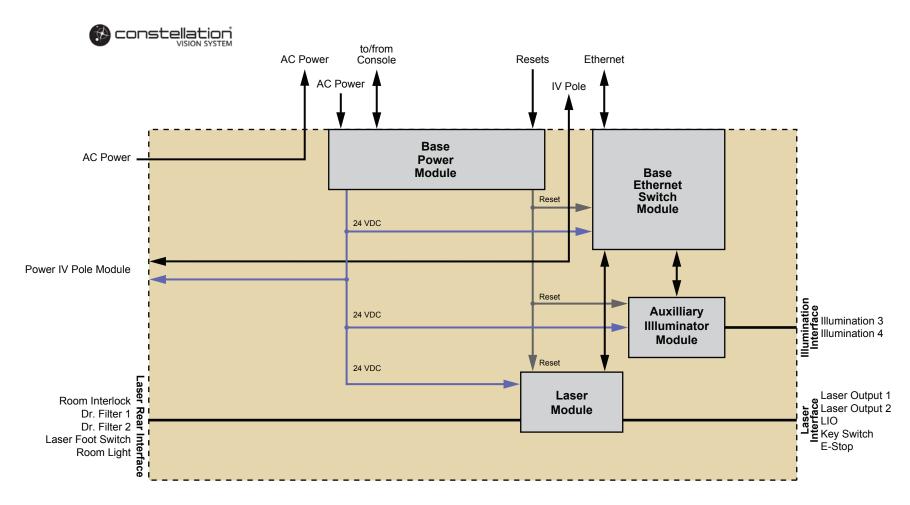


Figure 2-2 Base Console Block Diagram

mechanism consists of the following:

- Cassette Clamp Mechanism Provides mechanism for securing the fluidics cassette to the console's internal fluidics system.
- Cassette Valve Pincher Actuators Provides actuation to control fluid inputs/outputs.
- Module Controller Provides control and communication of various module functions.
- Non-Invasive Flow Sensor Senses flow.

- Infusion and Aspiration Level Sensors Used to determine cassette fluid levels.
- Cassette Detection Sensors Used to detect the presence of a cassette.
- Cassette ID Sensors Used to identify various cassette types.
- Drain Pump Used to transfer fluid from cassette to drain bag.
- LPAS Pump Generates pressure for infusion.

- Infusion Subsystem Controls and provides pressure necessary to maintain infusion.
- Irrigation Subsystem Controls irrigation levels.
- Aspiration Subsystem Controls vacuum.

These 12 elements, plus the fluidics cassette, work together to provide the necessary infusion, irrigation, aspiration, and LPAS functionality required by the *Constellation*® system.



Pneumatics Module

The pneumatics module is comprised of the following elements:

- Pneumatic Distribution Distributes clean filtered supply of pneumatic source pressure to the pneumatics and fluidics modules. It also provides the point of connection for the console to the hospital supply pressure.
- Vit Probes Pressure Drive Ports Provide pulsed pressure at a predetermined rate, duty-cycle, and pressure to drive pneumatic vitrectomy probes.
- Pneumatic Instruments Drive Ports Provide either proportional pressure or pulsed pressure at a predetermined rate, duty-cycle, and pressure to drive pneumatic instruments such as forceps and scissors.
- Viscous Fluid Control Port The VFC drive provides proportional pressure or vacuum to drive the VFC plunger to inject or extract viscous fluids.
- Auto-Gas Filling (AGF) Port The auto-gas filling port provides the automatic function of filling the gas consumable with a gas tamponade.

U/S Diathermy Module

The U/S diathermy module provides the following functionality:

- Phaco and Frag Connectors Provide the electric signals to drive the Phaco and Frag handpieces.
- Diathermy Connectors Provide the electric signals to drive the diathermy and coagulation accessories.

Remote Control

The remote control provides a navigational interface remotely through the IR receiver.

Base Assembly (optional)

The base assembly provides the mounting platform for the table top console. The base assembly contains the following modules/functionalities:

- Base Ethernet Switch Provided as an extension to the supervisor, and distributes ethernet and reset lines to the modules in the base assembly.
- Base Power Module The base power module distributes power through a single 24 VDC power bus.

Tray Arm (optional)

The tray arm can be mounted on either the left or right side of the base. It provides a movable work surface for set-up and use during surgery.

Laser Module (optional)

The laser module converts 24 VDC input power into laser light at the output port where it is coupled to a fiber-optic handpiece cable. The laser rear interface provides the primary external interface to the laser module. It includes the room interlock, two Dr. filters, a laser footswitch connector, and room light connectors.

Auxiliary Illuminator Module (optional)

The auxiliary illuminator is a xenon light source which couples to an endo-illuminator probe to facilitate visualization of eye tissues. The auxiliary illuminator is equipped with fixed UV and IR filters to remove unwanted ultraviolet and infrared light energy.

• • • •



Power System

The Constellation® Vision System uses a modular architecture. Each major machine function such as pneumatics or fluidics is controlled by a dedicated module. Power for all modules is provided by a single 24 VDC power bus distributed throughout the system. The host computer is an exception as it is uniquely powered from a dedicated power source which automatically derives energy from the 24 VDC bus or backup battery pack, as appropriate.

This power architecture eliminates line leakage stack ups from individual modules, relieving the requirement for a large, heavy, and costly isolation transformer. In a stand-alone table top configuration the system leakage is below 350 uA. The combined top and bottom consoles total a maximum leakage less than 500 uA.

The power system as a whole is comprised of five major functional blocks: AC input, power conversion, power distribution, host battery backup (including charger), and a dedicated host DC power converter module. The five blocks work together to convert a universal 90-264 VAC,

50/60 Hz input into a 24 VDC regulated power bus that meets the *Constellation*® total system power requirements.

The table top (console) and monolith (console with base) configurations utilize the major functional blocks depicted in Figure 2-3. A brief description of each block follows.

• AC Input

The AC input block provides the interface between the AC power line and the AC to DC power conversion block. The AC input block consists of an AC power entry module, over-current

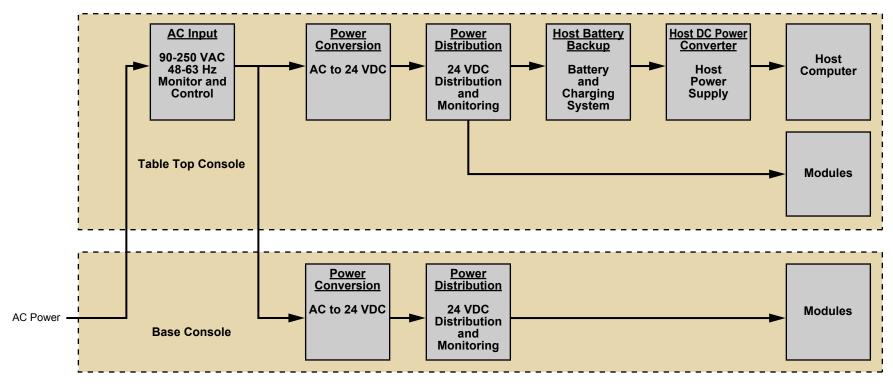


Figure 2-3 Five Major Power Functional Blocks



protection, EMI filter, and AC power distribution. The AC input block also includes AC voltage and current monitoring, and a serial communication port reporting results to a system supervisor.

• Power Conversion

The AC to DC power conversion block consists of a single 24 VDC, AC/DC main power supply with wide input range capability. This supply has two outputs: a main 24 VDC and a low power logic level standby output. The entire system can be put into a sleep-mode by powering down the main 24 VDC output via a remote shut off input. The main 24 VDC output defaults to an off state when the system is first plugged into AC power, and remains off until an operator activates a wake-up standby switch. A microcontroller in the power distribution block controls the power down sequence when a shut-down command is issued by the operator via the host computer.

• Power Distribution

The DC distribution block refers to the breakout of power to the individual modules. The main 24 VDC from each supply is brought on-board, then fanned out and distributed to the individual modules. Cable harnesses are used to connect the multiple 24 VDC output connectors to the individual modules. Additional circuitry is added to monitor voltage and current levels at key points throughout the board. Results are reported to the system supervisor.

• Host Battery Backup

A rechargeable Li-ion battery is included in the system as a backup power source. The battery backup provides a dual function. It acts as a UPS, keeping the host alive if there is a loss of AC power, allowing for an orderly controlled shutdown of the host. It also provides power when the host is remotely commanded to wake up, permitting software upgrades to be downloaded without the need for AC power.

• Host DC Power Converter

The host computer is based on an Intel Pentium class processor with a hard drive, DVD, DVI video controller, sound, USB, etc. The host power module generates the voltages necessary to run the host computer and its peripherals. This module derives its power from either the 24 VDC bus, or from the backup battery, as required.

Console/Base Integration

In a fully integrated system, the console and base mate to provide the full feature *Constellation*® system (monolith). In this configuration AC power enters the bottom console then is routed to the top. Once in the top console, AC is controlled and monitored, then distributed between the two consoles. To limit AC line in-rush current, the top and bottom power supplies are sequenced upon power up. The top console is first powered up, followed shortly by the base.

The 24 VDC power bus in the base is supported by its own dedicated power supply capable of delivering ample power to all base modules. The base's breakout board has minimal circuitry, and is generally used to fan out power to its modules.

Functional Block Description

An expanded power system block diagram showing a more-detailed signal flow is presented in Figure 2-4. The five major functional blocks discussed before are depicted by the shaded areas.

Along with the AC switching supplies and the backup battery pack, four circuit boards (AC Power, Power Controller, DC\DC Converter, and Bottom Power Distribution) constitute the full power system. An overview of each of the four PCB assemblies follows.

AC Inlet

For the monolith system, AC power enters the at the bottom of the base unit. The power is routed through the base to the top console AC inlet. (If the system is only the table top console, the power enters directly into the console's AC inlet.) The inlet incorporates a low leakage, high frequency, EMI filter. Power is then routed from the inlet receptacle to a combination On/Off rocker switch and thermal circuit breaker. From here the AC power is wired to the AC Power Board system level EMI filter.

AC Power PCB

The AC Power PCB performs three basic functions: AC power monitoring, AC power switching to base unit, and system EMI filtering.



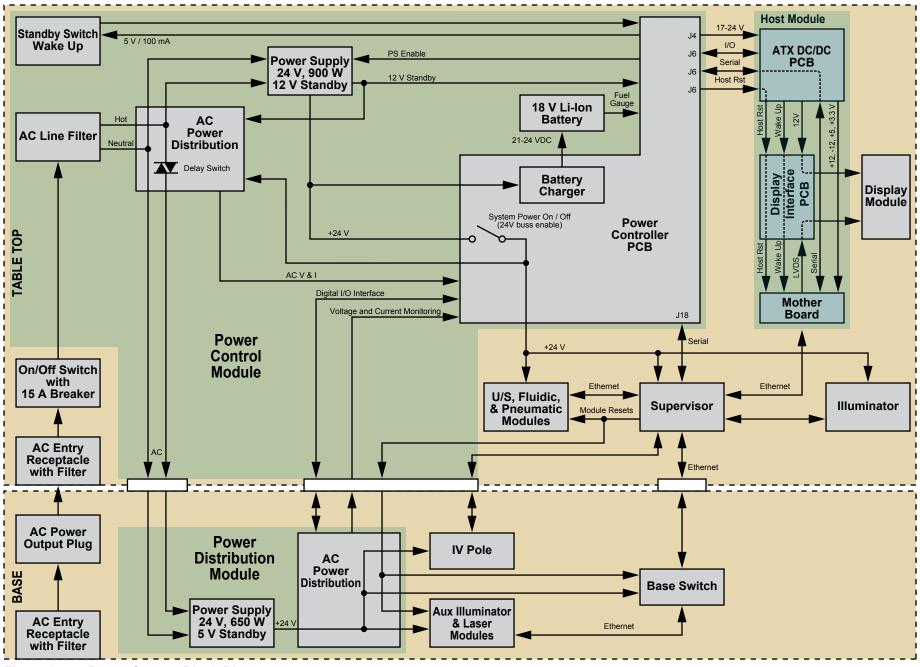


Figure 2-4 Power System Block Diagram



Power Controller PCB

As its name implies, the Power Controller PCB controls, monitors, and reports the status of the AC and DC power coming into the *Constellation*® system, as well as the power being distributed to all the sytem's submodules.

Power States

The power system can reside in any one of six power states; battery-powered sleep mode, wall-powered standby mode, e-connectivity mode, UPS host back-up mode, and full system power-up mode (see Table 2-1).

Control Logic Power

For e-connectivity wake-up purposes, the system utilizes the PIC processor's real time clock capacity. In sleep mode the main switcher power supplies are powered down. If there is no AC power, power must be derived from the 21 V lithium back-up battery pack. To ensure a long shelf life, battery

drain must be limited below 1 mA, yielding about one year of operation before re-charge is required on an initially-full battery.

To conserve power in sleep mode, power is routed only to the PIC processor via a pair of back-to-back n-mosfets operating as a bi-directional power switch. A separate mosfet feeding all other logic is powered down. Steering diodes turn on the appropriate mosfets as various power sources are available; i.e., battery, standby, and host converter power.

In the event that the lithium battery is removed for servicing, a 1.5 Farad power capacitor keeps the real-time clock running for about one-half hour.

Standby Switcher Power

The top console switching power supply has a +12 V auxiliary standby power output, active when AC input is greater than 80 VAC. When the

auxiliary voltage is present at the input to the micro power switching regulator, the battery back-up feed is disconnected by a mosfet switch.

Lithium Back-up Battery Pack

A nominal 21 V smart lithium battery pack provides sleep mode power for the system, as well as acting as the back-up and e-connectivity power source for the system. The pack has a 4.3 ampere hour rating translating to about 20-30 minutes of host run time under back-up or e-connectivity operation. Integrated smart battery electronics within the pack provide battery gas gauging capacity, indicating the ampere hours of capacity remaining at any given time by coulomb counting both charge and discharge currents.

Communication to the battery is maintained via a SMBus data link (battery industry modified I2C). The link provides detailed pack information including state of charge, cell voltage, temperature, current, date of manufacture, etc. In addition to the data link, the pack incorporates a thermistor which provides additional hard wired protection against overheating if the data link fails.

The pack is easily replaced by disconnecting a 10 pin Molex minifit connector, and removing Velcro straps holding the pack in a cradle.

Lithium Pack Charge Control

The charger has the capacity to operate fully independently; however, all charging parameters are available to the PIC processor via the SMBus communication link to control. As a safety precaution, hard-wired resistor values limits maximum charge voltage and current to the battery pack, regardless of higher software commands.

| Power State | Description |
|---|---|
| Battery-Powered Sleep Mode Wall-Powered Standby Mode | When main AC power off, system real time clock battery powered. When main AC power switch is on, AC switching supply is active. System operates in standby mode, drawing system power from switcher auxiliary output until system is commanded on. |
| E-Connectivity Mode | When main AC power switch off, and e-connectivity is self activated, host operates from battery power. |
| E-Connectivity Standby Power | When main AC power switch is on, and e-connectivity is self activated, AC supply and host are turned on. The rest of system is held off. |
| UPS Host Back-Up Mode | Upon loss of AC power, all modules go into an off fail-safe mode, with exception of host computer which remains active operating from battery power until Windows OS can be properly shut-down. |
| Full System Power-Up Mode | All power is derived from AC switching power supply. |

Table 2-1 Power States



Likewise, the temperature of the battery pack is hard-wire monitored via a thermistor located in the pack. If cell temperatures are too high, the charger will terminate the charge.

Host DC/DC Converter Input

The power provided to the host DC/DC converter ranges from 16 to 24 volts, dependent on the power source. The source can originate from the AC switching supply or a low level battery pack.

Microprocessor

The microprocessor used onboard is a PIC 16-bit processor (PIC18F6527) clocked by an external 10 MHz oscillator. In sleep mode, to reduce power consumption, the clock is switched over to a slower 32.768 KHz external oscillator and internal 8 MHz clock. The oscillator is also used as a time base for the processor's real time clock.

All inputs are ESD and noise protected before entering the board, and all outputs are buffered before exiting. This includes ESD and noise protection on the I2C lines.

Host Interface

Communication to and from the host is included in a single 14-pin connector (see Table 2-2).

Base Console Interface

Communication to and from base console is in single 16-pin connector (see Table 2-3).

Top Console Fan Cooling

Based on the temperature reading from the sensor above, the top console system fan is speed controlled via a PWM signal from the PIC processor. A fan fail monitor IC (MAX6684)

monitors the fan's tach output signal. If the fan is not spinning for any reason, a fan fail signal is reported to the PIC.

The output lines to the fan are fully current-protected. If the output current exceeds one ampere, the gate of the output mosfet will be held low. As the PWM signal drops low, the latching circuitry is reset, thereby yielding a cycle-by-cycle self-resetting current limit.

Standby Switch

Under normal operation, the *Constellation*® console is turned on by depressing the system standby switch located at the back of the machine. The switch glows orange while in system standby mode, and blue once the console is activated. The switch input is both ESD and noise protected.

Top 24 V Supply Interface

Other than the main +24 V output from the AC supply, three signals are connected to the Power

| Signal | Functional Description |
|------------------|---|
| RX1 & TX1 | Pseudo RS232 interface passing measurements and status to host. Host passes real time clock updates and programming to PIC. |
| Display Enable | Activates +12 V power to display. (Not active in e-connectivity mode.) |
| Host Soft Reset | Direct soft reset line to motherboard. |
| Host Shut Down | Signal originating in motherboard calling for shutdown of its own power supply. |
| Host Power Good | Signal from host DC/DC converter indicating all voltages are regulation. |
| 0V Return | Common 0 V reference return. |
| Laser Reset | Pass thru signal from supervisor to external laser system for cabling efficiency. |
| Supervisor 0 V | Supervisor 0 V reference used by laser reset. |
| Back Light Level | PWM signal controlling back light level of display. (Level initiated from the host through RS232 link to PIC.) |

Table 2-2 Host Interface Signals

| Signal | Functional Description |
|--------------------|--|
| +24V Bottom | 24V signal from base power board to monitor +24V level at base. |
| 24V I Bottom | +24V buss current level signal from Base PCB scaled at 0.1V / Amp. |
| 0VRefAnalog Bottom | 0V reference from bottom console / base Power PCB. |
| Base Present | Loop back signal to 0V indicating base console interface connector is engaged and base console is present. |
| 0V Ref Top | 0V reference from top console to base Power Distribution PCB. |
| Over Cur Bottom | Signal drives low if base Power Distribution PCB detects a load higher than 30 amps. |
| Bottom Power OK | Active low signal if base console +24V is in regulation. |

Table 2-3 Base Console Interface Signals



Controller PCB. The AC Good signal indicates the supply has sufficient AC voltage to remain in regulation. The +24 V enable signal turns on the main +24 V supply output when driven to 0.0 volts. A high enable level turns the output off (standby mode). The third output is the standby auxiliary +12 V used to power the circuit board during standby mode.

Supervisor Interface

Communication between the PIC and Supervisor is through an opto-coupled pseudo RS232 interface to maximize the signal-to-noise ratio. In addition, the external laser reset line is passed through the controller for cable wiring efficiency.

Host DC/DC Converter and Interface PCB

The host DC/DC Converter and Signal Interface PCB performs two primary functions. The first role is providing all voltages necessary to operate the host computer and motherboard; as such, the DC/DC converter mimics a standard 150 Watt power supply. The second function the board provides is electrical safety isolation between the host computer, all of its I/O, and the *Constellation*® internal electrical system. Isolation is necessary to meet safety agency requirements.

Communication lines between the host and *Constellation*® system are included in a single 14-pin connector with the exception of the ethernet network line. Isolation in this instance is provided in the ethernet coupling transformer on each side of the ethernet cable.

The interface cable between the host DC/DC Converter PCB and Power Controller PCB has a one-to-one pin assignment (see Table 2-4).

Bottom Power Distribution PCB

The primary function of the Bottom Power Distribution PCB is to provide an interconnect platform for the AC and DC voltages distributed throughout the top *Constellation*® console, as well as monitoring general environmental conditions of the base console, and reporting these to the top Power Controller PCB.

Top to Bottom Console Interface

A number of data lines are required to interconnect the top and bottom power boards (see Table 2-5).

• • • •

| Signal | Functional Description |
|------------------|--|
| RX1 & TX1 | Pseudo RS232 interface passing measurements and status to the Host. Host passes |
| | real time clock updates and programming to the PIC. |
| Display Enable | Activates +12V power to the display. (Not active in e-connectivity mode.) |
| Host Soft Reset | Direct soft reset line to the motherboard. |
| Host Shut Down | Signal originating in motherboard calling for shutdown of its own power supply. |
| Host Power Good | Signal from the Host DC/DC converter indicating that all voltages are regulation. |
| 0V Return | Common 0V reference return. |
| Laser Reset | Pass thru signal from Supervisor to External Laser for efficiency in wire cabling. |
| Supervisor 0V | Supervisor 0V reference used by Laser Reset. |
| Back Light Level | PWM signal controlling the back light level of the display. (Level initiated from the Host |
| | thru the RS2323 link to the PIC). |
| | |

Table 2-4 Host Interface Signals

| Signal | Functional Description |
|--------------------|--|
| Shield | Chassis ground line for cable shielding. |
| +24V Bottom | 24V signal going to top console to monitor +24V power buss in base. |
| 24V I Bottom | +24V buss current level signal from Base Board scaled at 0.1V / A. |
| 0VRefAnalog Bottom | 0V reference from bottom console / Base Power Board. |
| Base Present | Loop back signal to 0V indicating the bottom console interface connector is engaged and the bottom console is present. |
| 0V Ref Top | 0V reference from the top console to the Base Power Distribution Board. |
| Over Cur Bottom | Signal drives low if bottom Power Distribution PCB detects a load higher than 30 A. |
| Bottom Power OK | Active low signal if the base console +24V is in regulation. |
| Supervisor 0V Ref | Supervisor 0V reference used by reset signals routed to each module in base. |
| Reset 7-10 | Reset lines 7 thru 10 routed to each module in the base. |

Table 2-5 Top to Bottom Interface Signals



- 1. With power cord plugged into AC outlet, turn On/Off rocker switch/breaker, located on rear of table top, to the ON position. The Power Controller PCB receives 12 V from the 900 W power supply and converts/sends 5 V / 100 mA to the standby switch; its button illuminates amber.
- 2. Press the amber standby button to begin powering up the system. The button turns blue to indicate the boot sequence has begun.
- 3. The Power Controller PCB sends the PS enable signal to the 900 W power supply to allow 24 V to go through the battery charger to the 18 V Li-Ion battery and back to the Power Controller PCB which then delivers 24 V to the Host ATX DC/DC PCB through J4.
- 4. The ATX DC/DC PCB sends -12 V, +5 V, +3.3 V to the Motherboard. It also sends +12 V to the Display Module through the Display Interface PCB.
- 5. After a few minutes, the Host Module sends a message back to the Power Controller PCB through J6, triggering +24 V 900 W power supply to the table top modules and supervisor.
- 6. After the table top modules successfully report back to the Supervisor, and if Table Top is connected to a Base unit, a Host signal triggers the delay switch which allows AC power to enter the Base 650 W power supply and its modules.
- 7. Once Table Top modules (and Base modules, if present) report back to the Supervisor, the Supervisor sends a message through the ethernet indicating it has taken control.

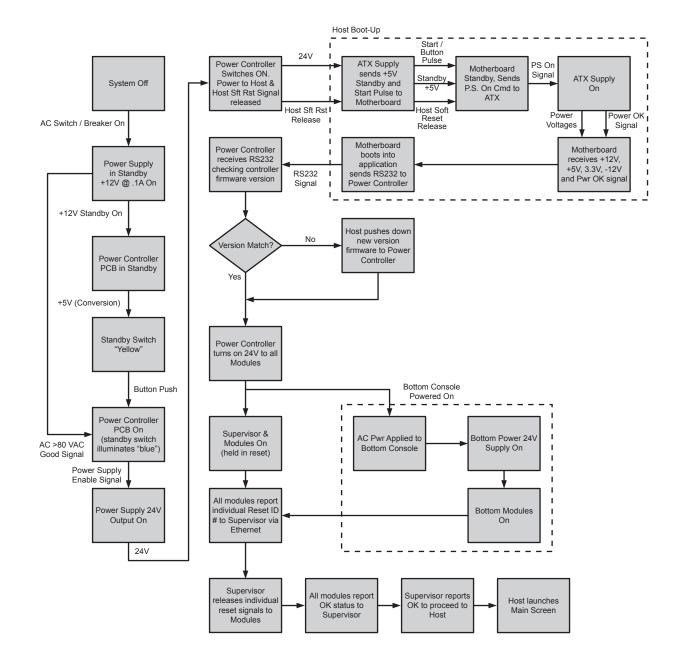


Figure 2-4a Power Up Sequence



Host & Expansion Panel

General Overview

The *Constellation*® Host module provides the computing platform for the Host software and Graphical User Interface (GUI). It communicates system level controls to subsystems via the Supervisor module (see Figure 2-5).

The Flex ATX Motherboard receives all necessary DC power (ATX power) from the Host DC-DC Converter PCBA, which also supplies DC power for the hard disks and DVD read/write drive. The PCI cards receive power directly through PCI slot connectors to perform specific functions of each board.

The Expansion Panel at the rear of the Constellation® console serves as the main user interface for external device connections. It has two horizontal rows of connectors, upper and lower, clearly labeled for their intended applications. The panel assembly contains upper and lower Expansion PCBA's, a Wi-Fi antenna cable connector, and cables from the Flex ATX Motherboard.

The Host module is composed of the following:

- Flex-ATX Motherboard
- VideOverlay PCBA (PCI)
- Wi-Fi PCBA (PCI)
- Two SATA hard disk drives
- DVD read/write drive
- Host DC-DC Converter PCBA
- Host Display Connector PCBA
- All required interface cables

Flex ATX Motherboard

The Flex ATX Motherboard contains an *Intel*® Pentium M745 1.8 GHz CPU with cooling fan, and a 1 GB DDR SDRAM (two slots available). Two embedded chipsets are also included on the motherboard:

- The Intel® 855GME Graphics and Memory Controller Hub (GMCH) is responsible for 24bit LVDS, AGP/DVO, VGA graphics interface support, and 184-pin DDR333 memory.
- The *Intel*® 6300ESB I/O Controller Hub (ICH) supports 32-bit, 33 MHz PCI 2.2 bus connectors, 10/100 Ethernet port, ATA100, SATA150, USB, and Serial I/O interfaces.

The system BIOS on this board stores all the preferred configuration default settings so that when the CMOS looses its battery power, only the date and time information must be re-entered.

Display Interface

The motherboard has the ability for analog and digital display through an *Intel*® Extreme Graphics 2 controller.

- The analog display support is provided by a 350 MHz integrated 24-bit RAMDAC, and the VGA Monitor connector is located on the real I/O as a 15-pin female D-sub connector for analog monitors up to 2048x1536 resolution at 75 Hz.
- The LVDS port supports single or dual channel LVDS with 18/24-bit open LDI up to UXGA panel resolution, and is located internally as a 40-pin ribbon connector. It connects to the Host Display Connector PCBA, then the LVDS signal is sent to the front panel LCD display.

Audio Interface

The Flex ATX Motherboard employs an AC97 version 2.3 subsystem using the Realtek ALC655 codec to support Audio-In (MP3), Audio-Out (speakers), Mic (not used), and internal DVD interface (not used). Audio amplification of stereo sound input takes place on the Host DC-DC Converter PCBA and is sent to the two speakers.

Peripheral Interfaces

The Flex ATX Motherboard has two serial ATA IDE interfaces, two parallel ATA IDE interfaces (only one used), s-video and composite video connectors, four serial RS-232 ports, four USB 2.0 ports (two external [only upper one used], two internal), ATA-66/100 support, PS/2 keyboard (not used) and mouse ports (not used).

• Serial ATA HDD - Two SATA hard disk drives (SATA0 & SATA1) are used as non-removable storage devices for OS software, host software, GUI software, and to support the high-speed data transfer of 1.5 GB/s.

The two hard drives are configured as soft-RAID1 for its fault-tolerance benefit. The mirrored pair of two hard disks increases reliability exponentially over a single disk. Each hard drive contains a complete copy of the data and can be addressed independently.

• Parallel ATA DVD Burner - One parallel ATA IDE interface is used to install software, and to back up system & data files. This removable data storage device is located on the mounting tray directly above the motherboard's CPU fan within the host enclosure. The drive is accessible from the rear of the console to load and unload a DVD disc.



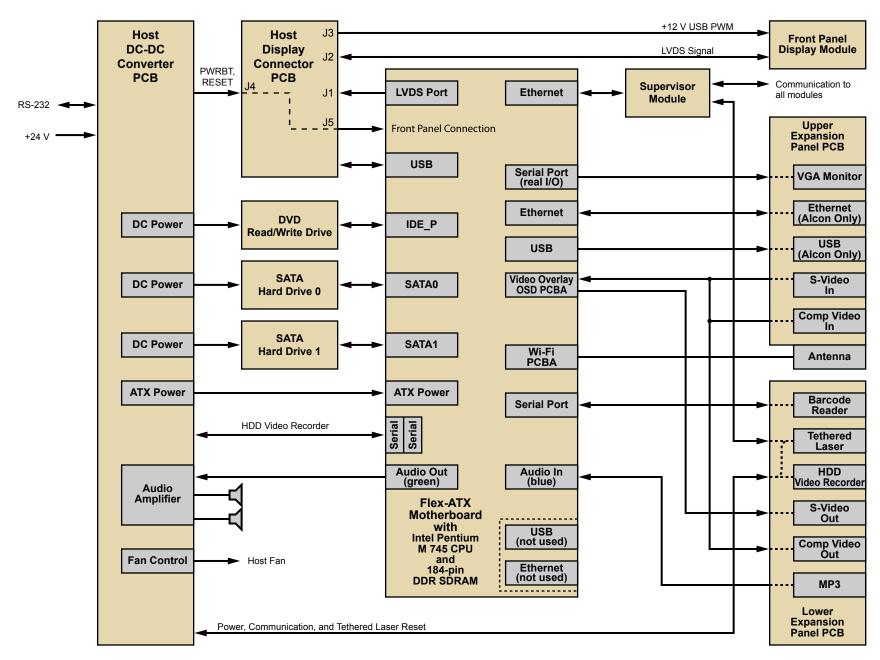


Figure 2-5 Host and Expansion Module Block Diagram



The DVD drive is a 5.25-inch half-height internal ATAPI DVD writeable drive. This drive can read digital data stored on CD-ROM, CD-R, CD-RW, DVD-RAM, DVD-ROM, DVD-R, DVD-RW, DVD+R, DVD+RW and CD audio discs. It can record digital data on DVD-R, DVD-RW, DVD+R, DVD+RW, CD-R, and CD-RW discs. It supports the RPC II format.

• Video Overlay - The Video Overlay Module (VOM) is comprised of two main components: a PCI card with video overlay capability (inside of Host module), and an external DVD recorder with RS-232 serial ports (recorder not supplied with Constellation® system)

The VOM allows the user to add information (such as system status, settings, and parameters) to the live video being captured during the surgical procedure. This added data (text and graphics) is laid on top of the incoming video from the surgical scope. The resulting video/data can be viewed on an external monitor in real time and/or recorded using an external DVD recorder.

The video overlay function is implemented by an On Screen Display (OSD) PCI card, installed in a Host PCI slot. The OSD card has the capability to accept either an s-video or a composite video input in either PAL or NTSC format, and to output the combined video and overlay data in the same format as the incoming video.

External DVD Recording

DVD recording of the output video can be accomplished using an external real time DVD recorder (such as the Sony DVO). The *Constellation*® system provides a dedicated RS-

232 port (REC), accessible by the user via the expansion panel, to control Start/Stop recording of the external DVD recorder, which can be controlled using the footswitch. This feature requires the external recorder to provide an RS-232 port with remote start/stop capability.

Barcode Reader

Barcoding is a type of Morse code used to encode information into a universally-recognized code language in the form of a barcode pattern. The barcode reader decodes a barcode by shining a light source across the barcode and measuring the intensity of light reflected back by the barcode. The pattern of reflected light is detected with a photodiode, which produces an electronic signal that exactly matches the printed barcode pattern. This signal is then decoded and transmitted to the *Constellation*® application software. A barcode system consists of a barcode printer, barcode labels for identification, scanning equipment for data collection, a database for barcode data analysis, and relay.

A handheld laser scanner (MS9544 by Metrologic) is used to scan the barcode labels that are printed on each consumable pak. It is a RS-232-based device that can read both 1D and 2D types of barcodes.

The Constellation® system provides barcode reading capability via a dedicated barcode reader connector on the expansion panel (IIIIIIIII). The handheld reader scans the product's barcode label and transmits the raw data to the Host module. The data processing software decodes the product identification and compares it with the product database, allowing the product information to aid in system setup, keep track of products used during procedures, keep metrics, and keep inventory

of products used. Once each consumable pak is scanned, it enables the *Constellation*® system to set itself up accordingly and offer on-screen help information to the OR staff.

Wireless PCI Adapter

The Wi-Fi card (Wireless-G PCI card) is used in the *Constellation*® system for wireless network connectivity with the internet, printer, and other future applications, utilizing its external antenna. The Wi-Fi card operates in the 2.4 GHz frequency spectrum with throughput of up to 54 Mb/s in Wireless-G mode. It complies with IEEE 802.11g standards and is backwards-compatible with IEEE 802.11b products.

Operational Description

The Host module is a PC with two Alcon custom PCBA's (Host Display Connector PCBA and Host DC-DC Converter PCBA), several OEM boards and storage devices (HDD & DVD), and interconnecting cables residing in the Host enclosure chassis. The chassis is equipped with the Host cooling fan/duct cover on the top. The Expansion Panel assembly is basically an extension platform of the Host module's signal ports for various applications. Two Alcon custom PCBA's (Lower and Upper Expansion) are included in the Expansion Panel assembly along with the associated extension cables.

Host Display Connector PCBA

The Host Display Connector PCBA is basically a connector interface board that distributes signals and power between the Host DC-DC Converter PCBA, Motherboard, and Front Panel Display Module.



LVDS Video Signal Interface

The Host Display Connector PCBA receives two channels (A, B) of LVDS data & clock signal pairs and supply voltage (+5 V) from the Motherboard's LVDS port via a 40-pin flat ribbon cable. These signals are routed to a 26-pin connector (J2) so that the LVDS cable can be connected from outside of the Host enclosure for easy cable installation to the Front Panel Display Module.

Display Power Signal Interface

The Host Display Connector PCBA receives 12 V backlight inverter input power and the backlight brightness control (PWM) signal from the Host DC-DC Converter PCBA via connector J4. These signals are routed to a 14-pin connector (J3) so that the LVDS cable can be connected from outside of the Host enclosure for easy cable installation to the Front Panel Display Module. Two signals (PWRBT, RESET) from the Host DC-DC Converter PCBA enter the Host Display Connector PCB at J4 and are passed through connector J5 to the Motherboard.

The Host Display Connector PCBA also relays a separate +12 V input power via the LVDS port ribbon cable to supply the power to the Host Front Panel PCBA in the Front Panel Display Module as input power for the circuitry.

The Host Display Connector PCBA relays USB signal pairs from the Host PC's front panel connector through connector J3.

Upper Expansion PCBA

The Upper Expansion PCBA is used to provide an external I/O interface between the Host module and external devices. The PCBA is mounted in the upper section of the expansion panel to support

the top row of I/O connectors at the rear of the console.

Analog Display

The analog display signal from the Motherboard serial port on the rear I/O connects to the external VGA Monitor 15-pin female connector. Two transient voltage suppression (TVS) diode arrays are used both on the analog and digital signal lines for electrostatic discharge (ESD) protection of the I/O data lines. This device has an array of surge rated diodes with internal TVS diode. During transient conditions, the steering diodes direct the transient to either the positive side of the power supply line or to ground. The internal TVS diode prevents over-voltage on the power line, protecting any downstream components. The TVS device has a typical capacitance of 3 pF, and operates with virtually no insertion loss to 1 GHz.

• Service Ethernet

The Ethernet signal from the Motherboard connects to the external RJ-45 Service Ethernet connector with built-in magnets. The TVS diode arrays are used on TX+, TX- signal pair and RX+, RX- signal pair for ESD protection. The TVS device has a typical capacitance of 3pF and operates with no insertion loss to 1GHz. The RJ-45 jack used for external Ethernet cable connection has an internal 1:1 transformer with 1.5KV dielectric withstanding capability and common mode chokes for filtering.

• USB Connector

The USB 2.0 signal from the Motherboard (using top port only) connects to the external USB-A receptacle connector which is normally blocked externally and is available for Alcon

service personnel use only. One TVS diode array is used on USB signal pair for ESD protection. The TVS device has a typical capacitance of 3pF and operates with no insertion loss to 1GHz.

Video Overlay

The Video Overlay PCBA can accept two types of signals (S-Video or Comp Video). The external connectors are a 4-pin Mini-DIN connector for S-Video In, and a 75-ohm BNC jack for Composite In. The S-Video Out and Composite Video Out connectors are located on the Lower Expansion PCBA. However, the composite video out signal is relayed through the same cable as the S-Video In and Composite Video In signals. Two TVS diode arrays are used on these video signals for ESD protection. The TVS device has a typical capacitance of 3pF and operates with no insertion loss to 1GHz.

• Wi-Fi Antenna

The external antenna connects directly to the Wi-Fi PCBA on the Motherboard. Although not physically a part of the Upper Expansion PCBA, externally it is located in-line with the upper expansion panel external connectors.

Lower Expansion PCBA

The Lower Expansion PCBA is used to provide an external I/O interface between the Host module and external devices. The PCBA is mounted in the lower section of the expansion panel to support the bottom row of I/O connectors at the rear of the console.

• Barcode Reader Interface

The Motherboard serial port supplies both the signal and +5V which are relayed through a 9-pin female D-sub connector to the external



Barcode Reader. The external connector was selected so that it would not be used as a normal serial port; therefore, an RS-232 cable cannot be mistakenly connected to this port. This port will only work with the Barcode Reader with a custom interface cable that has been identified for the Constellation.

Two bidirectional TVS array (SMDA15C) are used on all RS232 signal lines for ESD protection of the I/O data lines. "SMDA15C" is a bidirectional device and is designed for use on lines where the normal operating voltage is above and below ground level.

• Tethered Laser Interface

Ethernet signals from the Supervisor PCBA are received through an 8-pin RJ-45 connector. This connector is used for Tethered Laser console connection only via a Cat-5 cable. The signal pin assignments of this connector were selected so that any PC connected to the system, if attempted, will not be able to communicate with, or cause any damage to, the console.

The laser reset (LSR_RST) signal is received from the Host DC-DC Converter PCBA and routed to one of the connector pins. This connector has an internal transformer with 1.5KV dielectric withstanding capability and common mode chokes for filtering. The TVS diode arrays are used on TX+/TX-, RX+/RX- signal pairs and Laser control signals (LSR_SNS,LSR_RST) for ESD protection. The TVS device has a typical capacitance of 3pF and operates with no insertion loss to 1GHz.

• HDD Video Recorder

The external Video Recorder receives its signal via a serial port from the Motherboard to the Host DC-DC Converter PCBA, which is then routed to the 9-pin male D-sub connector. This connector is basically a serial RS-232 port, and is primarily used for the external HDD video recorder.

Two bidirectional TVS array (SMDA15C) are used on all RS232 signal lines for ESD protection of the I/O data lines. "SMDA15C" is a bidirectional device and is designed for use on lines where the normal operating voltage is above and below ground level.

Video Overlay

The Video Overlay PCBA sends two types of signals (S-Video and Comp Video). The external connectors are a 4-pin Mini-DIN connector for S-Video Out, and a 75-ohm BNC jack for Composite Out. The S-Video In and Composite Video In connectors are located on the Upper Expansion PCBA. The S-Video Out signal has its own individual connector to the Video Overlay PCBA (lower port). Although the Composite Video Out is physically located on the lower Expansion PCBA, its signal is routed through the same cable as the S-Video In and Composite Video In signals that are located in the Upper Expansion Panel PCBA.

The two TVS diode arrays are used on these video signals for ESD protection. The TVS device has a typical capacitance of 3pF and operates with no insertion loss to 1GHz.

• MP3 Audio

The Lower Expansion PCBA receives MP3 audio signal inputs through a 3.5mm stereo jack from an external audio player. These signals are then routed to the Motherboard's Audio In connector on the rear I/O. The signal is routed from the Motherboard's Audio Out connector to the Host DC-DC Converter PCBA where it is amplified and sent to the two speakers.

Two single line TVS diodes (SD05C) are used on these audio signals for ESD protection. "SD05C" is a bidirectional TVS diode with working voltage of 5volts and is used on lines where the signal polarity is above and below ground level.

• • • •



Supervisor

GENERAL DESCRIPTION

The *Constellation*® Supervisor serves as a central clearinghouse of information and real-time control for the other modules in the system. The supervisor is comprised of a number of key elements (see Figure 2-6).

Kernel

The kernel is common to all intelligent *Constellation*® modules. It includes: PowerPC microprocessor and embedded peripherals, flash memory, SDRAM, FPGA, CPLD, ADC's, and DAC's.

Ethernet Switch

All intelligent modules in the system, including the supervisor itself and host, connect through this 100BASE-TX ethernet switch IC. The host PC only communicates with the supervisor directly, while all other modules communicate only with the supervisor. The ethernet switch, although residing on the Supervisor PCBA, is more or less autonomous. Other than a software-controlled reset line, the ethernet switch does not receive any command or control from the supervisor's processor. To the ethernet switch, the supervisor processor is just another client (module).

Illuminator Interface

The supervisor directly controls the table-top Illuminator assembly. This consists of turning control lines on and off, and reading back status information.

Footswitch Interface

The supervisor directly controls the footswitch assembly. This includes not only reading treadle and button status, but providing drive current for the treadle's feedback motor.

I/V Pole Interface

The supervisor directly controls the power IV pole assembly. Unlike the footswitch, the supervisor merely sends commands and reads

status from the power IV pole assembly. The supervisor does not run the motor directly; this is handled by the Power IV Pole PCB.

RS-232

The kernel portion of the supervisor provides an RS-232 port for connection to a debug terminal. This port is for development only, and is not accessible when in-system.

Module Reset Lines

The supervisor has the capability to individually reset each intelligent module. This is done at power-up and, if required, for hazard mitigation. If a module does not reset within the specified time, an advisory or warning will appear and the particular module will not be available.

Power Conditioner

The power conditioner provides current-limiting and soft-start capability to the module. During a soft-start, the host operating system remains active, but the application software and power to the modules are reset in approximately 40 seconds.

Asynchronous Serial - Power Control Serial Port

The supervisor communicates with the Power Control PCB through an opto-isolated asynchronous serial interface. The supervisor reports system temperatures to the Power Control PCB which changes system fan settings in response.

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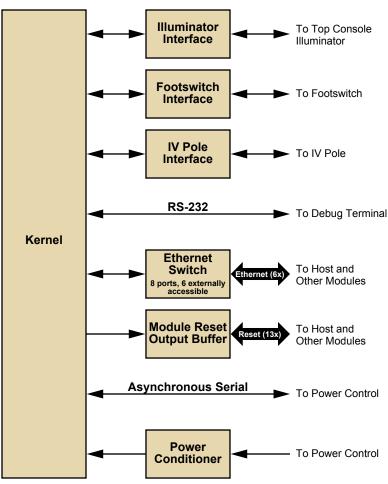


Figure 2-6 Supervisor Block Diagram



Front Panel Display

The front panel display is the main user interface of the *Constellation*® system. It has an LCD which displays the system Graphical User Interface (GUI), and a touch screen which is the primary user input device for the system.

The front panel display's major components are the display assembly and the pivot mechanism. The display can be manipulated left and right, and tilted up and down, to accommodate different user positions.

Figure 2-7 is a block diagram of the PCBAs & other electrical components used in the front panel display module, and interconnection scheme of the hardware. Figures 2-8 is a block diagram of the front panel display module communications.

Display Assembly

The primary components of the display assembly are an LCD, a touch screen, and a pair of Infrared (IR) receivers. The assembly also contains a Display Interface PCB, an SD Card Reader PCB, a Backlight Inverter PCB, and two IR Sensor PCB's. The LCD and Display Interface PCB are each connected to the host module via their own dedicated cables. Additional internal cables connect the other boards to the Display Interface PCB. Enclosures and a frame hold these components in place, and faraday shields are used to suppress radiated emissions (EMI) to and from the boards.

LCD

A 17-inch color TFT-LCD is used as the GUI display. The LCD employs an integral Cold

Cathode Fluorescent Lamp (CCFL) backlight system, and is driven by LVDS display signals from the LVDS port in the host PC computer. This thin, lightweight display uses little power, and has a 17.0 inch diagonally-measured active area with SXGA resolution (1280 by 1024 pixel array).

Two power inputs are required for this LCD; one to power the LCD electronics and to drive the TFT array & liquid crystal, and a second to power the CCFL which is generated by an inverter. A 30-pin connector is used for the LVDS signal & LCD power interface. Two channels (odd/even) of pixel data signal pairs are required to drive this LCD.

Touch Screen

A 17-inch, 8-wire, resistive touch screen is mounted directly in front of the LCD. This is the primary user input device for operating the system.

Backlight Inverter PCB

The Backlight Inverter PCB receives +12 V from the host module via the Display Interface PCB and converts it to high frequency of 69-75 kHz, and up to 730 VRMS waves, to ignite and operate the LCD's CCFL lamps.

The inverter includes a dimming input that allows brightness control from either a DC voltage source

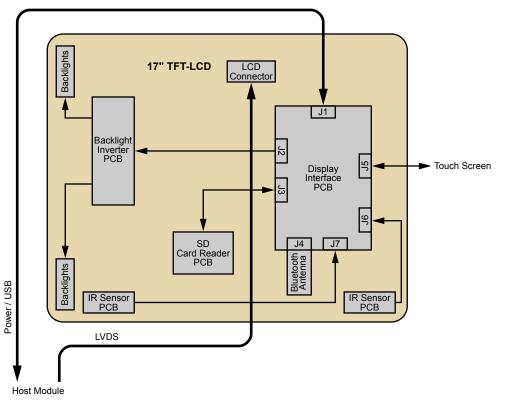


Figure 2-7 Front Panel Display Module Interconnection



or a PWM signal. The maximum output current is externally programmable over a range of 5 to 8 mA to let the inverter properly match the LCD panel lamp current specification.

Bluetooth Antenna

The Display Interface PCB provides a USB-A receptacle dedicated for a USB Bluetooth adapter connection. The Bluetooth antenna is capable of communicating with any Bluetooth-enabled device, such as the wireless headset/microphone for the system's voice activation feature.

The Bluetooth antenna supports Bluetooth 1.1 specification, and is compatible with USB 1.1. The RF-wireless frequency for this device is 2.4 GHz, and the covered range is up to 33 feet, peer-to-peer.

IR Sensor PCB

The display assembly also houses two IR Sensor PCB's and interface cables. The *Constellation®* system utilizes the same IR Sensor PCB as Alcon's *Infiniti®* system; however, the angle of the IR sensor chip has been modified to be parallel with the PCB surface. Two of these boards are mounted in the front lower corners of the display.

Display Interface PCB

The Display Interface PCB receives power, USB, and other control signals from the host module, and allocates the signals to the appropriate PCB's. It interfaces with the Backlight Inverter PCB to supply DC power (+12 V) and send backlight control signals. This board has two USB connectors; one for the SD card reader and the other for the Bluetooth antenna.

This PCB has an on-board, high-speed, USB hub

controller circuit using Philips' ISP1520 device (U4). This device supports data transfer at high-speed (480 Mbit/s), full-speed (12 Mbit/s), and low-speed (1.5 Mbit/s). The upstream-facing port is connected to a USB 2.0 host, therefore the ISP1520 operates as a high-speed USB hub. The vendor ID, product ID, and string descriptors on the hub are supplied by the internal ROM. Analog over-current detection has been inhibited by connecting OC_N pins to +5 V, even though the ISP1520 supports over-current protection mode.

The touch screen control function is provided by Hampshire's HU10-100SO0 touch screen controller ASIC chip (U6). This device is a USB-based, 10-bit resolution, touch screen controller to support screen types of 4, 5 and 8 wires. Currently, the Display Interface PCB is designed to support 8-wire resistive touch screen. Transient voltage suppressors (TVS) are added to the excite lines (X+, X-, Y+, Y-) near interface connector J5 to prevent ESD damage to the IC from touching the screen.

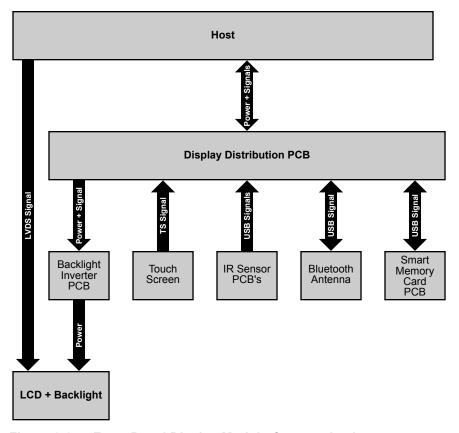


Figure 2-8 Front Panel Display Module Communications



The IR receiver circuit design on the Display Interface PCB is the same as the IR Receiver PCB design used in Alcon's *Infiniti®* system. The received pulse train of remote control transmission signal is converted into USB signals by peripheral controller device AN2131QC, and is sent to the host module.

SD Card Reader PCB

The SD Card Reader PCB interfaces with the Display Interface PCB to receive power and USB signals. There is an on-board Low Dropout (LDO) regulator circuit to generate +3.3 V from the +5 V supply.

The USB 2.0 SD card reader controller has all I/O signals to support SD1.1 flash card specification, and has built-in 2.5 V regulator output to be used as core power for the device.

The SD memory card reader is located at the bottom of the front display panel. Its connector is a reverse mount type so the card can be inserted into the slot with the label facing upward.

Shielding

Separate Faraday shield covers are used over the Display Interface PCB and the Backlight Inverter PCB to minimize radiated EMI emissions from the boards.

Operational Description

The front panel display serves several functions. It displays images processed from the host and GUI software. It houses a touch screen which acts as the primary user input device. It receives signals from the remote control, and sends these signals to the host for processing. The front panel display

module provides a place for Bluetooth antenna installation, and a card slot for Secure Digital (SD) memory card reader functionality.

Display Image Processing

The host software commands that LVDS video signals to be sent from the LDVS port on the host PC motherboard to the display module. These signals travel through a dedicated LVDS cable directly to the LCD module where they are interpreted and displayed on the GUI.

Touch Screen Operation

A finger press generates analog signals from the resistive touch screen. These analog signals travel to the touch screen controller circuitry on the Display Interface PCB where they are converted into USB signals. The USB signals are then routed to the host to work in conjunction with the software to recognize the touch point to activated corresponding system parameters.

IR Receiver Operation

The IR Sensor PCB's read signals transmitted from the remote control. These signals travel to the IR receiver circuitry where they are converted into USB signals. The USB signals are then routed to the host to work in conjunction with the software to control system parameters.

SD Card Reader Operation

Data can be read from, or written to, a SD memory card placed in the slot in the lower center of the display face.

Bluetooth Antenna Operation

The Bluetooth antenna can receive signals from, or send to, any Bluetooth compatible device for the wireless communication.

Cable Routing

Primary Cabling

Two primary cables are connected from the host through the pivot arm assembly and into the display assembly. The first of these cables carries the LVDS signals from the host module directly to the LCD, and the other cable carries power, USB, and control signals from the host module to J1 on the Display Interface PCB.

Both of these cables run from the display assembly through the pivot mechanism and out to the host. The arm assembly has channels to enclose the cables, and each joint is open in the center so the cables may pass through. As the display is manipulated, and each joint is rotated, the cables must twist to follow the motion of the pivot mechanism. The cables have strain relief at the display and at the tabletop so that the twisting can be absorbed over the longest possible length of cable. Additionally, a ground strap is routed through the same path as the primary cabling, grounding the display chassis to the console chassis.

Interior Cabling

Several smaller cables carry signals from the Display Interface PCB to other PCB's in the display module. A pigtail from the touch screen is connected to the Display Interface PCB. Another pair of cables runs from the Display Interface PCB to the IR Sensor PCB's. Yet another cable connects the Display Interface PCB to the SD Card Reader PCB. • • • •



Fluidics Module

The *Constellation*® system uses a modular architecture. The Fluidics submodule is connected to the rest of the system through the 24 VDC system power bus, an ethernet connection, reset and slot ID signals, and a high pressure pneumatic air supply provided by the Pneumatics submodule.

The Fluidics submodule is comprised of two main functional blocks: the cassette and the receiver mechanism. The receiver mechanism consists of twelve functional blocks.

- Cassette Clamp Mechanism
- Cassette Valve Pincher Actuators
- Module Controller
- Non-Invasive Flow Sensor
- Infusion and Aspiration Level Sensors
- Cassette Detection Sensors
- Cassette ID Sensors
- Drain Pump
- LPAS Pump
- Infusion Subsystem
- Irrigation Subsystem
- Extraction Subsystem

These twelve blocks work together to provide the necessary infusion, irrigation, and suction functionality.

To aid in understanding the following written descriptions, block diagrams of the pneumatic system and Fluidics PCB partition are shown in Figures 2-9 through 2-14.

Cassette

The cassette provides direct control of infusion, irrigation, and aspiration fluids. It filters the air provided by the LPAS to ensure that no contamination reaches the patient during operation of pressurized infusion and irrigation functions. The cassette is a consumable assembly that contains pinch valves, flow channels, fluid chambers, a pump section, and clamping features for retention by the receiver mechanism. It will ultimately be available in several configurations; each designed to meet the specific requirements for posterior, anterior, and combined surgical case types.

The premium combined cassette is capable of providing all the functions needed to perform anterior, posterior, and combined surgeries. A drain bag attached to the cassette fills with aspirated waste fluid. The premium cassette provides fluid aspiration and pressurized fluid, filtered air, or infusion to the eye at a constant intraocular pressure independent of aspiration flow rates during posterior segment surgery. The infusion fluid source to the cassette can be changed during a procedure without interruption or re-priming the tubing from the cassette to the infusion cannula.

The Basic (gravity) and Day use cassettes provide fluid aspiration and fluid, or unfiltered air, infusion to the machine with on/off control. They do not provide pressurized infusion, IOP control, or infusion fluid source changes without re-priming.

Receiver Mechanism

The receiver mechanism is housed in the table top console. It provides control of the cassette features listed in above. The receiver mechanism is fully functional with all cassette configurations. The functional blocks of the receiver mechanism are described below.

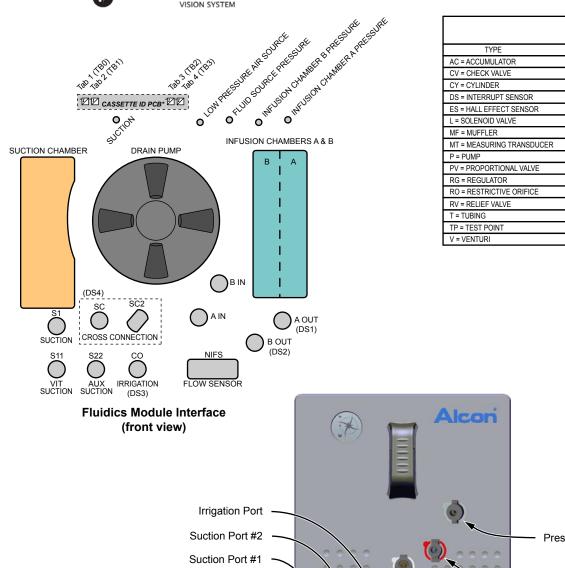
Cassette Clamp Mechanism

The cassette clamp mechanism retains the cassette in the receiver module during a surgical case. It consists of a pneumatic cylinder, a linkage mechanism, clamping jaws, on/off solenoid valves, and a release mechanism. The cylinder is driven by the on/off valves, which are supplied with regulated pneumatic distribution air. Together, these components provide the motion and force necessary to either clamp a cassette or release it. The release of the cassette is commanded by pushing a button on the front of the submodule, which activates an infrared optical sensor under software control. A mechanical release is available to eject the cassette when electrical power or pneumatic supply to the submodule is turned off. The Fluidics system also contains dual optical sensors for detecting cassette presence, and four optical sensors for determining the type of cassette inserted.

Cassette Valve Pincher Actuators

The cassette valve pincher actuators are pneumatic cylinders with special tips on the rods, which contact the valve bubbles on the rear side of the cassette. When the actuators are extended, they compress the valve bubble and close it, thus stopping flow across the valve. There are two types of actuators: a normally-retracted type, which is spring-loaded to return to the retracted position when pressure is removed, and a normally-extended type, which is spring-loaded to return to the extended position when pressure is removed. The type of actuator for each valve bubble is determined by the safe-state requirement for that





Cassette (front view)

| COMPONENT DESCRIPTION | | | | | | |
|---------------------------|--------|---------------|---|-----------|--|--|
| TYPE | NUMBER | FUNCTION | LOCATION | LAST USED | | |
| AC = ACCUMULATOR | 1 | F = FLOW | A[I][O] = INFUSION CIRCUIT A [IN][OUT] | AC4 | | |
| CV = CHECK VALVE | 2 | I = ISOLATION | B[i][O] = INFUSION CIRCUIT B [IN][OUT] | CV1 | | |
| CY = CYLINDER | 3 | IN = INTAKE | BA = INFUSION BACKUP | CY12 | | |
| DS = INTERRUPT SENSOR | ETC | L = LEVEL | CO = IRRIGATION | DS7 | | |
| ES = HALL EFFECT SENSOR | | P = PRESSURE | C[L][U][R] = CASSETTE [LWR][UPR][RELEASE] | ES1 | | |
| L = SOLENOID VALVE | | S = POSITION | D = DRAIN PUMP | L20 | | |
| MF = MUFFLER | | V = VENT | E = SOURCE PRESSURIZATION | MF2 | | |
| MT = MEASURING TRANSDUCER | | | F = F/AX | MT12 | | |
| P = PUMP | | | I = INFUSION SUPPLY | P2 | | |
| PV = PROPORTIONAL VALVE | | | L[O][C] = LATCH [OPEN][CLOSED] | PV9 | | |
| RG = REGULATOR | | | N = NIFS | RG5 | | |
| RO = RESTRICTIVE ORIFICE | | | P = PINCHER SUPPLY | RO2 | | |
| RV = RELIEF VALVE | | | R = REFLUX | RV3 | | |
| T = TUBING | | | S = SUCTION | T7 | | |
| TP = TEST POINT | | | SC = CROSS CONNECTION | TP5 | | |
| V = VENTURI | | | SY = SYSTEM SUPPLY | V1 | | |

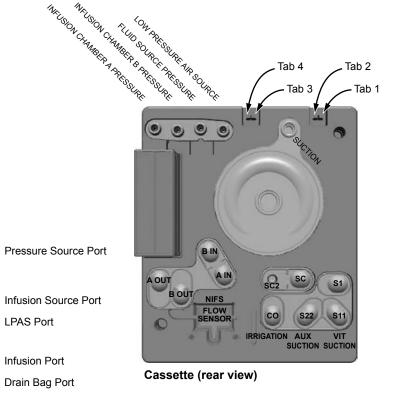


Figure 2-9 - Fluidics Faceplate Interface

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LPAS Port

Infusion Port

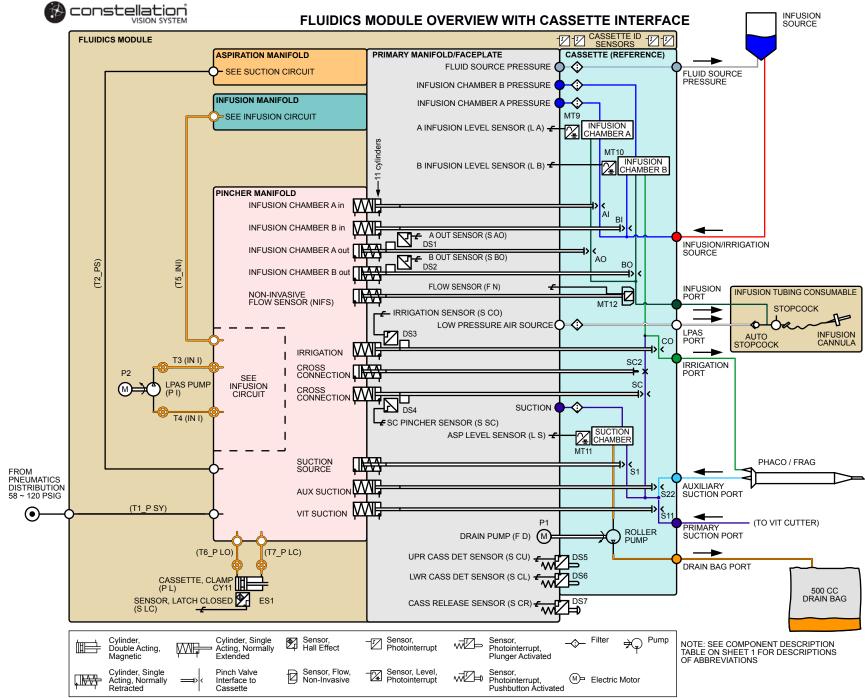


Figure 2-10 – Fluidics External Connections



INFUSION CIRCUIT

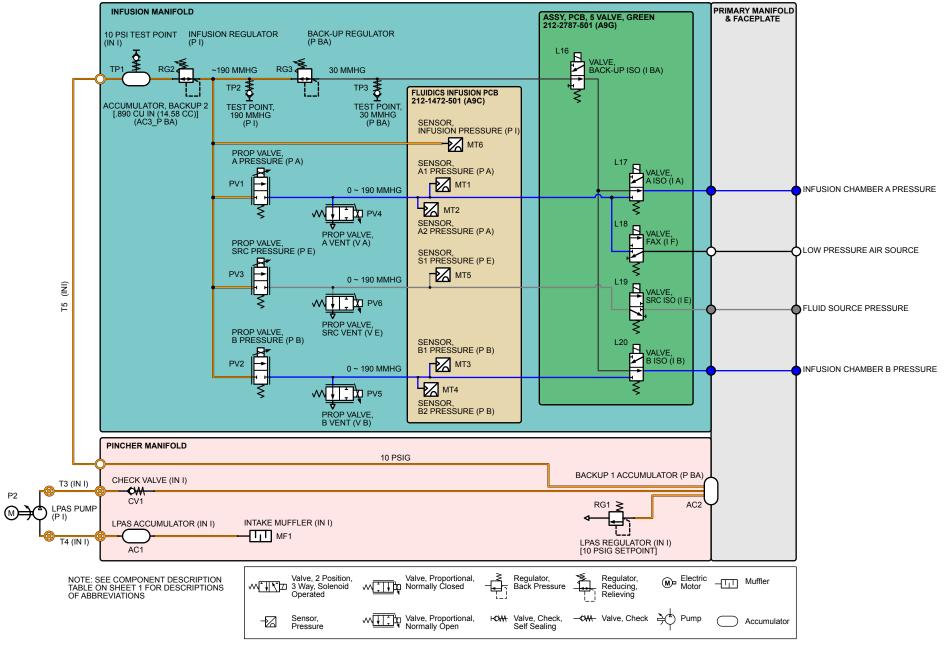


Figure 2-11 - Fluidics Infusion Circuit



SUCTION CIRCUIT

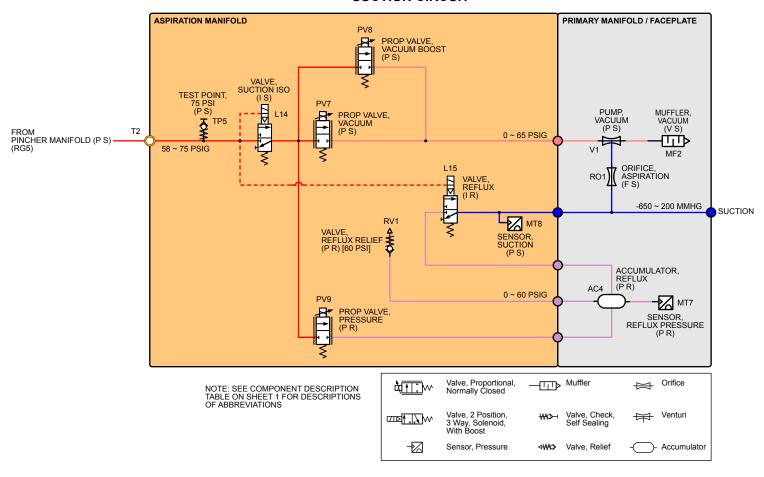
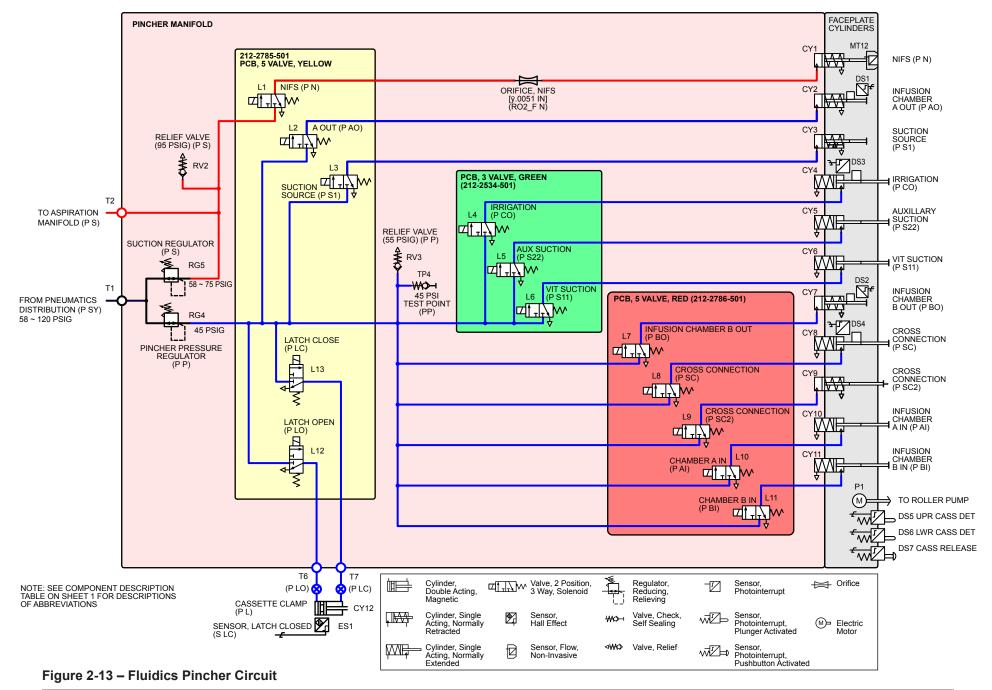


Figure 2-12 – Fluidics Aspiration Circuit



PINCHER CIRCUIT





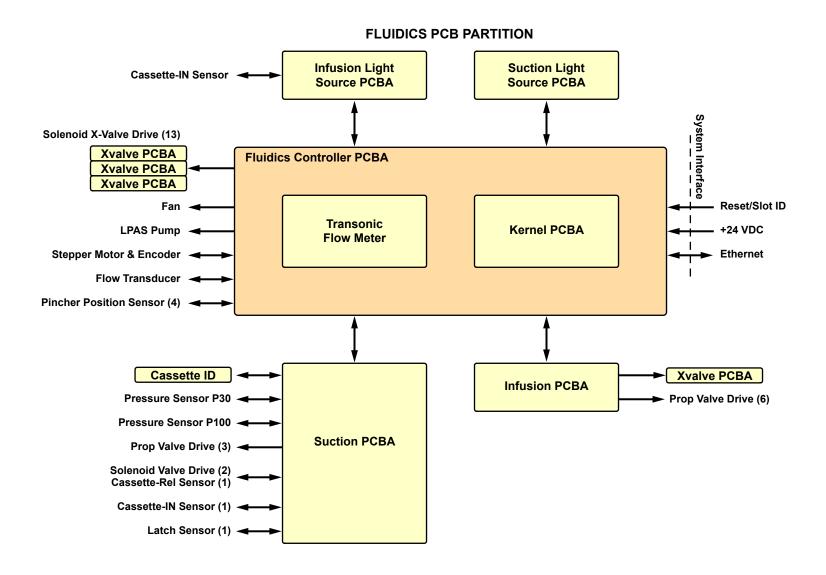


Figure 2-14 – Fluidics PCB Partition



cassette pinch valve bubble. A special type of normally-retracted pincher is used for the cross-connect (normally closed) valve actuator; it has a smaller head diameter so that it can actuate inside the special cassette valve in this location. The actuators are driven by on/off valves, which are supplied with regulated pneumatic distribution air. Valve actuators that have been determined to be critical for safe operation of the submodule are equipped with optical position sensors. The circuitry for these sensors is located on the Fluidics Controller PCB. The driver electronics for all other actuators are equipped with current feedback circuits which allow the software to verify the state of each one of the actuators' drive solenoids.

Module Controller

The module controller is made up of three circuit board assemblies: the Kernel board, the Fluidics Controller board, and the Flow Controller board.

The hardware on the Kernel board is common to all *Constellation*® submodules. It consists of an MPC8270 processor, DRAM and Flash memory, Ethernet and serial communication drivers, an FPGA with common and Fluidics specific logicware, and a number of ADC, DAC, and PWM channels. Flash memory on the Kernel board contains a small boot loader program responsible for downloading the fluidics application program from the Host module during system startup. The application program is downloaded into, and executed out of, DRAM memory.

The Fluidics Controller board provides the necessary interface and drive signals to support the main Fluidics module functions, such as the interface to the level sensors, proportional valve drivers, solenoid valve drivers, stepper motor

drivers, and cassette interface control signals. It also physically interconnects with the Kernel PCB and the Flow Sensor PCB.

The Flow Sensor PCB utilizes ultrasound technology to measure the flow rate of *BSS®* irrigating fluid out of the infusion port on the cassette. The board is connected through a cable to the actual ultrasonic transducers. It receives commands from the Kernel board via one of the MPC8270 processor's serial communication channels. The serial channel is running at 115200 baud to allow for flow measurements to be received from the Flow Sensor PCB at a maximum rate of 1 KHz.

Non Invasive Flow Sensor

The Non Invasive Flow Sensor (NIFS) is a discrete element capable of measuring the flow velocity in a special section of the cassette's infusion flow channel. The sensor contains a pair of piezo-electric crystals. One crystal emits an ultrasound sound signal while the other receives the signal. The two crystals alternate between emitting and receiving. As the ultrasound beam traverses the flow channel, each ray undergoes a measurable phase shift proportional to the average velocity of the infusion flow. The Flow Sensor PCB converts the measured phase shift into a volume flow rate.

When a cassette supporting infusion flow measurements is inserted, the NIFS is moved from its location inside the receiver mechanism out into contact with an elastomeric patch on the cassette; the patch acoustically couples the sensor with the flow channel. During the infusion calibration routine, readings from the infusion pressure and NIFS sensors are combined to characterize the flow resistance in the cassette, tubing set, and infusion

cannula. The equation for the acquired flow rate vs. pressure drop curve is then used in the intraocular pressure (IOP) control scheme, where the IOP is equal to the infusion pressure in the submodule minus the pressure drop in the infusion tubing set and infusion cannula at the currently-measured infusion flow rate.

When no cassette is inserted, the NIFS is retracted back into the receiver mechanism to prevent accidental damage to the sensor's sensitive parts.

Infusion and Extraction Level Sensors

The infusion and aspiration circuits contain chambers in the cassette which are used as reservoirs for the liquid flow demands of each circuit. The level of liquid in each chamber must be known during system operation, since it is these chambers which supply the liquid used during the case (infusion) and store the aspirated fluid (aspiration). The infusion and aspiration circuits provide continuous optical sensing of the liquid levels in the chambers. The level sensor consists of an array of sensing elements that are vertically aligned with the chamber. The liquid inside the chamber blocks the source light from reaching the portions of the sensing elements below the fluid level.

Cassette Detection Sensors

Two mechanisms utilizing optical interrupt sensors are used to sense the position of the cassette relative to the receiver. When the cassette is properly installed into the receiver, the optical sensors are tripped, signaling the software to close the cassette-clamping mechanism.



Cassette ID Sensors

Four optical sensors are located on the Cassette ID PCB mounted on the face of the receiver mechanism. The sensors interface with the plastic tabs on the rear of the cassette. If a plastic tab is present, the IR transmission is deflected and does not reach the corresponding optical sensor. The particular combination of tabs present on a cassette allows the system to identify it for appropriate use in the *Constellation*® system.

Drain Pump

When a cassette is inserted into the receiver, the roller-type drain pump makes forceful contact with the cassette's elastomeric pump section. Rotating the pump causes fluid in the aspiration chamber to be pumped into the drain bag. The design of the pump ensures that the flow rate is directly proportional to the pump rotation speed, while minimizing pulsations associated with peristalsis.

Low Pressure Air Source Pump

The Low Pressure Air Source (LPAS) pump supplies low pressure air to the infusion subsystem. It consists of a positive displacement air pump, an intake accumulator (for quiet operation), a filter/muffler, an accumulator (an air reservoir to supply LPAS under fault conditions), a mechanical regulator set to 196 mmHg, and one pressure sensor to monitor the mechanical regulator output. The pump is used to provide pressurized and filtered air (not nitrogen) for infusion of liquid or air into the eye at a safe pressure level (there is no connection to pneumatic distribution pressure). The integrity of the pressure sensor is checked during setup.

Infusion Subsystem

The infusion subsystem utilizes LPAS pump-supplied air to provide controlled infusion pressure. It consists of three separate circuits. The first two are active infusion circuits; one supplies the cassette's infusion chamber A, and the other supplies infusion chamber B. Infusion circuit B can be used as a redundant infusion circuit or as an irrigation circuit as required by certain case types. The third circuit is the infusion back-up circuit, intended for use when a failure occurs such that neither circuit A nor B can provide pressure to support infusion.

Infusion circuit A includes the components listed below. Together with the module controller, these components control the pressure and flow in infusion circuit A.

- a normally-closed proportional valve which is used to regulate the flow of incoming air.
- a normally-open proportional valve which is used for venting the circuit to atmosphere
- two redundant pressure sensors which sense the pressure in the infusion circuit
- a three way valve used to divert pressurized infusion circuit A air into the F/AX circuit
- a three way valve used to allow 30 mmHg infusion backup air or infusion circuit A air into cassette infusion chamber A.

Similar to infusion circuit A, infusion circuit B includes the components listed next. Together with the module controller, these components control the pressure and flow in infusion circuit B.

- a normally-closed proportional valve which is used to regulate the flow of incoming air
- a normally-open proportional valve which is used for venting the circuit to atmosphere
- two redundant pressure sensors which sense the

- pressure in infusion circuit B, and
- a three way valve used to direct 30 mmHg infusion backup air into the circuit.

The infusion backup circuit is directly connected to the LPAS supply. The backup circuit includes a mechanical regulator set at 30 mmHg and a normally-open solenoid isolation valve. The infusion backup circuit is connected downstream to the normally-open ports on the three-way FA/X valve in infusion circuit A and the isolation valve in infusion circuit B. When either infusion circuit A or B fails, the normally open isolation valve will open, and the three-way valves will shuttle to the normally-open position, thus allowing the 30 mmHg back-up infusion pressure to reach infusion chambers A and B on the cassette.

Source Pressure Subsystem

The source pressure subsystem utilizes LPAS pump-supplied air to provide controlled pressure for the *BSS*® fluidics bottle. It includes the components listed below. Together with the module controller, these components control the pressure and flow in the source pressure circuit. The integrity of the pressure sensor is checked during setup.

- a normally-closed proportional valve used to regulate the flow of incoming air.
- a normally-open proportional valve used to vent the circuit to atmosphere.
- one pressure sensor which senses the pressure in the circuit.
- a three way valve used to isolate the circuit from the port connection to the cassette.

Extraction Subsystem

The extraction subsystem utilizes the pneumatic distribution supply to provide controlled vacuum



or pressure to the extraction circuit. It consists of the components listed below. Together with the module controller, these components are used to control the pressure, vacuum, and flow in the extraction circuit.

- a pressure regulator which regulates the maximum supply pressure to the circuit.
- a normally closed shut off valve which is used to shut off the supply air to the circuit.
- two normally closed proportional valves which supply air to a vacuum generator.
- a venturi vacuum generator which provides vacuum to the circuit.
- an orifice on the vacuum output of the generator which is used to choke the occasional reverse flow through the generator.
- a normally-closed proportional valve which is used to charge a receiver for generating proportional pressure and impulse reflux.
- a receiver.
- two pressure sensors.
- a pressure relief valve which is used to limit the maximum pressure in the receiver during reflux.
- a normally closed shut off valve which is used to charge the extraction circuit from the receiver.

Operational Description

The operation of the different functions supported by the Fluidics submodule is described in this section.

Cassette Insertion and Removal

The two cassette presence sensors are continuously monitored during operation of the system. When both sensor signals indicate that a cassette is inserted (after having been properly debounced) the cassette is locked in place by activating the Latch Close valve and turning off the Latch Open valve. Software monitors the Hall Effect sensor mounted on the latching mechanism to make sure the latch completely reaches its locked position.

After the cassette has been locked in place, the cassette type is identified by reading the analog outputs of four cassette ID sensors. Each ID sensor has an IR transmitter and receiver. The IR transmitters are turned on one at a time to avoid cross-talk between the receivers. The outputs of the ID sensors are connected to four ADC channels on the Kernel PCB. Software reads the analog voltages generated by the sensors and compares them against a threshold value for determining whether or not a tab is present in each one of the sensor locations.

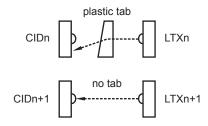


Figure 2-15 - Cassette ID Detection

If the cassette is identified as being compatible with the Non-Invasive Flow Sensor (NIFS), the NIFS actuator valve is turned on to move the NIFS in contact with the elastomeric flow sensor patch on the cassette.

When pressed, the cassette release button on top of the receiver mechanism triggers the cassette release optical sensor. When software detects that the cassette release button has been depressed, an ethernet message is transmitted by the fluidics software to the supervisor subsystem to get an approval to release the cassette. If the current operating state of the machine allows for the cassette to be removed, the supervisor in turn issues a command back to the fluidics subsystem to release the cassette. At this point the NIFS actuator and all pincher valves are retracted, after which the Latch Close valve is turned off and the Latch Open valve is activated to move the cassette clamping mechanism to the open position.

Extraction

The extraction function is used to aspirate cut vitreous and lens material out of the eye. The

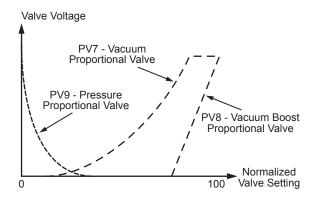


Figure 2-16 - Prop Valve Drive Voltage Mapping



extraction system is venturi based; however, since the *Constellation*® system has the ability to measure the flow of aspirated fluid, both suction and flow control modes are supported.

The fluidics submodule is capable of generating both pressure and vacuum in the extraction subsystem. Three proportional valves are used to control the pressure level in the aspiration chamber in the cassette. The fluidics software executes a control algorithm to control the pressure level in the aspiration chamber. The software reads the redundant pressure sensors and updates the drive voltages to the proportional valves every millisecond. The output of the algorithm is a normalized valve drive voltage setpoint that is mapped into an analog control voltage for each one of the three proportional valves. In this way, the algorithm simultaneously controls all three valves so the pressure level in the aspiration chamber can be varied from +150 mmHg pressure to -650 mmHg vacuum.

One of the differences between this cassette and the Accurus® cassette is that aspirated fluid enters the cassette from the bottom of the aspiration chamber. This design change was made to support the new flow operating modes and various reflux modalities of the Constellation® system. When fluid enters the chamber from the bottom, a continuous flow of fluid enters the chamber. If fluid enters from the top, drops of fluid falling into the chamber causes the fluid surface to fluctuate and disrupt flow measurements; and if air is present in the aspiration tubing set, air bubbles enter the chamber and disturb the flow measurements. In order to minimize the disturbance of air bubbles in the cassette, a plastic wall divides the aspiration chamber into two halves. Air bubbles pass through the fluid on one side of this bubble separator while flow measurements are being made on the other side. Most fluid level disturbances are damped by the presence of this plastic wall.

Suction Mode

In suction mode, the pressure in the aspiration chamber is set to the desired pressure as commanded by the user through the footswitch. The pressure in the aspiration chamber is controllable between +150 mmHg pressure and -650 mmHg vacuum. By allowing the chamber to be pressurized, and by setting the starting range of the treadle-controlled pressure to be close to the IOP, passive flow is minimized and precise control of low aspiration flows can be achieved.

Minimum and maximum flow limits are associated with the suction mode. The minimum flow limit is set to 0 cc/min to make sure regurgitation does not occur if, for some reason, the PEL is not configured correctly. The maximum flow limit is set through the user interface. If the calculated flow goes outside the range of the configured flow limits, the fluidics subsystem automatically transitions into flow control mode. The system transitions back to suction mode when the measured flow is back within the flow limit range. Hysteresis is added to the flow limits to prevent the system from oscillating back and forth between the suction and flow control mode.

Flow Mode

In flow control mode, the flow rate commanded by the user through the footswitch treadle is used as the setpoint to the algorithm that controls the pressure in the suction chamber. The actual flow rate calculated is used as the input variable to the control loop. The peristaltic drain pump is set to a speed that results in the desired flow rate with adjustments made to keep the fluid level in the cassette in the middle of the flow mode operating range. If the fluid level goes outside the flow mode operating range, accurate flow measurements can no longer be made, and flow mode is turned off.

Minimum and maximum pressure limits are associated with the flow mode. If the required pressure to achieve the desired flow rate goes outside the range of the configured pressure limits, the fluidics subsystem automatically transitions into pressure control mode. The system transitions back to flow mode when the measured pressure is back within range of the pressure limits. Hysteresis is added to the pressure limits to prevent the system from oscillating back and forth between the flow and pressure control modes.

Priming

Priming is the process of removing air from the probe and/or handpiece, connecting the aspiration tubing set to the cassette's suction ports, and priming the suction circuits within the cassette. Additionally, priming fills the aspiration chamber with enough fluid to make operating the system in flow mode possible, and to allow reflux. There are two different ways of priming: push-prime and suction prime.

Push-Prime

The push-prime sequence primes the aspiration path of a probe or handpiece that is connected to the cassette by forcing fluid from the aspiration chamber into the aspiration tubing set and the probe or handpiece. Push-priming is only used when the cassette is clean in order to prevent contaminated material from exiting the aspiration ports.



Push-priming is a two step process. First, the aspiration chamber is filled with fluid from infusion chamber B. This is accomplished by applying a vacuum in the aspiration chamber and opening the SC and SC2 valves to open the fluid path between the infusion and aspiration chambers. When a sufficient amount of fluid has entered the aspiration chamber, valves SC and SC2 are closed. Secondly, the selected aspiration port is opened and the aspiration chamber is pressurized. Fluid is pushed out of the aspiration chamber into the aspiration tubing set and the probe or handpiece. The volume of fluid pushed into the tubing set is measured by reading the change of the fluid level in the aspiration chamber. When a predefined volume of fluid has been pushed into the tubing set, the push-prime process is complete.

By utilizing push-priming instead of suction prime, the time required to prime a 25 gauge probe is greatly reduced.

Suction Prime

The suction prime sequence primes the aspiration path of a probe or handpiece that is connected to the cassette by aspirating fluid through the probe or handpiece into the aspiration chamber. The pressure level in the aspiration chamber is set to a predefined vacuum level while the fluid flow into the cassette is monitored. The prime sequence is complete when the fluid level sensor in the aspiration chamber indicates that a certain volume of fluid has entered the aspiration chamber. The prime sequence is considered to have failed if the maximum prime timeout period is exceeded.

Reflux

Reflux is the ability to reverse the direction of aspiration flow such that effluent material is pushed back out of the aspiration tip. Reflux is typically used to clear a clogged aspiration tip. Additionally, it may be used for visualization of a surgical site by "blowing" blood and other material away from a particular point of interest, or it can be used to facilitate entry of the surgical tools into the wound. Three different types of reflux are supported: micro reflux, continuous reflux, and proportional reflux.

Micro Reflux

Micro reflux is created by generating a shortduration pressure pulse at the aspiration port. To generate the pulse, this sequence is executed.

- 1. The reflux valve is turned off to be able to charge the reflux accumulator.
- 2. The reflux accumulator is charged by running the extraction control loop with a high positive-pressure setpoint, typically around 1000 mmHg.
- 3. When the pressure in the reflux accumulator reaches the setpoint, the proportional valve is closed and valve S11 or S22 is opened, depending on the selected aspiration port.
- 4. After a short delay (the delay time depends on the opening time of the aspiration port) reflux valve L15 is turned on. The pressure stored in the reflux accumulator creates a pressure pulse that travels through both the suction port and the suction orifice on the vacuum generator. The suction orifice limits the maximum pressure and duration of the pressure pulse sent through the aspiration port.
- 5. After a predefined timeout period, typically in the 100 mS range, the previously-opened aspiration port valve is closed.

Continuous Reflux

Continuous reflux is reflux that generates a constant fluid flow out of the aspiration tip. Continuous reflux is typically only used to "bloom" the wound site for tool insertion during anterior segment procedures. The continuous reflux function is implemented by configuring the pinchers in the receiver mechanism to route fluid from infusion chamber B through the infusion/aspiration crossconnect path out of the aspiration output port. The flow out of the aspiration port is controlled by the pressure generated in infusion chamber B.

Proportional Reflux

Proportional reflux is reflux that ranges between a low flow rate and a high flow rate depending on the footswitch treadle position. As the treadle is depressed, materials are pushed out of the aspiration line at a quicker rate. The proportional reflux function is implemented by running the extraction system in suction mode with variable pressure setpoints being transmitted down to the fluidics submodule from the supervisor module. The volume of fluid available for proportional reflux is limited to the amount of fluid present within the flow mode operating range of the aspiration chamber.

Occlusion Detection

When anterior flow mode is active, the software monitors the flow impedance for the handpiece connected to the active aspiration port. The occlusion test evaluates different aspiration vacuum and flow conditions and establishes appropriate aspiration limits for the detected conditions.



Drain Bag Volume

The fluidics application software estimates the volume of fluid transferred into the drain bag by utilizing the relationship between the pump speed and the generated flow rate. The pump efficiency relationship has been determined for a typical combination of cassette and receiver mechanism. When the estimated volume of fluid pumped into the drain bag indicates that the drain bag is full, a warning message is displayed to the operator.

Infusion

The infusion subsystem provides control of irrigation and infusion pressures during surgery. The infusion subsystem operates in single chamber or dual chamber mode depending on the type of

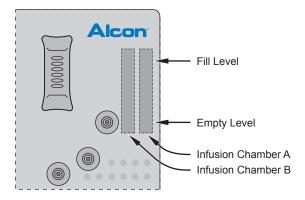


Figure 2-17 - Cassette Infusion Chambers

surgery that is to be performed. With premium cassettes, pressurized infusion and irrigation are supported. With all other types of cassettes, only on/off control of infusion and irrigation are supported. The subsystem also controls infusion of air during F/AX.

The infusion subsystem contains three sets of proportional pressure valves and redundant

pressure sensors to generate simultaneous independent infusion, irrigation, and *BSS®* fluidics bottle pressure levels. Each pressure generator is controlled using a software algorithm.

The fluid levels in the infusion chambers of the cassette are measured using the same type of level sensors used to measure the fluid level in the aspiration chamber.

LPAS Pump

The LPAS pump provides air pressure to the infusion subsystem. The pump charges an accumulator with air to a pressure of 10 PSIG. To ensure safe operation, a pressure regulator located downstream from the accumulator limits the pressure output of the accumulator to 207 mmHg. In the case of a power loss, this volume supplies the 30 mmHg infusion backup pressure circuit with reserve air.

Dual Chamber Mode

The dual chamber infusion operating mode is used with premium cassettes during posterior cases. In dual chamber mode, control of infusion pressure is switched back and forth between the two cassette chambers. While one chamber is providing infusion pressure ("active"), the other chamber ("filling") is being refilled with fluid from the *BSS*® fluidics bottle.

When the fluid level in the active infusion chamber reaches the Empty Level, a chamber switch is initiated. The pressure in the filling chamber (previously filled with fluid) is adjusted to the same pressure as in the active chamber. When the pressure in the filling chamber has stabilized, the output of the filling chamber is opened and the active chamber's output is closed. The pressure

in the previously active chamber is turned off and its input is opened to allow it to be refilled with $BSS^{\tiny\textcircled{\tiny{18}}}$ irrigating fluid.

Software monitors the fluid level in the chamber while the chamber is being refilled. When the level reaches the Fill Level, the input valve is closed. If the chamber does not fill with fluid within a specified timeout period, or if software detects large level fluctuation in the chamber, the BSS® fluidics bottle is deemed to be empty and the operator is notified. The volumes in the infusion chambers were designed to allow the BSS® fluidics bottle to be replaced with enough reserve available in the active chamber to allow the bottle to be replaced without interrupting surgery.

Single Chamber Mode

The single chamber operating mode is used in combined and anterior surgical modes. Both infusion chambers can be active at the same time, providing independent infusion and irrigation pressures. Infusion is controlled by chamber A and irrigation is controlled from chamber B.

In single chamber mode, when the fluid level reaches the Empty Level, the input to the chamber is opened to allow the chamber to be refilled while it provides infusion or irrigation pressure. The *BSS®* fluidics bottle is pressurized to overcome the pressure in the infusion chambers. The algorithm controlling the chamber pressure compensates for the pressure inside the infusion bottle by adjusting the voltages to the proportional pressure and vent valves to not disturb the pressure delivered to the eye during the fill process. When the fluid level in the chamber reaches the Fill Level, the input valve is closed. If the chamber does not fill with fluid within a specified timeout period, or if software



detects large level fluctuation in the chamber, the BSS^{\circledR} fluidics bottle is deemed empty and the user is notified. The Empty Level is set at a higher level than in dual chamber mode to make a large enough volume of fluid available to be able to not interrupt surgery if the infusion bottle runs out of fluid and needs to be replaced.

IOP Compensation

IOP compensation is one of the key innovations with the *Constellation*® system. The IOP control algorithm compensates for the pressure drop caused by fluid flowing through the infusion tubing set to provide a constant IOP. IOP compensation is available only with premium cassettes in posterior and combined surgical modes.

Tubing Calibration

Tubing calibration is required to determine factors required for IOP compensation calculations. During calibration, the infusion cannula is placed at the same level as the cassette and the infusion pressure is ramped from 0 to a max pressure setpoint and back to 0 mmHg while flow and pressure data samples are being collected. The max calibration pressure is dependent on the gauge of the selected infusion cannula.

Priming

Before infusion and irrigation can be turned on, the infusion chambers and connected tubing sets and cannulas need to be filled with fluid.

In dual chamber mode, the following sequence of steps is executed to prime the infusion tubing:

1. AI and BI are opened to fill the infusion chambers with fluid from the BSS® fluidics bottle.

- 2. AI and BI are closed when the chambers are filled with fluid.
- 3. Chamber A is pressurized and AO is opened to start priming the infusion tubing.
- 4. Software monitors the fluid level in the infusion chambers. After a volume of fluid sufficient to prime the path between the output of chamber A and the infusion port on the cassette has flowed out of chamber A, AO is closed and the pressure in chamber A is turned off.
- 5. Chamber B is pressurized and BO is opened.
- 6. After a volume of fluid sufficient to fill the complete infusion tubing set has been transferred out of infusion chamber B, BO is closed and priming is complete.

In single chamber mode, the following sequence of steps is executed to prime the infusion and irrigation tubing:

- 1. AI and BI are opened to fill the infusion chambers with fluid from the BSS® fluidics bottle.
- 2. AI and BI are closed when the chambers are filled with fluid.
- 3. Chambers A and B are pressurized and valves AO and BO are opened to start priming the infusion and irrigation tubing sets.
- 4. Software monitors the fluid levels in the chambers. After a volume of fluid sufficient to fill each one of the connected tubing sets has been transferred out of the chambers, the output of the respective chamber is closed and the pressure turned off.
- 5. When both tubing sets have been filled with fluid, priming is complete.

BSS® Fluidics Bottle Pressurization

The pressure in the BSS® fluidics bottle needs to be higher than the pressure in the infusion chambers in order for the chambers to be refilled while infusion and/or irrigation are turned on. The pressurization circuit is controlled by a software algorithm. The bottle is pressurized to 150 mmHg. No venting of the bottle pressure is available.

BSS® Fluidics Bottle Empty Detection

During operation, with a premium cassette inserted, the system can detect when the *BSS®* fluidics bottle runs out of fluid and issue a warning to the operator. When the operator is notified, a limited reserve of infusion fluid is still available as described previously, allowing surgery to continue while the bottle is being replaced. Additionally, while operating in a posterior surgical mode with a premium cassette, the system keeps track of the volume of fluid remaining in the bottle. When an estimated 50 cc of fluid is left in the bottle, a near empty warning is issued.

Level Sensing

The fluid level sensors utilize 512-pixel linear sensor arrays. The individual sensing elements are spaced 0.005" apart. They provide optical sensing of the liquid levels in the chambers due to the difference between the liquid vs. air effective transmission of the source light which travels through the chambers. The maximum level sensor reading acquisition rate is 1 KHz. The logicware in the FPGA on the Kernel board generates the clock signals which shift out the captured analog light intensity readings of each pixel element. The logicware converts the analog pixel signals into digital values, processes the values, and compares the results against a programmed fluid detection



threshold value. A digital level reading is then presented to the fluidics application software.

The source light to the sensors is generated by two banks of seven LED's. If one bank of LED's fails, the other bank will still provide sufficient light for fluid level readings to continue, but at a reduced level of functionality.

Calibration

The gain of each sensor element within each level sensor is not identical. In order to compensate for this variation, the logicware in the Fluidics FPGA applies a different gain value to each pixel element. After a cassette has been inserted, the software performs a calibration of the level sensors. During calibration, the logicware stores ADC readings from all 512 pixel elements into a memory area in the FPGA, the value for each pixel element being an average of multiple level sensor readings. The fluidics software retrieves the ADC readings and calculates the required gain for each pixel to eliminate sensitivity discontinuity among pixel elements. The resulting gain profile is written back to the FPGA. The gain profile is used by the logicware to adjust the output of each pixel element.

High Resolution Mode

The level sensor is capable of operating in a high resolution mode in which fractional, sub-pixel fluid level information can be acquired. In this mode, the FPGA logicware captures a full frame of 512 pixel intensity readings into a memory array in the FPGA each time a fluid level reading is performed. The logicware compares the captured values against the programmed fluid detection threshold value and returns the pixel location that is closest to this value to the fluidics software. The fluidics

software then reads back the intensity values of the pixels surrounding the triggered pixel location from the FPGA memory array and, by utilizing an interpolation algorithm, uses these values to calculate a high resolution fluid level. Specifically, this high resolution mode is used in extraction flow control mode to be able to accurately calculate the aspiration flow.

• • • •



Pneumatic and Air Distribution Module

The Air Distribution Module provides the Pneumatics and Fluidics Modules with compressed air or nitrogen (N2) gas. The Pneumatics Module provides the required signal to run various pneumatic instruments.

The Pneumatics Module serves several functions. It delivers proportional pressure/vacuum and pulsed fix pressure. It also provides a method to select and deliver a specific gas to a specific consumable.

Air/Gas Distribution Module

The compressed air/gas (nitrogen) is delivered from either source of pressure through the inlet hose to the console. The compressed air/gas is routed through a channel/tube with an online pressure transducer and pressure relief valve. At this point the inlet pressure is monitored to ensure pressure is within a specified range. If inlet pressure is within the specified range, the isolation valve is commanded to open automatically and allow the compressed air/gas to go through, but if inlet pressure is below minimum or above maximum requirements, the operator is advised and it will not open the isolation valve.

If inlet pressure is within the specified range, air/gas is sent through a filter/moisture separator and on to a second transducer. These two transducers read the dynamic pressure differential across the filter/moisture separator to determine filter service intervals and filter status.

Pneumatics Module

The Pneumatics Module consists of two combined independent reservoirs which provide a means to store energy. The stored energy is used to generate proportional and fixed pressures. These pressures are controlled dynamically via a close loop. The main manifold assembly contains a series of submanifolds in which there are valves, transducers, cables, PCBA's, and connectors to support all the components within the assembly.

Dynamic Pressure Control Systems

The pneumatic manifold has two built-in reservoirs which allow two dynamic pressure control systems to operate independently from each other. The proportional valves, together with the transducers and software/PID loop, control the pressure generated by these two independent

pressure control systems. Any pressure set point is generated by a constant communication between the proportional valve and the transducer. The resultant pressure is sent through the appropriate channel to the dedicated control valve. This valve is either open or pulsed, and the pressure is then routed to the dedicated console connector.

• The 58 (psig) Sub-System

The system provides proportional and fixed pressure for the vitrectomy probe (dual acting) and pneumatic scissors. These devices share the same dynamically-variable pressure control system, but do not share the same pneumatic port connectors.

Vitrectomy probes have specific pneumatic requirements. The system generates the required pressure and pulses to run the probes correctly.

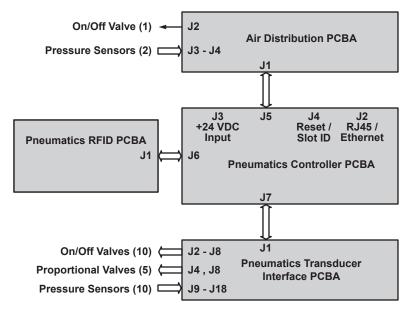


Figure 2-18 Pneumatics and Air Distribution - This figure shows a physical block diagram of the PCBAs and their interconnectivity.



The main manifold provides two ports with different genders to connect and run vitrectomy probes.

Scissors pressure requirements are generated by the same variable pressure and proportional/ pulsed pressure control system, but are delivered through a different single port. It provides all the required proportional and pulse pressures.

• The 80 (psig) Sub-System

The system provides proportional and fixed pressure for forceps, shear cutters, viscous fluid control (inject/extract), and auto gas filling.

Forceps pressure requirements are generated by the variable proportional pressure control system, but are delivered through a different single port.

Shear cutter requirements are generated by the variable proportional pressure control system, but are delivered through a different single port.

VFC requirements are generated by the variable proportional pressure/ vacuum control system, but are delivered through a different single port. This port provides pressure and vacuum for VFC injection and extraction.

Auto Gas Filling (AGF) pressure requirements are generated by the same variable proportional pressure control system, but are delivered through a specific and unique dual/coax port. The delivery system for the gases (C3F8 and SF6) is routed through specific circuits that allow pressure control and selected gas to be delivered to the consumable.

Pneumatic Module Functionalities

• *UltraVit®* Probe High Speed Cutter *UltraVit®* probes require a dual-alternating-pressure signal in order to function. To achieve this requirement the Pneumatic Module has a set of valves strategically located and routed to provide a dual-output pressure. This dual-output pressure is routed to male and female pneumatic connectors located on front of the

module. When the operator selects vit cutting, an electric signal, and a set point pressure (psig) is sent to a 3-way isolation valve; this isolation valve is command to open. At the same time, a second pulsed-electrical-signal (PWM) is sent to a 4-way valve to generate a variable-speed pulsed-dual-output pressure signal to the console dedicated connectors.

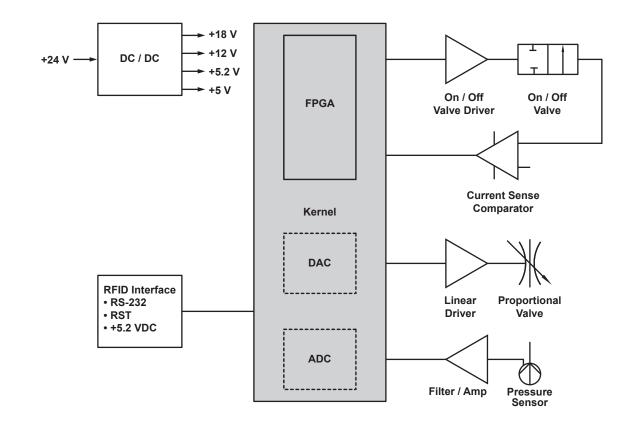


Figure 2-19 Pneumatics Electronics Hardware - This figure shows a functional block diagram of the Pneumatics Module electronics hardware.

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- Scissors and Forceps (fixed or multi-cut)
 Commanded by the operator, and directed by software, an electrical signal and a set point pressure (psig) are sent to a control valve. This is delivered and commands the valve to open. If this takes place, the compressed air/gas coming out of the appropriate console connector is fixed or proportional depending on operator input. On the other hand, if the signal to the control valve is PWM, the valve is pulsed, and the connector at the console delivers a pulsed pressure.
- Viscous Fluid Controller (inject or extract)
 VFC is required to generate proportional pressure and proportional vacuum. To achieve this, the system uses the proportional pressure control system. This pressure is routed through the manifold to the appropriate valve. If this valve is open, proportional or fixed pressure is

delivered to the appropriate connector on the console. If vacuum is required, the same pressure control system delivers pressure to a different valve. These valves redirect the pressure to a vacuum generator. Vacuum is routed to another valve that delivers vacuum to the common console connector.

• Auto Gas Filling (AGF)

AGF requires two different gases (SF6 or C3F8, one at a time) to be routed through the main manifold and delivered to a consumable (i.e., syringe). When the AGF functionality is selected by the operator, an air pressure signal is delivered to the back of the syringe, forcing the syringe plunger to move forward to the front end of the stroke. The next cycle directs the selected gas to enter the manifold and travel through a pressure regulator and a set of redundant transducers. The regulator adjusts the selected gas pressure to a

maximum of 10 PSIG; the inline transducers confirm the pressure set point. The selected gas is then delivered to the syringe. The pressure of the gas forces the plunger to move back to the end of the stroke of the syringe.

At this point the system has completed a full stroke of the syringe, but it is necessary to purge the syringe of the air mixed with gas. Compressed air pressure is routed one more time to the back of the syringe, this pressure forces the plunger to the forward end of the its stroke and the pre-loaded gas is forced to evacuate the syringe via a set of check valves. The next step allows gas to enter and fill the front of the syringe while allowing the back to exhaust to atmospheric pressure. At this point the system has completed a second full cycle, the syringe is full of gas at the required gas concentration, and is at a preset pressure (no mixing).

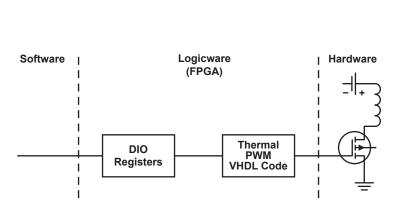


Figure 2-20 On / Off Valve Driver - This figure shows the partition of software, logicware, and hardware that drive the on/off and drive/control proportional valves.

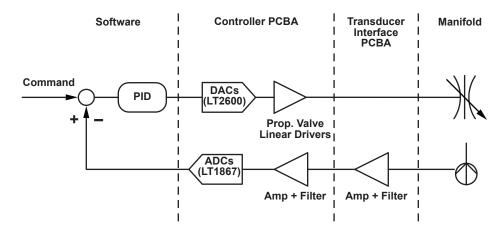


Figure 2-21 Pressure Control - Closed Loop - This figure shows the closed loop control/drive of proportional valves.

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Electrical

The Pneumatics Module provides pneumatics control and air pressure to enable the use of various pneumatics tools such as cutters, scissors, and forceps, and functions such as AGF and VFC. The Pneumatics Module electronics hardware allows control and actuation of on/off and proportional valves, and provides pressure sensor reading for control of these valves, all under software control. The electronics hardware is composed of the following PCBA's.

- The Pneumatics Controller PCBA can be partitioned into kernel and application parts. The kernel provides and supports the Ethernet connection which allows the Pneumatics Module to communicate with the host via the supervisor. The application part of the controller provides valve drivers, DC/DC converters, pneumatics RFID interface, and other circuitry. The Controller PCBA also interfaces with the Transducer Interface and Air Distribution PCBA's.
- The Pneumatics Transducer Interface PCBA interfaces with all the pneumatics module valves and pressure sensors. This PCBA routes valve driver signals from the Controller PCBA to respective valves, and provides 10 conditioned (amplified and filtered) pressure sensor signals to the kernel ADCs, via the Controller PCBA.

• The Air Distribution PCBA resides outside of the Pneumatics Module. It provides access to the main air pressure source. This PCBA routes a single valve driver signal from the Controller PCBA to an on/off valve, and provides two conditioned (amplified and filtered) pressure sensor signals to the kernel ADCs, via the Controller PCBA.



U/S Diathermy Module

The US module includes two PCBs, a large controller with an integrated NGVS PowerPC kernel designed to provide simultaneous ultrasound and diathermy power to respective handpieces, and a smaller PCB used to illuminate colored rings around connectors at the front of the module. The colors reflect the state of a particular connector and/or the attached device.

Other components which are part of this module include two US handpiece interface cables, one diathermy probe interface cable, an interface cable to the Ring Illumination PCB, a sheet metal enclosure, and a plastic face plate.

The block diagram shows the different functions of the US module. They include power conversion, kernel, ultrasound driver, diathermy driver, and ring illumination control.

Power Conversion

The US module is designed to operate on a single 24 VDC supply at a maximum current of 6 A. Inside the module, the 24 VDC is filtered and converted to nine other voltages required by the module's electronic components.

The block diagram shows the structure of the power conversion scheme for the US module with the inputs and outputs of the various regulators.

Input Filters

Two common mode and one differential mode filters are implemented to limit noise and emissions from the +24 V DC input power line to the module. The first common mode filter is a high frequency

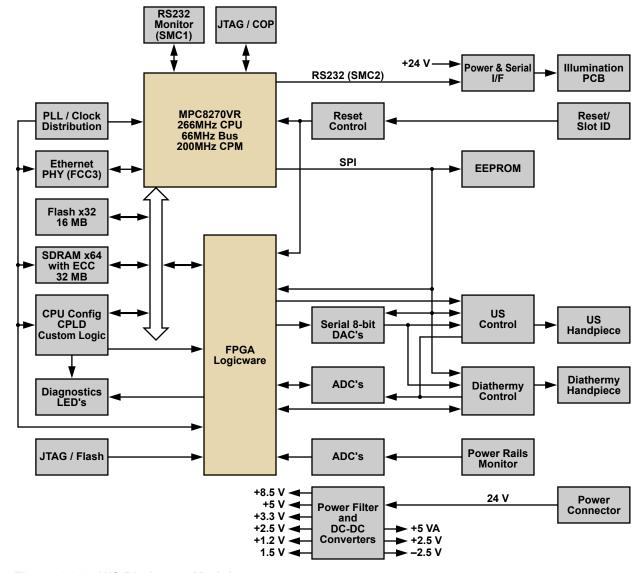


Figure 2-22 U/S Diathermy Module

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two stage filter (L36, L37, C608, & C609) designed to attenuate harmonics of 66 MHz CPU clock and prevent them from escaping the module or radiate off the power cable.

The second common mode and the differential mode filters are built around L2 and L1; they are intended to control the internal power converter harmonics up to 30 MHz, and to protect the module from external power disturbances.

This extensive filtering serves to reduce EMI, and to present a constant impedance to the system power source regardless of the switching or loading fluctuation of the internal DC-DC converters.

Input Power Protection

To meet safety and immunity requirements the module uses 7 A resettable fuse F1 for over-current protection, and 26 V transient voltage suppressor CR1 to limit high voltage transients.

Power Conversion

The DC voltages are designed to meet the power requirements of the different components used inside the module. The DC converter topologies are chosen based on efficiency and current requirements.

The +5 V and 3.3 V are generated using dual phase synchronous converter U5. They are designed for a continuous load of 4 A each.

The +8.5 V is generated at U4, designed for a maximum current of 3 A. It is used to power the FET drivers.

The analog supply +5 VA is derived from +5 V. It is used to power precision analog components

such as ADCs, DACs, and operational amplifiers. Analog supplies +2.5 V and -2.5 V power the RMS to DC converters and the difference amplifiers. The +2.5 V is generated from +5 V with low dropout regulator U3, and the -2.5 V is also generated from +5 V using sepic converter U123; both outputs are designed for a maximum current of 0.3 A.

Digital power sources +1.2 V for the FPGA and +1.5 V for the CPU are generated using two synchronous converters U8 and U6. The converters have integrated FETs and are capable of supplying 4 A to the load. On the module the requirement is about half that value. +2.5 V required by the FPGA is designed for a 1 A load using U7.

The digital voltages are continuously monitored using the POWER_GOOD signals from U6, U7, and U8. These signals are wired-ored together and connected to pin F13 of the FPGA at U23. Logic inside the FPGA uses this signal to reset the module in case these voltages exceed their preprogrammed 10% tolerance.

Power Supply Monitoring

Each of DC voltages has a visual status indicator and is monitored through a dedicated channel of kernel ADCs U63 & U65. ADC U65 is also used to monitor board temperature VTEMP, and reference voltages 2.048 V and 4.096 V.

Kernel

The kernel refers to the microcomputer on the PCB. It consists of a 32-bit MPC8270 power-pc processor running at 266 MHz, DRAM and flash memories, ethernet phy, an FPGA, a CPLD, four 8-channel 16-bit ADCs, and two 8-channel 16-bit DACs. Other key features are listed in Table 2-6.

| <u>Feature</u> | Description |
|----------------|---|
| | |
| Processor | MPC8270VR, 266 MHz Core, |
| | 200 MHz CPM, 66 MHz bus. |
| SDRAM | Up to 64 Mbyte @66 MHz clock rate. |
| | Bus width is x64, with ECC option. |
| FLASH | Up to 64 Mbyte Spansion MirrorBit |
| 501 | FLASH Bus width x32. |
| PCI | PCI not used. |
| Ethernet Port | 10/100 Base T Ethernet ports, Intel |
| | LXT971. MII interface, MDIO and |
| Ethernet LEDs | MDIC generated by CPLD. RJ45 connectors / with LFDs. |
| Monitor Port | 2x5 header for TXD, RXD, & GND. |
| JTAG/COP | 2x8 header, wired per MPC8270 |
| 017107001 | documentation. |
| JTAG/CPLD | 2x5 header for CPLD programming. |
| LEDs | Power (+5V, +3.3V, +1.5V, +24V, |
| | +1.2V, +2.5V). Four Status |
| | (customer: SYSERR, SYSRDY, |
| | PWRGD, HBEAT). Two user LEDs |
| | controlled by CPLD. |
| Reset Switch | Pushbutton mechanical switch. |
| Power Supply | +24 V input power. |
| FPGA | Xilinx XC3S1000. |
| ADC | LTC1867. |
| DAC | LTC2600. |

Table 2-6 Kernel Features Summary



Communication

The US module kernel is assigned IP address 192.168.1.4, and uses the UDP protocol to communicate via Ethernet to the NGVS supervisor.

SPI Bus

The Serial Peripheral Interface (SPI) controller is integrated inside the 8270 PowerPC. It is a common resource used to communicate to serial devices used in the module and the US handpieces.

The SPI protocol is chosen for its speed and ability to communicate variable-length synchronous data packets. It uses three unidirectional lines (MISO, MOSI and SPICLK) that makes it relatively easy to have isolated communication when required.

There are three types of devices in the US Module that use SPI: serial EEPROMs built into the US handpieces and a similar EEPROM at U13 on the US Controller PCB, serial 8-bit Digital to Analog converters U29 & U32, and Numerically Controlled Oscillator (NCO) U27.

In addition to MISO, MOSI, and SPICLK, each SPI device requires a separate line to select it and

| Address 0 | Numerically Controlled Oscillator |
|--------------|-----------------------------------|
| Address 1 | (U27). Current DAC (U29). |
| Address 2 | Current DAC (U32). |
| Address 3 | US handpiece EEPROM port 1. |
| Address 4 | US handpiece EEPROM port 2. |
| Address 5 | Serial EEPROM on the PCB (U13). |
| Address 6-14 | Not used. |
| Address 15 | None. Used to deselect a channel. |

Table 2-7 SPI Devices Address Map

set it in communication mode. The FPGA is used to generate these SELECT signals using a 4-to-16 bit decoder based on the least significant four bits of register DIOO. A list of the SPI devices and their addresses is shown in Table 2-7.

Ultrasound Driver

The ultrasound driver refers to the US programmable DC-DC converter, the NCO, US push-pull amplifier, and the associated FPGA logic and feedback circuits. It is operated in closed loop control to maintain safe and efficient operating conditions for the patient and the handpiece (see Figure 2-23).

Numerically Controlled Oscillator (NCO)

NCO U27 is a 32-bit programmable frequency generator. It is programmed using the SPI interface to generate a desired ultrasound operating frequency in the range of 35 KHz to 45 KHz with 0.009 Hz resolution. It uses 16.67 MHz reference oscillator Y2.

The NCO output is routed to the FPGA and manipulated to generate two complementary square waves to drive the MOSFETS of the ultrasound push-pull amplifier. In normal ultrasound operation mode, the NCO output frequency is adjusted every 1 mS to maintain the handpiece impedance close to its tuned value, and to keep the internal piezos off their resonance points.

U/S Programmable DC-DC Power Supply

This circuit uses synchronous controller U28. It is designed to operate at a constant switching frequency of 150 KHz and deliver a programmable DC output in the range of 0 to 23 V. U28 drives two external n-channel MOSFETs Q8 and Q10

with pulse width modulated (PWM) signals. Top MOSFET Q8 is turned on at the start of a clock cycle, then turned off when inductor L12 current exceeds 10 A, the threshold peak current set at ITH. While the top MOSFET is turned off, bottom MOSFET Q10 is turned on until either the inductor current reverses or the next cycle begins.

U28 pin 8 is left open to allow the DC output to be adjusted by U29, a 0 to $50\mu A$ SPI based 8-bit current DAC placed in the feedback loop. When the DAC current is varied, it causes the voltage sense pin Vosense of U28 to change and the output to change. Vout can be linearly adjusted from 0 to about 23 V when the DAC output is reduced from $50\mu A$ to $0\mu A$.

Ultrasound Push-Pull Amplifier

The ultrasound power amplifier generates a sine wave of the same frequency as the NCO, with adjustable output power of 0 to 35 W into 2500 Ω . The amplifier consists of power transformer T4 with two primaries and one secondary winding configured in a 20:1 turn ratio. Two leads, one from each primary, are tied together to form the transformer center tap, and the other lead of one primary is connected to the drain of power MOSFET Q23 while the other to the drain of power MOSFET Q24.

The center tap of T4 is connected to the output of the DC-DC converter VPHACO. It is used to set the amplitude of the output sine wave. Phaco_CLK1 and Phaco_CLK2 are two complementary clock signals derived from the NCO clock inside the FPGA used to drive the gates of Q23 and Q24, respectively. The resulting waveform at the secondary of T4 is heavily filtered by the low pass



filter formed by L17, C319, and C320 to turn it into a clean sine wave.

The amplifier can be operated in continuous or pulse modes. In pulse mode it is necessary to cut off power to the output at the end of each pulse. This is accomplished by turning Q11 off, and in either mode, when it is necessary to reduce the output power, the DC-DC converter is disabled by turning Q9 on, and its output capacitors are discharged by turning Q13 on.

Ultrasound Voltage and Current Feedback

The ultrasound function is controlled by the module application software which uses concurrent power and frequency PID (Proportional, Integral, and Derivative) loops to control and drive the ultrasound handpiece safely and efficiently.

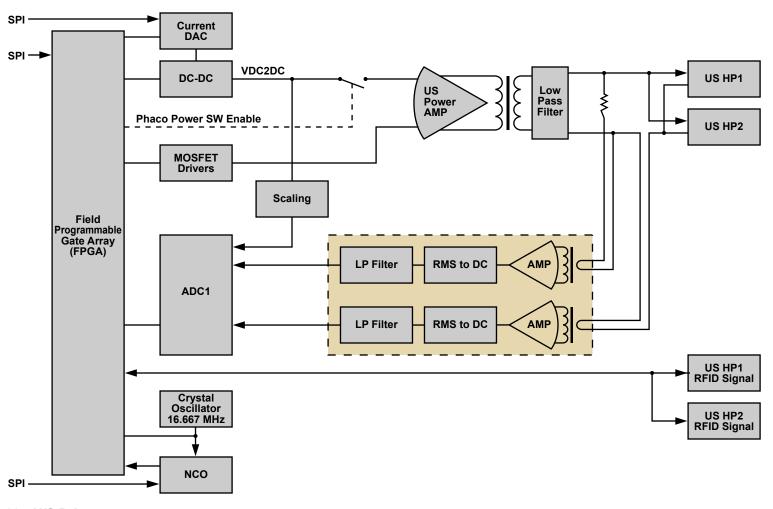


Figure 2-23 U/S Driver



The PID controls depend on parameters such as tune power, tune frequency, and power versus tip displacement table read directly from the handpiece EEPROM, and handpiece voltage and current measured in real time.

The handpiece voltage is sampled at the secondary of transformer T4, using R321 and 50:1 ratio transformer T5. The secondary of T5 is converted to voltage, then amplified five times using difference amplifier U50A before it is converted to a DC voltage using RMS-DC converter U48.

RMS-DC converter U48 operates from ±2.5 VDC. It has a maximum output of 0.707 V which correspond to an input of 1 V peak. The 1 V peak limitation defines the gain of U50A, and the 0.707 V maximum output defines the gain of the ADC driver amplifier to insure that its output falls within the allowed ADC range of 0 to 4 V.

The RMS-DC converter output is filtered first by a two-pole Sallen-Key type filter, then by a single-pole RC filter. The output of the second filter is amplified 5.1 times by non-inverting amplifier U49B. The gain of U49B is calculated using the maximum ADC input 4.096 V divided by the maximum output of RMS-DC converter 0.707 V, and the result is reduced by 0.5 V to account for amplifier offset and bias errors.

In a similar fashion, the handpiece current feedback is sampled with 50:1 ratio current transformer T6. The voltage output of T6 is reduced by 50% by difference amplifier U50B to bring it within the range of RMS-DC converter U52. The U52 output is filtered in the same way as voltage using opamp U43.

When ultrasound function is active, the FPGA samples the ADC values of the handpiece voltage and current as well as the DC-DC converter voltage every 80µsec.

Ozil® and Frag Handpiece Support

Ozil® and Frag handpieces are supported by the same US amplifier. No special hardware is required. In Ozil® mode software switches the amplifier between two different frequencies, one for longitudinal and the other for transverse operation. And the pulse width and amplitude of each is set to meet a specific power need.

Handpiece Interface Circuit

Each ultrasonic handpiece has a built-in serial EEPROM that contains specific parameters necessary for the system to determine its type and tuning parameter such as: Handpiece ID, calibration parameters necessary for proper standard ultrasound stroke at full power, calibration parameters necessary for proper Ozil ultrasound stroke at full power, and the tune start and end frequencies.

When phaco is inactive, the SPI controller continuously hunts for a handpiece to determine when a new handpiece is inserted or removed from the US module.

Functionally the US driver has a single output, but a second port wired in parallel with the first is added to give the user a backup physical connector. The low voltage signal wires of the handpiece cable are isolated from the high voltage to prevent possible crosstalk.

Diathermy Driver

The diathermy driver is a proportional bipolar high frequency amplifier. It is designed to output a 1.5 MHz sine wave to drive electrosurgical probes for the purpose of coagulating vessels and other soft tissues. The amplitude of the sine wave is adjustable via a programmable DC-DC converter. A power control PID loop is implemented in software to limit and control the power delivered to the probe (see Figure 2-24).

The 1.5 MHz base frequency is generated from a fixed source inside the FPGA, and is used to generate COAG_CLK1 and COAG_CLK2 complementary clock signals to the diathermy amplifier MOSFETs, and set the frequency of the sine wave.

Programmable DC-DC Power Supply

This circuit is a replica of the one used for ultrasound. It is based on synchronous controller U31, designed to operate at a constant switching frequency of 150 KHz and deliver a programmable DC output in the range of 0 to 23 V. Pin 8 of U31 is left open to allow the DC output to be adjusted by U32, a 0 to $50\mu A$ SPI based 8-bit current DAC placed in the feedback loop. When the DAC current is varied, it causes the voltage sense pin Vosense of U31 to change, and the output to change.

Diathermy Push-Pull Amplifier

The diathermy power amplifier is designed to drive up to 15 W, 1.5 MHz sine wave into a 75 Ω load. The amplifier consists of the programmable DC-DC converter, power switch Q17, high frequency power transformer T8, and two power MOSFETs Q25 & Q26.



The output of DC-DC converter VDIA is tied to the center tap of T8. VDIA level sets the amplitude of the output sine wave. COAG_CLK1 and COAG_CLK2 are two complementary clock signals derived from the 1.5 MHz clock inside the FPGA, used to drive the gates of Q25 and Q26. The resulting waveform at the secondary of T8 is filtered by L21 and C330 to make it a clean sine wave.

Diathermy Voltage and Current Feedback

The diathermy output voltage is sampled on the secondary of power transformer T8 using a 50:1 of transformer T7. The secondary of T7 is converted to voltage then amplified 1.18 times using high speed difference amplifier U55A. The output of

U55A is converted to a DC voltage using RMS-DC converter U53.

The output of the RMS-DC converter is filtered first by a two-pole Sallen-Key type filter, then by a single-pole RC filter. The output of the second filter is amplified 5.1 times by non-inverting amplifier U30B. The gain U30B is calculated using the maximum ADC input 4.096 V divided by the maximum output of RMS to DC converter 0.707 V, and the result is reduced by 0.5 V to account for amplifier offset and bias errors.

Similarly, the diathermy current is sampled at the secondary of power transformer T8 with another 50:1 ratio current transformer T9. The output of

T9 is converted to voltage, then attenuated 80% by difference amplifier U55B to bring it within the acceptable input range of RMS-DC converter U57. The RMS-DC output is filtered and amplified in the same way as the voltage.

When the diathermy function is active, the FPGA samples the ADC values of the diathermy probe voltage and current as well as the DC-DC converter voltage every 80µsec.

Ring Illumination PCB

The Ring Illumination PCB uses PIC18F4410 microcontroller from microchip to control the lighting of three color LEDs forming light rings around five connectors on the front connector

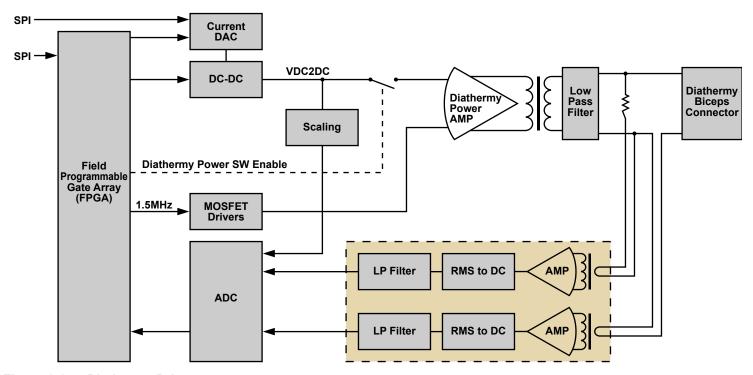


Figure 2-24 Diathermy Driver



panel (see Figure 2-25). Each ring is made of 12 discrete tri-color LEDs. The anodes of all the LEDs are tied together to +5 V, and the cathodes of each color from around each ring are tied to a single n-channel MOSFET. Each MOSFET is driven by a programmable duty cycle output pin from the microcontroller. A total of 12 outputs are used as the two rings for the diathermy are driven in parallel. The microcontroller runs from a 10 MHz external oscillator and has a JTAG interface for testing and programming.

Power and Protection

Isolated power is provided from 3 W, 24 V to 5 V DC-DC converter U104 on the US Controller. Isolation is required because of the PCB proximity to the handpiece connectors.

Fuse F1 is used to prevent possible overloading of the DC-DC converter, and to protect against overcurrent conditions that may occur on the board. CR61 is used to protect against voltage transients over 6 V.

LED Color Interpretation

The different LED colors are chosen to indicate the status of an entry port or the device attached to it when selected for a particular surgical procedure. Ring colors identify the connector status. Blue indicates that the port is ready and is expecting a device to be connected. Green indicates that the device is connected and working properly. Amber indicates that the device is connected, but it may be the wrong device, or it may not be functioning properly.

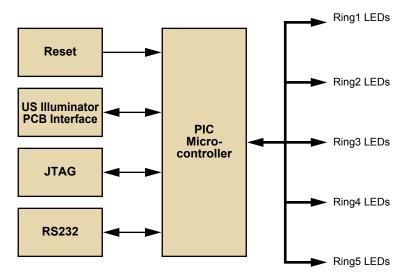


Figure 2-25 Ring Illumination PCB

The brightness of different colors is independently controlled for each ring; it can be adjusted in 224 discrete steps by programming the duty cycle of that color MOSFET driver.

Communication

The PIC18F4410 communicates to the PowerPC SMC2 serial channel at 38400 baud over a standard RS232 interface. Transmit (SMC2_TXD) and receive (SMC2_RXD) lines are optically isolated by U107 and U108 on the US Controller PCB to meet the creepage and clearance requirements defined for the system, and to ensure the Ring Illumination PCB is remains electrically floating.

The use of standard RS232 levels allows flexibility in the choice of test equipment and maximizes communication reliability.

Reset

The PIC processor on the Ring Illumination PCB can be reset in two ways: pushbutton switch S1 on the Ring Illumination PCB which is accessible only during testing, and isolated signal RESET_ILLUM.RESET_ILLUM is generated either from the module main reset line RESET_SYS# or the module software by setting bit 0 of DIO register C0010C00 to one.

All physical connections, including power between the US Controller PCB and the Ring Illumination PCB, are made with a one-to-one cable between J20 on the US Controller PCB and J2 on the Ring Illumination PCB.

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Footswitch

Input to the *Constellation®* system is accepted from a footswitch. The physical structure and function of the *Constellation®* footswitch is broken into two major subassemblies: the main footswitch assembly and the toe/heel switch assembly. The main footswitch assembly houses the treadle and detent mechanisms. The toe/heel switch assembly consists of the housing, environmentally sealed switches, and switch activation mechanism.

Main Footswitch Assembly

The main footswitch assembly consists of a treadle mechanism and six side switches. There are four switch actions on the front of the footswitch (two switches, each with horizontal and vertical action) and two at the heel (vertical action).

The treadle mechanism consists of a treadle, treadle shaft, and gear drive mechanism. The treadle rotation is transmitted to a DC motor to provide three tactile detents by means of a gear drive mechanism. The treadle angle of rotational motion is picked up by the encoder that closes the signal/treadle position loop. Once the treadle force is released, the extension spring returns the treadle to its home position.

The heel switch assembly consists of the switch housing, switch cover plate-striker, electromechanical pushbutton switch, rear fulcrum device, and front cover support device. The heel switch assembly (left and right) is mounted on the rear side of the main footswitch housing.

Operational Description

Most of the surgical functions such as irrigation, aspiration, vitrectomy, phacoemulsification, *AquaLase*[®], diathermy, and reflux are controlled through the footswitch. Major footswitch subassemblies are described in this section.

Treadle Mechanism

The user depresses the treadle to generate a desired signal. The treadle rotates about its shaft under applied pressure. There are four treadle tactile detents, designated 0, 1, 2, and 3. Position 0 is the home, fully upright, treadle position. Positions 2, 3, and 4 are programmed according to system specifications. The return spring tension is adjusted by turning a knob on the front of the footswitch.

Toe and Heel Switches

These pushbutton-type switches are used to enable and disable system functions. The toe switches (one on each side, with two activations each) are activated by pressing the switch cover sideways (horizontally) or down (vertically). The surgical functions the toe switches control are user-remappable, and may include the following: enable/disable cutting in vitrectomy mode, enable/disable U/S in a fragmentation mode, infusion or F/AX mode, diathermy mode, etc.

Each heel switch is activated by depressing the switch cover vertically. The cover pivots about a rear fulcrum and about a front support device. It may rotate about these pivot points or translate vertically down and activate a single pushbutton switch. This complex cover plate motion gives the user the feeling of a "floating" heel switch. The surgical functions the heel switch controls are user-remappable and may include reflux.

Encoder

The incremental type, panel mount, optical encoder used in the *Constellation*® footswitch, is coupled with the treadle rotation shaft by means of a gear train with a gear ratio of 5:1. It is a non-contacting rotary to digital converter with 500 cycles per revolution. The encoder is used as a position feedback device. It converts real-time shaft angle, speed, and direction into TTL-compatible outputs (two digital waveforms 90° out of phase). This encoder utilizes an unbreakable mylar disk, metal shaft and bushing, LED light source, and monolithic electronics. It operates from a single +5 VDC supply.

Vertical Treadle Position

The footswitch treadle is connected to an encoder which outputs quadrature information. This quadrature information is converted to a relative position by the FPGA. The current position is stored in this register. The register contents are cleared by the FPGA upon power on reset, or due to a true (high level) Treadle Up (vertical) signal from the footswitch.

Horizontal Treadle Position

The footswitch treadle is connected to an encoder which outputs quadrature information. This quadrature information is converted to a relative position by the FPGA. The current position is stored in this register. The register contents are cleared by the FPGA upon power on reset, or due to a true (high level) Horizontal Home signal from the footswitch.

Switch Register 1

The footswitch switch register is used to sense the condition of the footswitch switches.



Vertical Detent PWM

The footswitch vertical detent PWM is used to give force feedback to the surgeon. A zero value gives no force feedback and a 0xFFFF gives the maximum amount of force feedback.

Controlling Supervisor Board

The footswitch controlling supervisor board is located in the *Constellation*® console.

Treadle Spring Failure Input Mechanism

The treadle spring failure input mechanism consists of a normally-closed 2-pin switch, stainless steel gold plated push plate, and a push plate mounting lever which is attached to a treadle rotation shaft. The treadle tension adjustment spring preloads the push plate against the two pins. In case of spring failure, the contact between the two pins and a push plate breaks, upon which an electrical signal is sent to the console to warn about the failure.

Footswitch PCB

The Footswitch PCB passes the switch and treadle encoder signals to the Supervisor PCB. The software running on the supervisor receives and processes the switch signals and reads the encoder signals for the treadle position.

Button Switches

The PCB reads the six switch signals from two cables to six momentary switches and outputs them at TTL level outputs to the *Constellation*® supervisor module to indicate the switch status.

Treadle Home Position Sensor

The PCB reads the spring detection sensor signal for Treadle home position, and outputs it at TTL level to the *Constellation*® supervisor module.

Treadle Position

The PCB outputs two-channel quadrature signals from an optical encoder at TTL level to the *Constellation*® supervisor module to indicate the relative position of the footswitch, and to provide linear proportional control. The treadle position is reset by the treadle home sensor.

Detent Motor

The footswitch uses a DC motor to provide force detents and vibration to delineate positions of the footswitch treadle. The number of, location of, and values for the detents and vibration are programmed by the Supervisor PCB based upon the treadle position, which was output by two output signals from the encoder.

Footswitch PCB Revision Output

The voltage divider (resistors on the Footswitch PCB and on the Supervisor PCB) provide a voltage signal to the Supervisor module to distinguish different models of footswitches.

PCB Tilt Switch

The Footswitch PCB has a "tilt tip-over" device installed. The tilt switch operates when tilted from the horizontal position. It is a normally open, nonmercury, contacts switch. The switch movement required to cause control change, off to on, is called the differential angle. When the footswitch is in an operational position, the tilt switch is in its open position; the circuit goes through the tilt switch and a MOSFET device and provides the +5 VDC return signal. When the footswitch tilts more than 60 degrees (±10 degrees) or totally turns over, the tilt switch closes, shutting off the +5 V power supply for the PCB, disabling all of the switches.

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Remote Control

The *Constellation*® remote control is the same as the remote control for the *Infiniti*® system with only minor modifications to cosmetics and top assembly numbers. The remote control's primary components consist of an elastomeric keypad, a PCB that houses the functional electronics, and enclosures that embody the assembly. The remote control is powered by three AAA batteries.

Keypad

The keypad is the user input mechanism for the remote control. The keypad has an elastomeric sheet with formed buttons which protrude through holes in the bezel to form individual keys. Each of these keys has printing on them to indicate which parameter it controls. This elastomeric sheet is sandwiched between the bezel and the PCB. Metallic snap domes are mounted beneath each key to make electrical contact with traces on the PCB when depressed.

Remote PCB

The Remote PCB houses components that serve an assortment of purposes. These components include, but are not limited to, contact traces to create signals, a microprocessor with onboard Flash RAM to process the signals, and IR transmitters to emit the signals. Additionally, the PCB houses a photo-detector to sense low ambient light conditions, and blue LEDs to illuminate the elastomeric keys.

Enclosures

There are two enclosures in the remote control assembly: the front bezel, and the base. The bezel is molded from an IR transparent grade of polycarbonate. This material is molded inside a thin sheet of polycarbonate. For aesthetic reasons, this film has artwork printed on the back side prior to molding. The bezel face has holes that match the shape of each of the keys so that the keys protrude through them when assembled. Additionally, there is a hole in the molded plastic that does not extend through the artwork that allows the transmission of visible light for activation of the previouslymentioned photo detector. The back side of the bezel has a locating post and screw bosses to allow for the mounting of the PCB. There is also a pair of threaded inserts heat staked into the post for the fastening to the base.

The base covers the back side of the remote control. Its exterior is mostly covered with an overmolded elastomeric material that increases friction with the users hand as well as with the surface on which it is resting. An uncovered portion is used to mount the product label. The interior surface has features to house battery contacts and the batteries themselves. Captive fasteners are also mounted to the base for fastening it to the bezel to hold the assembly together.

Operational Description

When the user depresses a key on the elastomeric keypad a signal is generated. This signal is then translated into infrared (IR) digital signals, based upon the USB standard 101-keyboard key codes, and transmitted out the front side of the remote assembly. The IR receivers and supporting electronics in the *Constellation*® system's front

panel display receive and interpret these keyboard signal codes and provide the signal to adjust the desired parameters.

Keypad Activation

When a user applies force on a given key, the elastomeric material deflects inward and applies pressure on the metallic snap dome mounted on the PCB. When a sufficient force is applied, the snap dome flips over center and contacts a series of parallel traces on the PCB. This contact closes a circuit on the PCB that sends a signal to the microprocessor. Each key has a dedicated circuit so that the microprocessor can detect which key is depressed.

Signal Processing

When a signal arrives from one of the keypad circuits, the microprocessor receives the signal and, using the software algorithm stored in the flash RAM, sends out a unique coded signal to the IR transmitters mounted on the front edge of the PCB.

IR Transmission

The IR transmitting LED's send out infrared digital code which is unique for each key depression. This signal passes through the IR transparent material of the bezel and is received and processed by the tabletop.

Illumination

The remote control keys are illuminated during low light conditions. Blue LED's on the PCB are located beneath each key pad, and the elastomeric material of the keypad is semi-translucent. As a result, the light from the energized LED's causes the keys to glow.



Keypad illumination can be triggered either manually or automatically. Manual illumination occurs when the user depresses one of the illumination keys located on the side of the remote control enclosure. In this case the depressed key activates a momentary switch mounted on the PCB. This switch completes a circuit that sends a signal to the microprocessor which in turn completes a circuit to energizes LED's located beneath each key. Automatic activation of the illumination is triggered by the photo-detector mounted on top of the PCB. Light is allowed to penetrate through a window in the bezel directly above the photo-detector. When both the detected light level falls beneath the given threshold and any key is depressed, the microprocessor completes a circuit and the LED's are energized.

Remote Control Channel Selection

The remote control can be configured to operate on one-of-four channels. This feature allows four remote controls to independently control four *Constellation®* systems operating in the same room or area. Remote controls are factory preset to channel A. For proper remote operation, the *Constellation®* system must be set to the same channel as the remote. See operator's manual for instructions.

• • • •



Constellation® / PurePoint® Laser

The *Constellation*® System has two methods of laser interface, and in both of these schemes control of the laser settings (power, exposure, etc.) is made through the *Constellation*® System's user interface by means of its touch screen.

- Tethered Console In this configuration a complete *PurePoint®* Laser console is positioned close to the *Constellation®* System, and operates in a "tethered" capacity by means of an ethernet cable connection.
- Internal Laser Core Module The Constellation® System uses a standard PurePoint® Laser "core module" as the main electro-optical component, mounted and contained within the base assembly of the Constellation® System. The core module consists of an optics block assembly and two principal circuit boards. More detail can be found in the PurePoint® Laser Service Manual.

Core Module Interface - To interface the standard *PurePoint®* Laser core module into the *Constellation®* System chassis, a number of mounting panels and air-ducts are added within the lower base assembly. Within the mounting duct-work are two circuit boards:

• Extender PCB - A portion of this PCB is spring-mounted and has flexible electrical traces that allows a section of the board to "float." This arrangement provides some flexibility to allow the Extender PCB's main 72-pin connector to mate properly with the corresponding connector on the core module. It is through this 72-pin connector interface that all control signals are directed to tether the core module to the *Constellation*® System.

• Breakout PCB - The Breakout PCB contains the connectors, drivers, and signal protection needed to attach the various external devices such as the footswitch and Dr. Filter(s). This PCB supplants the normal Rear Panel PCB used on a standalone *PurePoint*® Laser console, when a core module is integrated into a *Constellation*® System.

The Breakout PCB contains LED's to provide illumination of the connector region on the rear panel. All external connections are protected by surge-supression components and filtered with RF beads. The external interfaces include:

- Footswitch: The Breakout PCB provides +12 V to the footswitch through a common-mode choke. The return signals from the four individual switches within the footswitch are pulled up to +12 V when the associated switch is closed, and these signals are level-shifted to 5 V logic levels and transmitted to the Controller PCB. The 12 V signal from the normally-open main switch is used to power the shutter driver (located on the Bottom Sensor PCB), such that the shutter cannot open unless the footswitch is connected and depressed.
- <u>- Doctor Filter:</u> Two doctor filter connections are provided. Each connection is powered with 5 V and provides both normally open and normally closed connections that are transmitted to the Controller PCB from the Power Driver PCB. <u>- Interlock:</u> This is typically used for a safety
- Interlock: This is typically used for a safety door-interlock, if desired by the user. In order for the laser to operate, external connections between J3 pins 1 to 6 must be in place. If these external connections is broken, the processor stops all laser emission. Typically, a jumper plug is inserted to make the connections, or the

user may elect to wire to a door switch.

- Laser Ready: P2 pins 1 and 9 are connected within the system through a relay when the laser is in Ready or Firing mode. Connection through these two pins can be put in series with an external lamp to provide and external indicator that the laser is firing, or could be firing at any time. The current path through the relay is protected with fuse F4 within the Core Module.

The Constellation Core Module is identical to the *PurePoint®* Core Module with one exception that the internal ethernet communication cable is routed differently. The cable itself is identical between the two, but in the *PurePoint®* module runs from Planet PCB to Rear Panel PCB, and in Constellation module from Planet PCB to Controller PCB.

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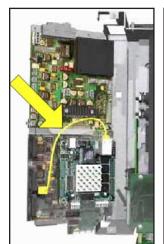




Figure 2-26 Cable Routing - On left is cable from Planet PCB to Controller PCB (*Constellation*® System), and on right is cable from Planet PCB to Rear Panel PCB (*PurePoint*® Laser).

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Base Switch

The Base Ethernet Switch, located in the base assembly portion of the system, is the module that allows communications between all the modules in the console and base assemblies (auxiliary illuminator and laser). It serves as an extension to the console's supervisor. The Base Ethernet Switch contains five 10/100 Mbps fast Ethernet ports fully compliant to the IEEE 802.3u standard. The shared memory based switch fabric is a fully non-blocking configuration. All ports are interchangeable and not specifically addressed.

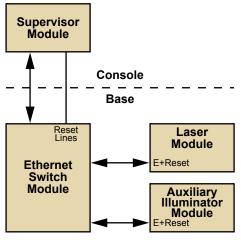


Figure 2-27 Ethernet to Base Switch

Figure 2-27 is an overview of the Ethernet connection from the supervisor through the base switch to the laser and auxiliary illuminator modules. Figure 2-28 shows the base switch.

5-Port Ethernet Switch Controller

The switch controller contains five transceivers, five media access control units, a high-speed non-blocking switch fabric, a dedicated address lookup engine, and an on-chip frame buffer memory. The switch controller is initially reset by passive power on a reset circuit. It is configured as a 5-port integrated switch. The switch controller can also be programmed to perform more advanced features by being configured from the EEPROM.

I2C EEPROM

The EEPROM can store advanced features like broadcast storm protection and rate control. If the EEPROM is programmed, the switch controller will load the information from the EEPROM via an I2C bus on power up.

Power Conditioner

The power conditioner provides conditioned, clean, 24 VDC power to the step-down switching regulators. Over-current protection, over-voltage protection, and noise-filtering circuits are used in this section to protect the board and produce clean 24 VDC for the module.

Step Down Switching Regulator – 24 V to 3.3 V

The step down switching regulator generates 3.3 V at 1.4 A max to power the LED's, the I/O circuitry on the Ethernet switch controller, the EEPROM, and the digital side of the Ethernet magnetics. It also generates analog 3.3 VA to power the physical layer side of the Ethernet magnetics.

Step Down Switching Regulator – 24 V to 1.8 V

The step down switching regulator generates 1.8 V at 1.4 A max to power the core circuitry in the Ethernet switch controller, and analog 1.8 VA to power the physical layer portion of the Ethernet switch controller.

1²C EEPROM

24 V > 3.3 V

5-Port
Ethernet
Switch
Controller
Conditioning

24 V > 1.8 V

Ethernet Jacks with
Magnetics and LED's

Figure 2-28 Base Ethernet Switch



Table Top Illuminator

The table top illuminator system block diagram is shown in Figure 2-29.

The primary components of the Tabletop Illuminator are the Optics Module, the Ballast Module and the Controller PCBA.

Optics Module

The Optics Module produces, filters, and focuses light into the ACMI output ports of the Tabletop Illuminator module. The Optics Module has a Sigma shaped layout which offers a dual channel output from a single light source.

Ballast Module

The lamp ballast provides the initial ignition pulse and the power necessary to sustain the lamp arc. Once the arc is established the ballast acts as a DC constant current source to the lamp. The lamp terminal voltage is governed by the gas chemistry and arc gap length. The ballast output voltage will therefore vary with lamp type and age.

Controller PCBA

The Controller PCBA acts as an interface board between Optics/Ballast/RFID and the Supervisor PCBA. It receives control signals from the Supervisor PCBA for stepper motor drivers, ballast and fan drivers via the TT blind mate connector board. The controller PCBA sends feedback signals back to the Supervisor PCBA for attenuator home position detection, ballast status, over-temperature conditions, lamp power and temperature readings. It also interfaces control signals for the RFID module for fiber detection, ring illumination and RFID tag R/W functionalities.



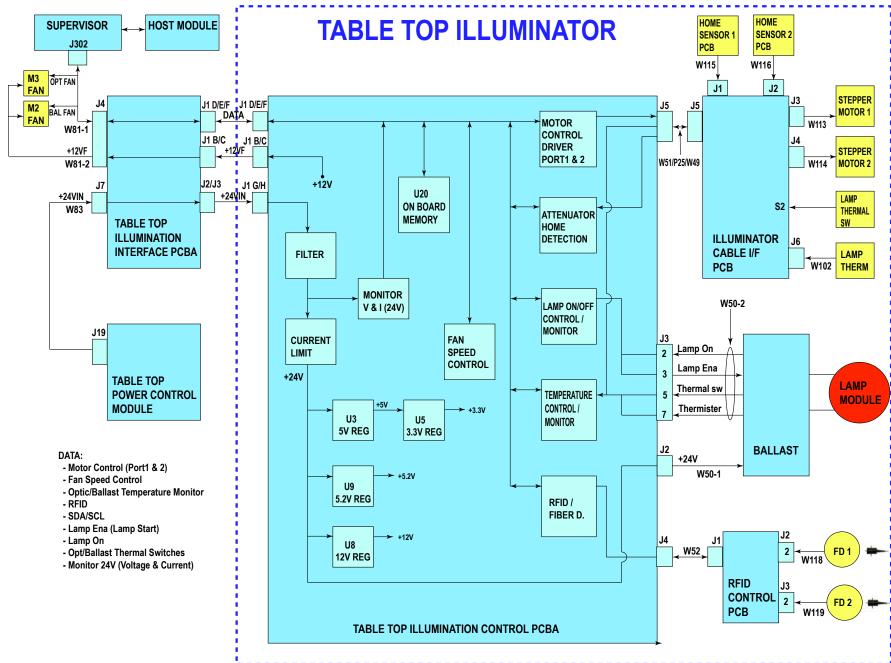


Figure 2-29 Table Top Illuminator Block Diagram



Auxiliary Illuminator

The Auxiliary Illuminator is contained in the base console. The block diagram is shown in Figure 2-30.

The primary components of the auxiliary Illuminator are the Optics Module, the Ballast Module and the Controller PCBA.

Optics Module

The Optics Module produces, filters, and focuses light into the ACMI output ports of the Tabletop Illuminator module. The Optics Module has a Sigma shaped layout which offers a dual channel output from a single light source.

Ballast Module

The lamp ballast provides the initial ignition pulse and the power necessary to sustain the lamp arc. Once the arc is established the ballast acts as a DC constant current source to the lamp. The lamp terminal voltage is governed by the gas chemistry and arc gap length. The ballast output voltage will therefore vary with lamp type and age.

- Ballast Mounting The base of the ballast will mount to the sheet-metal chassis wall by means captive hardware attached to the ballast.
- Ballast Cooling The ballast is intended to be cooled by air drawn from a fan located in the rear of the Auxiliary Illuminator Module. Temperature will be monitored by a thermistor in the Ballast module. Feedback from this thermistor will be used by the Kernel located on the Auxiliary Illuminator Controller Board to control the fan speed.

Auxiliary Controller PCBA

The Auxiliary Controller PCBA controls and monitors the Ballast, Optics, and RFID modules. The communication between the PCBA and the main console is through an Ethernet connection.



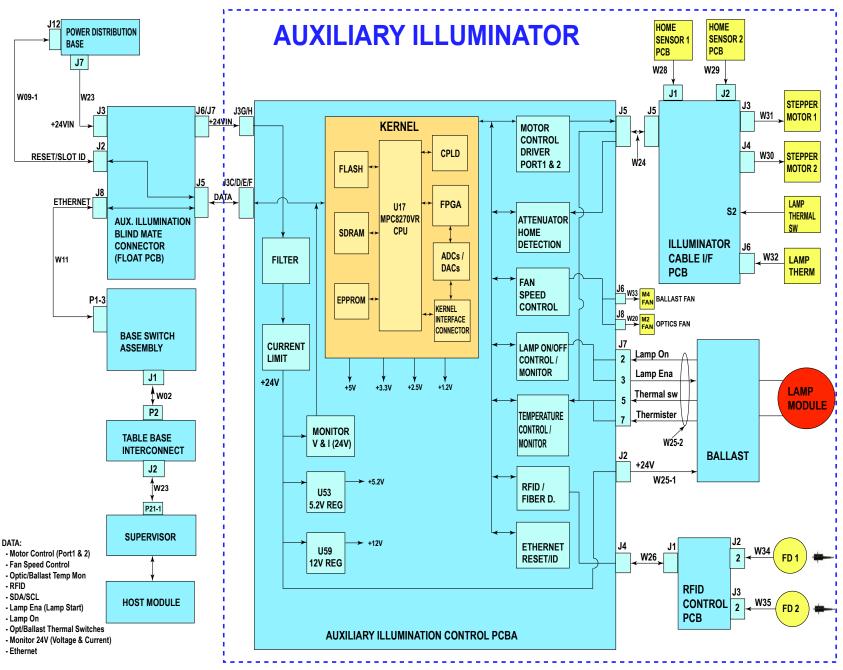


Figure 2-30 Auxiliary Illuminator Block Diagram



SECTION THREE PARTS LOCATION AND DISASSEMBLY

Introduction

Alcon's *Constellation®* Vision System contains several modules inside the Tabletop and Base assemblies. The instructions in this section of the manual are written to help you remove and replace these modules.

WARNING!

Before performing any internal service you must verify system power is turned OFF and power cord is disconnected from power source.

CAUTION

The Constellation® Vision System contains electrostatic discharge (ESD) sensitive devices. Always wear a wrist strap when working with this device.

NOTE: All references to "left" and "right" are directed with the user facing the front of the system.

Module Access and Removal Instructions

- 1. Remove Top Cover from Tabletop Console (see Figure 3-1)
- 1.1 Remove stationary bottle hanger, and barcode scanner holder, by turning each until their alignment pins reach slots that allow them to be removed up and out of the sleeves in their holes (alignment pins and slots are not visible until removed, so you must judge their alignment by feel).

- 1.2 Loosen a captive setscrew in each of two holes that held barcode scanner and bottle hanger.
- 1.3 Remove top rubber mat to expose four captive setscrews. Loosen all four setscrews.
- 1.4 Lift cover off tabletop console.

2. Remove Host Module From Tabletop Console

- 2.1 Remove top cover (step 1).
- 2.2 Loosen three captive setscrews securing Host Module to tabletop frame (see Figure 3-2). Tilt Host up and towards back of system.
- 2.3 To remove rear panel from Host, remove two hex screws from left side, and six screws from right side of rear panel (screws are circled in Figure 3-3). Remove rear panel.



Figure 3-1 Remove Top Cover

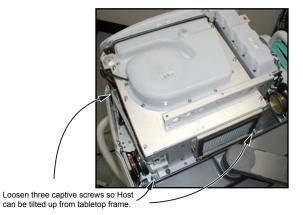


Figure 3-2 Loosen Captive Screws

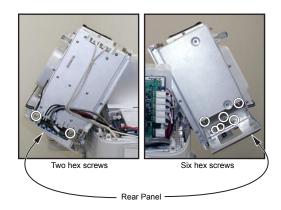


Figure 3-3 Remove Rear Panel From Host



- 2.4 Disconnect cables from Host assembly and Supervisor (see Figure 3-4 for locations):
 - W12 (A2AJ2) on Host
 - W13 (A2AJ3) on Host
 - W14 (A2BP6) on Host
 - W15 (A2BP7) on Host
 - W46 (A2BP19) on Host
 - W16 (A2PB1) on Host
 - W17 (A5A-P22-4) on Supervisor
 - W27 (A5A-P22-3) on Supervisor

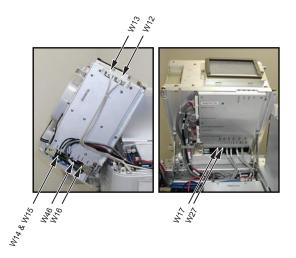


Figure 3-4 Remove Rear Panel From Host

- 2.5 Tilt Host back into its resting position.
- 2.6 Cut tie-wraps securing cables to side of Host assembly. When reassembling, secure cables with tie-wraps where shown in Figure 3-4.
- 2.7 Loosen four captive setscrews securing Host to tabletop frame.
- 2.8 Lift Host up and out of tabletop console.

3. Remove Fan from Host

The fan on top of the Host also serves as the Host top cover. Removing the fan allows access to the Host's internal components.

- 3.1 Remove top cover (step 1).
- 3.2 Disconnect cable W39 (A2BP14) from rear of Host (see Figure 3-5).
- 3.3 Loosen six captive screws securing fan/cover to top of Host.
- 3.4 Lift fan/cover up and off Host assembly.



Figure 3-5 Host Fan/Cover

4. Remove DVD From Host

- 4.1 Remove top cover (step 1) and fan (step 3).
- 4.2 Unplug Power and Data cables from DVD (see Figure 3-6).
- 4.3 Loosen two captive setscrews securing DVD player to mounting plate (white circles in Figure 3-6).
- 4.4 Slide DVD player out from Host.

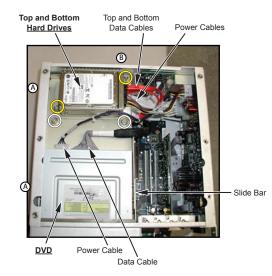


Figure 3-6 DVD and Two Hard Drives

5. Remove Hard Drives From Host

- 5.1 Remove top cover (step 1) and fan (step 3).
- 5.2 Unplug Power and Data cables from hard drives (see Figure 3-6). The Data cables must be properly labeled as TOP and BOTTOM to ensure they are replaced into the correct drives.
- 5.3 Loosen two captive setscrews securing hard drives to mounting plate (yellow circles in Figure 3-6).
- 5.4 Remove hard drives from Host.



6. Remove DVD/Hard Drive Mounting Plate

- 6.1 Remove top cover (step 1), fan (step 3), DVD (step 4), and Hard Drives (step 5).
- 6.2 Loosen two captive setscrews securing screen/filter to front of Host assembly and remove.
- 6.3 Loosen three captive setscrews securing Host assembly to tabletop frame (see Figure 3-2). Tilt Host up and towards back of system.
- 6.4 Remove two screws securing mounting plate to side of Host (labeled A in Figure 3-6).
- 6.5 Remove one screw securing mounting plate to end of Host (where screen/filter was mounted, and labeled B in Figure 3-6).
- 6.6 Loosen two screws securing slide bar to side of mounting plate, then slide the bar backwards to release mounting plate from Host (location of slide bar shown in Figure 3-6).
- 6.7 Remove mounting plate from Host.

7. Gain Access to Components Inside Host

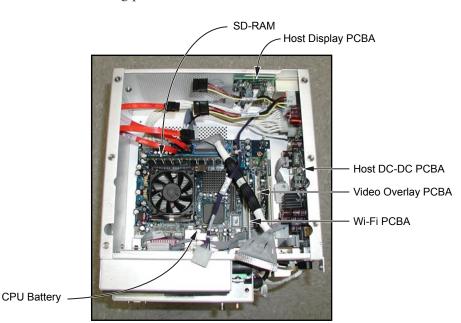
- 7.1 Remove top cover (step 1), fan (step 3), DVD (step 4), hard drives (step 5), and DVD/Hard Drive mounting plate (step 6).
- 7.2 Components inside Host can now be removed as required (see Figure 3-7).

8. Remove Expansion Module

At this time it is not advisable to remove the expansion panels due to possible changes that are being made to these components.

9. Remove Supervisor

- 9.1 Remove top cover (step 1).
- 9.2 Loosen three captive setscrews securing Host Module to tabletop frame (see Figure 3-2). Tilt Host up and towards back of system.
- 9.3 Unplug six cables across bottom, and six cables along left side of Supervisor.
- 9.4 Loosen four captive setscrews to release Supervisor, and remove from bottom of Host module.



Power Connectors

Data Connectors

Figure 3-8 Supervisor

Figure 3-7 Components Inside Host



10. Remove Power Module

- 10.1 Remove top cover (step 1).
- 10.2 Disconnect cables from Power Controller PCB (see Figure 3-9).
- 10.3 Loosen two captive setscrews at front of power module, and one captive setscrew at rear (insert long hex wrench between power module and rear panel).
- 10.4 Grasp power module with both hands and lift it up and out of multi-pin connector securing it to Host.

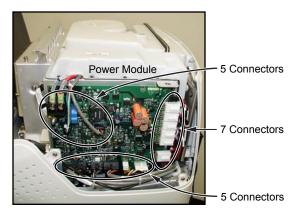


Figure 3-9 Power Module

11. Remove Display Arm Assembly

This instruction will be written in the next version of the service manual.

12. Remove Rear Panel From Display Assy

- 12.1 Remove nine setscrews from periphery of display's rear panel.
- 12.2 Remove rear panel from display. Several display panel components are now exposed (see Figure 3-10).

13. Remove Touch Screen

- 13.1 Remove rear panel (step 12).
- 13.2 Disconnect cable from J5 on Display Interface PCB (see Figure 3-10).
- 13.3 Disconnect cables from IR sensors.
- 13.4 With one hand securing front display panel to the frame, remove four setscrews securing display panel (screws are labeled A in Figure 3-10). Carefully remove panel and touch screen from frame.

CAUTION

Touch screen is not secured when the four setscrews are removed from display panel. Do not drop.

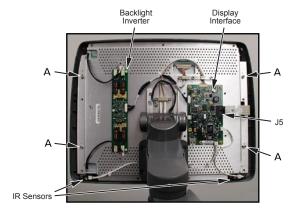


Figure 3-10 Display Assembly With Rear Panel Removed

14. Remove LCD

- 14.1 Remove touch screen (step 13).
- 14.2 Disconnect cable W12 from rear of LCD (see Figure 3-11).
- 14.3 Disconnect four cable connectors from Backlight Inverter.
- 14.4 With one hand securing LCD to the frame, remove four setscrews securing LCD (screws are labeled B in Figure 3-11).
- 14.5 Carefully remove LCD from frame.

15. Remove SD-RAM Card Reader

- 15.1 Remove Rear Panel (step 12).
- 15.2 Remove four setscrews securing cover over SD-RAM reader (circled in Figure 3-11).
- 15.3 Disconnect cable W4 from card reader (see Figure 3-12).
- 15.4 Remove two setscrews securing card reader to frame, and remove card reader.

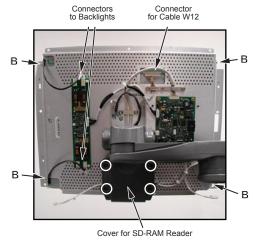


Figure 3-11 Removing the LCD

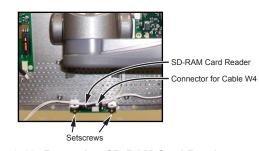


Figure 3-12 Removing SD-RAM Card Reader



16. Remove Front Panel from Tabletop Console

- 16.1 Remove top cover (step 1).
- 16.2 Press in and release tabletop filter tray to eject it from latch mechanism (see Figure 3-13). Remove filter tray.
- 16.3 Remove two setscrews exposed at bottom corners of front panel, and two captive setscrews at upper corners of front panel (all four screws circled in Figure 3-13).
- 16.4 Remove front panel.



Figure 3-13 Remove Front Panel

17. Remove Tabletop Illuminator Module

- 17.1 Press Eject button on tabletop rear panel to release Illuminator Module.
- 17.2 Slide Illuminator Module out from system.

18. Remove Fluidics Module

- 18.1 Remove front panel (step 16).
- 18.2 Loosen three captive setscrews securing Host Module to tabletop frame (see Figure 3-2). Tilt Host up and towards back of system.

- 18.3 Loosen four captive setscrews on front of Fluidics Module (see Figure 3-14).
- 18.4 Slide Fluidics Module forward to gain access to its rear panel connectors.
- 18.5 Use 11/16" wrench to remove Pneumatic tubing from back of module.
- 18.6 Disconnect W34 (power), W24 (ethernet), and W26 (slot ID) cables from back of module.
- 18.7 Slide Fluidics Module out from system.

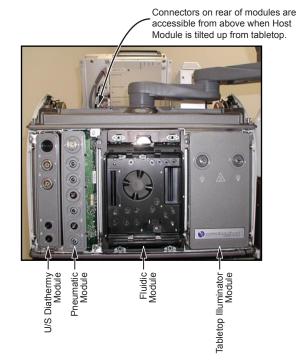


Figure 3-14 Modules With Front Panel Removed

19. Remove Pneumatic Module

- 19.1 Remove front panel (step 16).
- 19.2 Loosen three captive setscrews securing Host Module to tabletop frame (see Figure 3-2). Tilt Host up and towards back of system.
- 19.3 Loosen two captive set screws at front of Pneumatic Module (see Figure 3-14).
- 19.4 Slide Fluidics Module forward to gain access to its rear panel connectors.
- 19.5 Disconnect red and blue pneumatic tubes from rear of module.
- 19.6 Disconnect W32 (power), W21 (ethernet), and W26 (slot ID) cables from back of module.
- 19.7 Disconnect pneumatic pressure hose from rear of module (11/16" wrench).
- 19.8 Slide Pneumatic Module out from system.

20. Remove U/S Diathermy Module

- 20.1 Remove front panel (step 16).
- 20.2 Loosen three captive setscrews securing Host Module to tabletop frame (see Figure 3-2). Tilt Host up and towards back of system.
- 20.3 Loosen four captive setscrews on front of U/S Diathermy Module (see Figure 3-14).
- 20.4 Slide U/S Diathermy Module forward to gain access to its rear panel connectors.
- 20.5 Disconnect W30 (power), W20 (ethernet), and W26 (slot ID) cables from back of module.
- 20.6 Slide U/S Diathermy Module out from system.



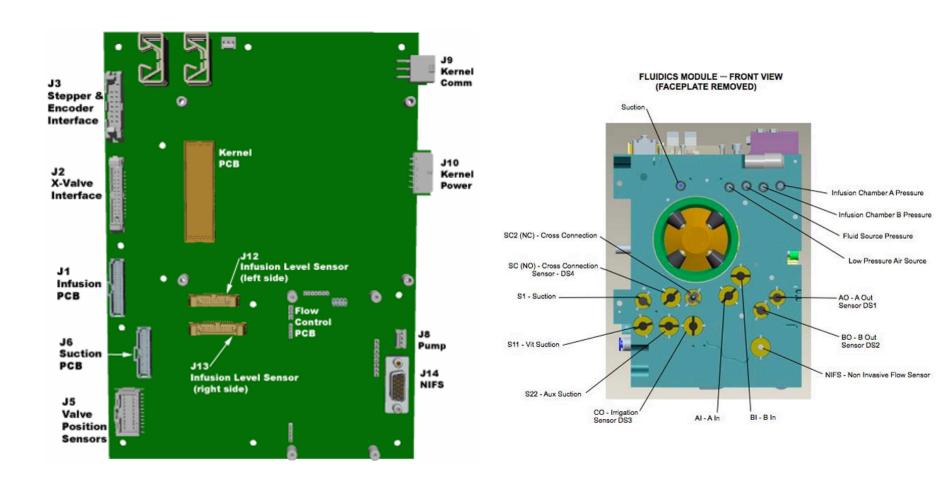
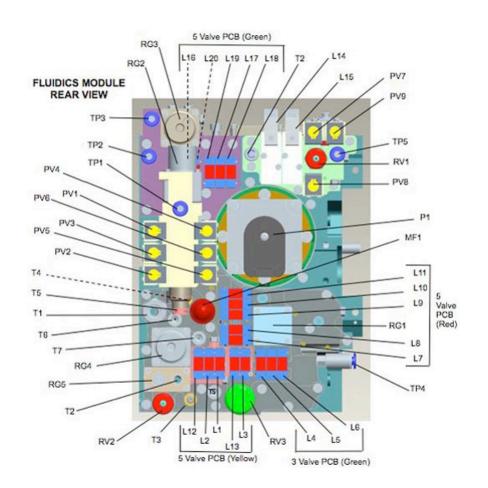


Figure 3-15 Fluidics PCB Locator Diagram

Figure 3-16 Fluidics Module Locator Diagram 1





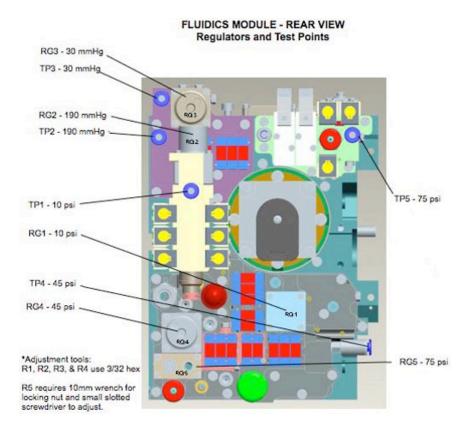
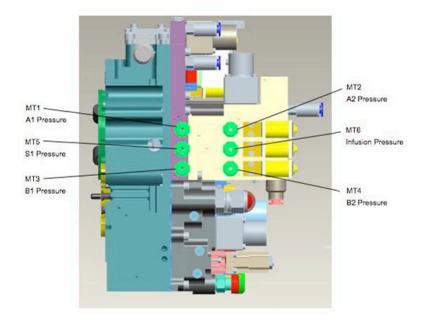


Figure 3-17 Fluidics Module Locator Diagram 2

Figure 3-18 Fluidics Module Locator Diagram 3



FLUIDICS MODULE RIGHT VIEW



FLUIDICS MODULE TOP VIEW

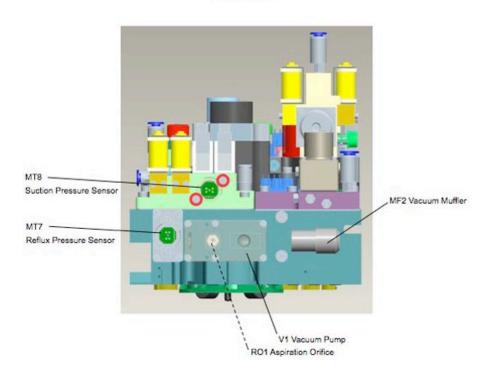


Figure 3-19 Fluidics Module Locator Diagram 4

Figure 3-20 Fluidics Module Locator Diagram 5



Right Side

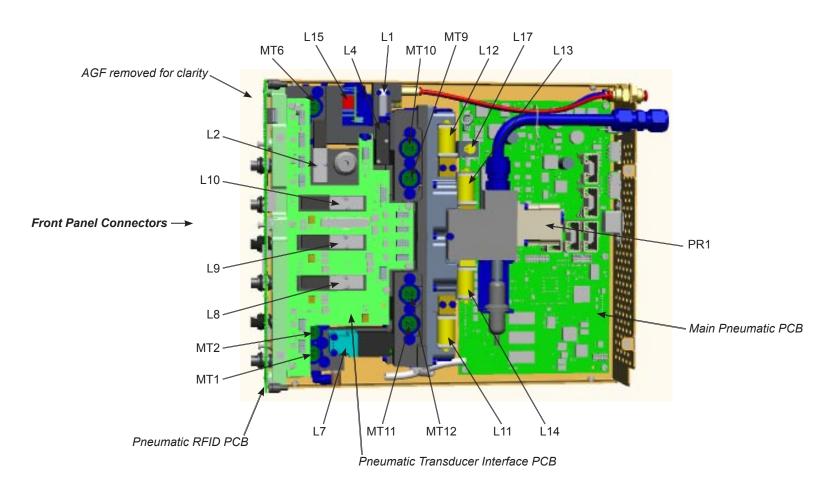
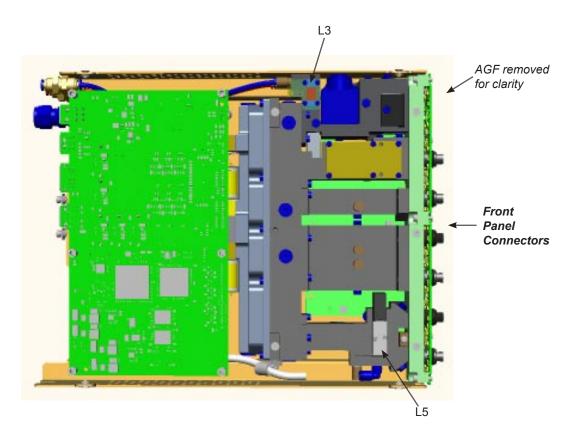


Figure 3-21 Pneumatic Module Locator Diagram 1



Left Side





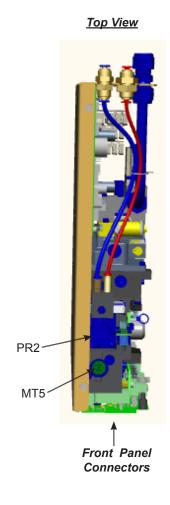


Figure 3-23 Pneumatic Module Locator Diagram 3



SECTION FOUR MAINTENANCE AND TROUBLESHOOTING

GENERAL INFORMATION

This section of the manual contains information to assist the Field Engineer in maintenance, troubleshooting, and repair of the *Constellation®* World Phaco System.

CAUTION

The *Constellation®* system contains electrostatic discharge (ESD) sensitive devices. Always wear a wrist strap when working with this device.

Description Part Number. Quantity **Standard Tools** Standard Tool Set N/A 1 · Screwdriver set, Allen Hex Wrench set, T Handle Hex Wrench set, Rachet and Socket set with Extensions, Metric Box/Open Wrench set, Pliers set. • Large Adjustable or 11/16" Open End Wrench (for Internal Pneumatic Connections). **Special Tools and Test Supplies** Video Capture Box (includes WinTV) N/A 1 Video Converter Box (includes video cables) N/A 1 Null Modem Cable N/A 1 Audio Cable N/A 1 Tubing and fittings required for Pressure tests N/A 1 SD Memory Card (minimum 1Gb) N/A 1 Phaco Handpiece 8065750121 1 25 ga Combined Procedure Pak 8065751071 1 Consumables connectors for RFID tests N/A 1 each Cautery Load box N/A 1 Digital Pressure Meter (DPM) N/A 1 Transducer Test Box N/A 1 Power Meter N/A 1 Power Head N/A 1 N/A 1 Safety Glasses 20 Ga Illumination Probe 8065812001 1 Caster Wrench N/A 1 **Extender Cables** N/A 1 Pneumatic Tubing Extension N/A 1 Scopemeter & 10:1 Probe N/A 1

Table 4-1 Recommended Tools and Test Supplies

SERVICE TEST PROCEDURE

Each time a field engineer works on a system it is required that system checkout is performed. The checkout is performed by following instructions written in the Service Test Procedure (STP), then returning its associated checklist to the local service support center for filing.

The STP/Data Sheet is an independent document, and can be ordered from the local service support center.

8065751153 4.1



| Fluidics Module | 1445-501 | | |
|-----------------------------------|-----------|--------------------------------|---------------|
| Air Dietribution Module | | Assy,PCB,Illum Cable I/F | .212-1974-501 |
| All Distribution Module | 1040-501 | Assy,PCB,Stand-By Switch | .210-1626-501 |
| Power Control Module | 1016-501 | Assy, Pincher, NIF | .212-2282-501 |
| Fabletop Illuminator | 1047-501 | Aux Illuminator Controller PCB | .212-1808-501 |
| Pneumatics Module | 1023-501 | Base Power Distribution | .212-2164-501 |
| J/S Diathermy Module212- | 1037-501 | Battery,Lithium,3v 220mah Coin | 190-022 |
| Display Module | 1003-501 | Cable Assy, W47, Footswitch | |
| Iluminator Latch | 2187-501 | Dc/Dc Conv PCB | |
| Host Module | 1010-502 | Fluidics Infusion PCB | .212-1472-501 |
| Supervisor | 2947-501 | Fluidics Suction PCB | .212-1473-501 |
| PCB 3 Valve, Green | 2534-501 | Infusion Manifold | .212-2172-501 |
| PCB, 5 Valve, Yellow | 2785-501 | Lower Expansion | .212-1869-501 |
| PCB, 5 Valve, Red | 2786-501 | NIFS Sensor Assy | |
| PCB, 5 Valve, Green | 2787-501 | PCB Assy,Video Overlay | .212-2304-001 |
| Agf Coaxial Connector | 2730-001 | PCB Extender | .212-2665-501 |
| Antenna, W1F1 | . 276-339 | PCB, AC Power Distribution | .212-1822-501 |
| Aspiration Level Sensor | 3055-501 | PCB, Bottom Power Distribution | .212-1512-501 |
| Assy, Arm, Display | 1003-501 | PCB, Fluidics, Cass ID | .212-1530-501 |
| Assy, Articulating Arms, Display | 1220-501 | PCB, IR Sensor | .210-1655-503 |
| Assy, Cable, W01, Foot Switch | | PCB, Power Controller | .212-1511-501 |
| Assy, Display, LCD 17 In | 1132-501 | PCB, SD Card Reader Control | .212-1834-501 |
| Assy, Host, Service | 1010-502 | PCB, Sensor, Flow | .212-2316-001 |
| Assy, PCB, Aux Illum Floating | 2368-501 | PCB, U/S-Diat-Aqua Module | .212-1231-501 |
| Assy, PCB, Display Interface | 1794-501 | Pneu Locking Female Connector | .212-1390-001 |
| Assy, PCB, Fluidics Controller | 2936-501 | Pneu Locking Male Connector | .212-1389-001 |
| Assy, PCB, Footswitch212- | 1480-501 | Pneum RFID PCB | .212-1621-501 |
| Assy, PCB, Home Sensor | 2413-501 | Pneumatics Main Controller PCB | .212-2672-501 |
| Assy, PCB, Host Display Conn | 1796-501 | Power Bracket Connector | .212-2714-501 |
| Assy, PCB, Illum RFID Cont212- | 1630-501 | Transducer Intf PCB | .212-2710-501 |
| Assy, PCB, InterFace Breakout212- | 1727-501 | Tray Arm | .212-1004-501 |
| Assy,Base, Switch | 1646-501 | TT Floating Conn | .212-2360-501 |
| Assy,Manifold,ASP Fluidics | 2154-501 | Upper Expansion | .212-1868-501 |

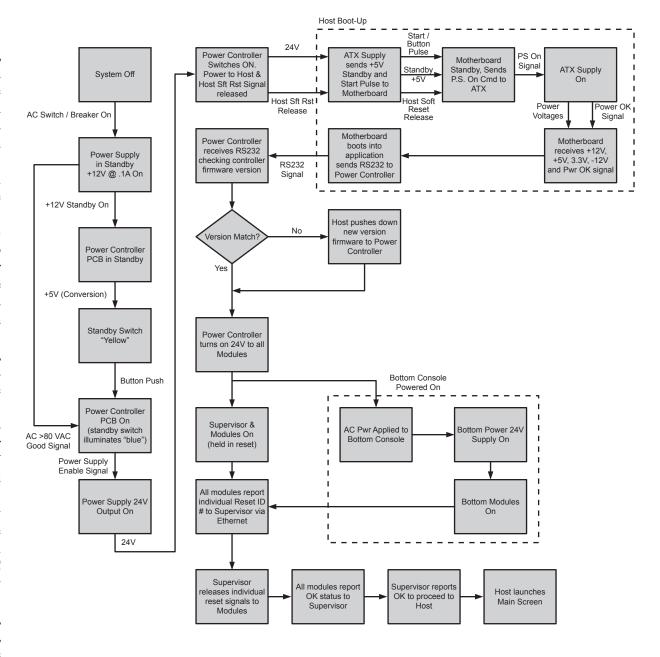
Table 4-2 Service Spare Parts

8065751153 4.2



POWER UP SEQUENCE

- 1. With power cord plugged into AC outlet, turn On/Off rocker switch/breaker, located on rear of table top, to the ON position. The Power Controller PCB receives 12 V from the 900 W power supply and converts/sends 5 V / 100 mA to the standby switch; its button illuminates amber.
- 2. Press the amber standby button to begin powering up the system. The button turns blue to indicate the boot sequence has begun.
- 3. The Power Controller PCB sends the PS enable signal to the 900 W power supply to allow 24 V to go through the battery charger to the 18 V Li-Ion battery and back to the Power Controller PCB which then delivers 24 V to the Host ATX DC/DC PCB through J4.
- 4. The ATX DC/DC PCB sends -12 V, +5 V, +3.3 V to the Motherboard. It also sends +12 V to the Display Module through the Display Interface PCB.
- 5. After a few minutes, the Host Module sends a message back to the Power Controller PCB through J6, triggering +24 V 900 W power supply to the table top modules and supervisor.
- 6. After the table top modules successfully report back to the Supervisor, and if Table Top is connected to a Base unit, a Host signal triggers the delay switch which allows AC power to enter the Base 650 W power supply and its modules.
- 7. Once Table Top modules (and Base modules, if present) report back to the Supervisor, the Supervisor sends a message through the ethernet indicating it has taken control.



Power Up Sequence Figure 4-1

8065751153 4.3



PRESSURE HOSE SETUP

The pressure hose is shipped in a configuration compatible with some facility air pressure source fittings; however, a BSPT-to-NPT adapter is packaged with the hose assembly to accommodate a facility with an NPT fitting at the pressure source. The shipped configuration is shown in Figure 4-2.

Notes:

- To ensure proper function of system, all pressure source fittings and hoses must have a minimum 1/4" inside diameter. If smaller diameter fittings are use in conjunction with the inlet hose fittings, degradation of performance will be experienced at minimal inlet pressures (58.8 psig/ 4 bar).
- All fittings on Alcon-supplied components are BSPT except for the BSPT-to-NPT adapter.
- Use thread sealant when connecting fittings.

Pacility Pressure Source (air) Quick Disconnect Fitting Quick Disconnect Fitting Adapter (use if necessary to adapt hose to facility pressure source) Right Angle Fitting (optional)

Figure 4-2 Shipped Configuration (for AIR pressure source)

Air Pressure Source Configuration

To connect the *Constellation*[®] System to a facility air pressure source, perform the following steps (see Figure 4-2).

- 1. Determine if facility has a BSPT or NPT fitting.
 - For BSPT fitting, no change is required; use pressure hose as shipped.
 - For NPT fitting, connect BSPT-to-NPT adapter to fitting on hose.
- 2. Connect threaded end of hose to facility air pressure source.
- 3. Connect quick disconnect fitting to rear panel of *Constellation*® System. If desired, a right angle fitting, included with hose assembly, may be added where shown.

Nitrogen (N₂) Pressure Source Configuration

To use a nitrogen pressure source, the fittings on the shipped hose configuration must be changed as instructed below (see Figure 4-3).

- 1. Remove connectors from both ends of hose.
- 2. Connect supplied NIST N₂ fitting to BSPT fitting on hose.
- 3. Remove female quick disconnect fitting from other end of hose.
- 4. Remove male quick disconnect fitting from rear panel of system.
- 5. Connect hose assembly to rear panel of system.
- 6. Connect hose's NIST N₂ fitting to facility's N₂ pressure source.

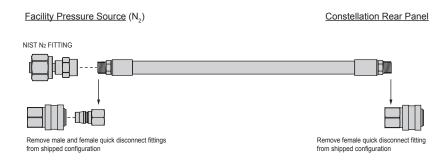


Figure 4-3 Modified Configuration (for N₂ pressure source)



REPLACE ILLUMINATOR LAMP

The *Constellation*® System's xenon arc lamp is specified to last 400 hours in normal usage. Some possible indications that the lamp needs to be replaced are listed here:

- A message appears on the display stating that the lamp should be replaced.
- Repeated failure to ignite lamp.
- Flickering of output light.
- Insufficient light output.

WARNINGS!

- Burn hazard exists. Do not remove lamp immediately after operation. The lamp temperature may be above 100° C. Allow lamp to cool for a minimum of five minutes before handling.
- Handle the lamp carefully when installing and/or uninstalling from the unit in order to prevent touching the glass to adjacent components.
- Do not touch the bulb glass. Contaminants from hands can cause the lamp glass to crack during use.
- Use eye protection when installing and uninstalling lamps. The lamp is pressurized and presents an explosion hazard if it is damaged and/or dropped, or if the glass envelope of the bulb is punctured.
- · Do not drop the lamp.
- Always store the lamp in its protective housing when it is uninstalled from the unit.

Removal

- 1. Extinguish lamp and wait a minimum of five minutes for lamp to cool.
- 2. Press ejection button on the back of tabletop or base (see Figure 4-4).
- 3. Pull illuminator assembly out to its full extension (see Figure 4-5).
- 4. Turn latch on top of illuminator 90° CCW (see Figure 4-6) and lift door up to its limit (see Figure 4-7).
- 6. Lift up on green bar of lamp clamp until it contacts door.
- 7. After waiting for lamp to cool, carefully lift lamp straight up and out of lamp chamber (see Figure 4-8).
- 8. Place lamp in its white plastic protective cover (see Figure 4-9).

Replacement

- 1. Remove new lamp from its shipping box.
- 2. Remove white plastic protective cover from lamp (see Figure 4-9).
- 3. Carefully insert the new lamp into socket in lamp chamber and push down on lamp until lamp clamp is vertical (see Figure 4-10).
- 5. Push down on lamp clamp until it is horizontal (see Figure 4-11).
- 6. Close illuminator door and push down on door latch while rotating it 90° CW.
- 7. Push illuminator assembly back into tabletop or base with sufficient force to engage latch.
- 8. Save white plastic protective cover and shipping carton for future lamp disposal.

Lamp disposal on next page







Figure 4-5



Figure 4-6



Figure 4-7



Figure 4-8



Figure 4-9



Figure 4-10

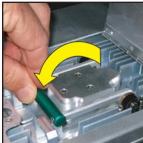


Figure 4-11

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4.5



Lamp Disposal

- 1. Place supplied cable tie around base of lamp and white plastic protective cover to ensure they stay together (see Figure 4-12).
- 2. Place lamp on edge of a hard, stable surface and strike center of white plastic protective cover with a hammer or other tool with sufficient force to break glass and depressurize lamp (see Figure 4-13).
- 4. Place discharged lamp with its protective cover in shipping box.
- 5. Dispose of carton in a standard trash receptacle.





Figure 4-12

Figure 4-13

REPLACE CPC CONNECTORS

There are three types of CPC connectors on the front panel of the Pneumatic Module: male, female, and coaxial (see Figure 4-14). The male and female pneumatic locking connectors are easily removed by inserting either a 3/32" or 1/8" hex wrench into the center of the connector and turning CCW. To replace, follow the instructions below.

- 1. Add a light coating of locking adhesive to threads of CPC connector (see Figure 4-15).
- 2. Place connector on hex wrench and insert connector into front connector panel.
- 3. Turn connector CW with hex wrench until it takes hold, then press and wiggle connector with your fingers until alignment ears click into their slots (see Figure 4-15).
- 4. Firmly tighten CPC connector with hex wrench.

The top AGF coaxial connector can be removed after removing Pneumatic Module from system.

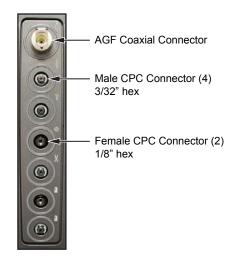
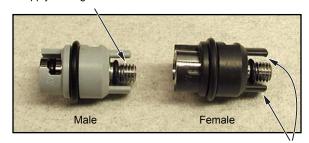


Figure 4-14

Apply locking adhesive to threads



Alignment Ears

Figure 4-15



DISASSEMBLE ILLUMINATOR ASSYS

Disassemble Table Top Illuminator

1. Remove nine 2 mm screws securing chassis top cover. Remove cover.

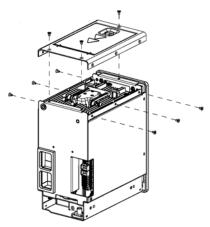


Figure 4-16

2. Remove two 2.5 mm screws from under chassis, and two 2 mm screws from chassis top, and remove front cover.

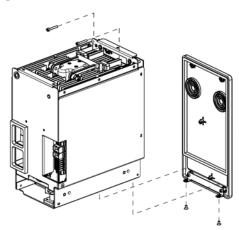


Figure 4-17

3. Remove three phillips screws and remove latch bracket.

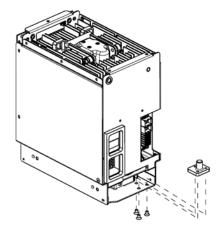


Figure 4-18

4. Remove two 2 mm screws from rear of chassis. Remove rear chassis panel.

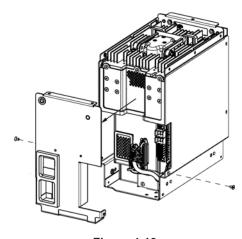


Figure 4-19

5. Remove four 3 mm screws securing RFID PCB to front of chassis. Disconnect three cables and remove RFID PCB.

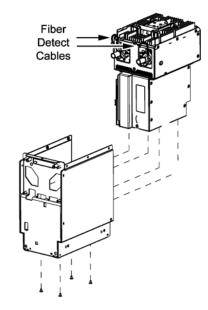


Figure 4-20

6. Remove four screws from under chassis. Remove chassis.

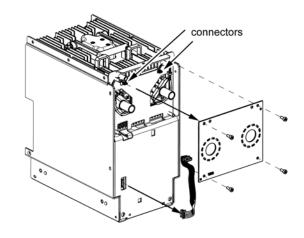


Figure 4-21



7. Remove four 2 mm screws securing connectors at rear of power supply. Disconnect two cables at both ends and remove.

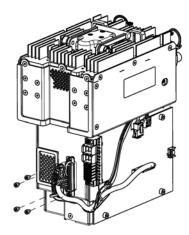


Figure 4-22

8. Remove four 3 mm screws securing Illumination Control PCB to power supply. Remove Illumination Control PCB.

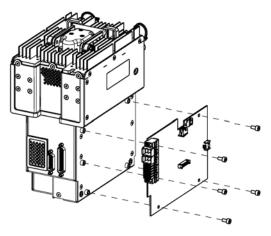


Figure 4-23

9. Remove eight 2 mm screws securing power supply to optics block. Separate the two and carefully remove optics block. ••••

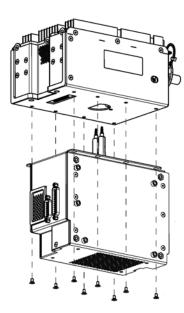


Figure 4-24

Disassemble Auxillary Illuminator

1. Remove six 2 mm screws securing top cover to chassis. Remove cover.

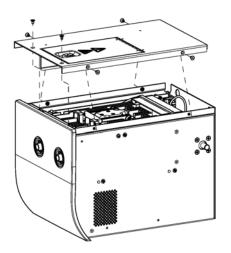


Figure 4-25

2. Remove two 2 mm screws from sides, and two 2.5 mm screws from top of chassis. Remove front panel.

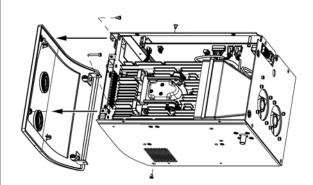


Figure 4-26



3. Remove five screws (2 mm and 2.5 mm) securing rear panel to chassis. Pull panel away slightly to access and disconnect two fan cables. Remove rear panel.

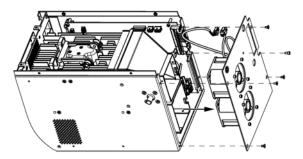


Figure 4-27

4. Remove two 2 mm screws from side of chassis, and pull the vent duct out and away.

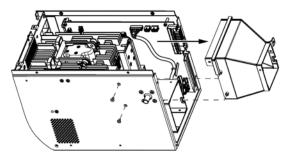


Figure 4-28

5. Remove three 2.5 mm screws securing lower duct. Remove lower duct.

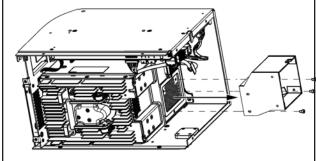


Figure 4-29

6. Remove four 2.5 mm screws securing two cable connectors to back of power supply. Disconnect both ends of cables and remove from chassis.

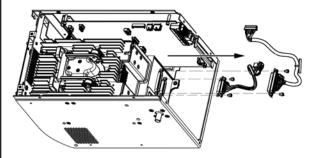


Figure 4-30

7. Remove four 2.5 mm screws securing RFID PCB to front of chassis. Disconnect cable from Illuminator Control PCB, and remove RFID PCB.

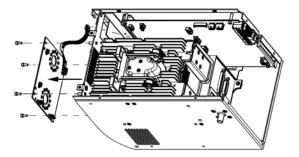


Figure 4-31

8. Remove three 3 mm screws securing Illuminator Control PCB to chassis. Remove Illuminator Control PCB.

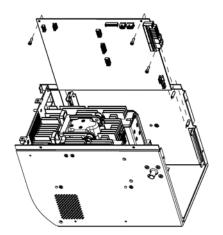


Figure 4-32



9. Remove three 2 mm screws from under chassis, pull chassis frame away and remove.

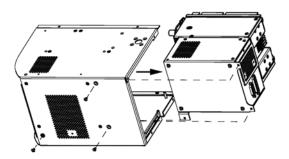


Figure 4-33

10.Remove four screws securing power supply to Optics Block assembly.

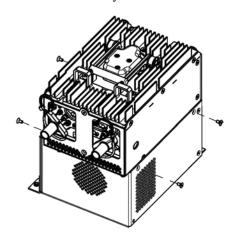


Figure 4-34

11. Carefully separate power supply from Optics Block (to gain access) and disconnect ribbon cable. Remove one 2.5 mm screw securing high-voltage connector to Optics Block. Remove connector from Optics Block and set block aside in a clean area.

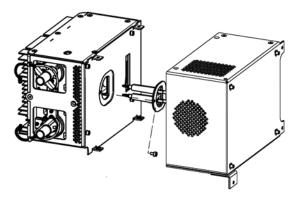


Figure 4-35

Disassemble Optics Module

1. Remove one 2 mm screw and remove fiber detector cable from output port. Repeat for second port.

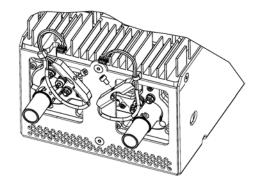


Figure 4-36

2. Remove two 3 mm screws securing filter brackets. Remove brackets.

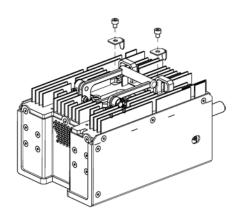


Figure 4-37



3. Remove both filter carriers.

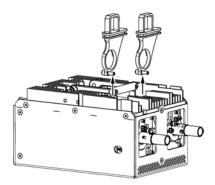


Figure 4-38

4. Remove the nine 2 mm screws securing rear panel. Remove rear panel.

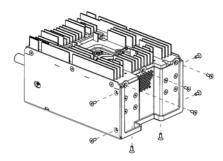


Figure 4-39

5. Remove eight 2 mm screws securing base cover to chassis. Remove base cover.

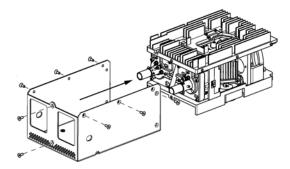


Figure 4-40

6. Remove five 2 mm screws securing top cover/heat sink. Remove heat sink.

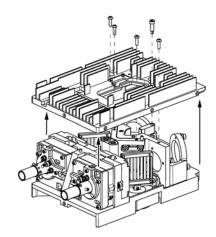


Figure 4-41

7. Remove three 2 mm screws securing HV receptacle to chassis. Remove HV receptacle.

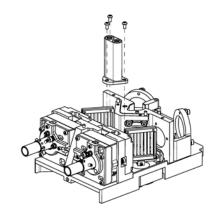


Figure 4-42

8. Loosen 1.5 mm setscrew securing attenuator to stepper motor shaft. Ensure that gap in attenuator vane clears opto-sensor, and remove attenuator.

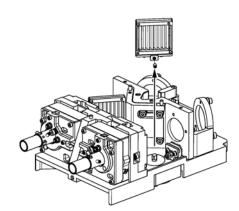


Figure 4-43



9. Remove two 3 mm screws securing stepper motor to underside of chassis. Remove stepper motor.

Repeat steps 8 and 9 as required for other attenuator/motor.

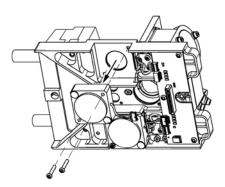


Figure 4-44

10.Disconnect thermistor cable from Interface PCB at J6. Unscrew thermistor from chassis and remove.

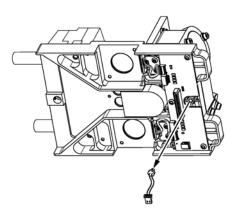


Figure 4-45

11. From under chassis, disconnect attenuator sensor cables from front of Interface PCB. From top, remove 2 mm screw from thermal switch and carefully bend leads up to allow removal of Interface PCB.

Remove three 2 mm screws securing Interface PCB to bottom of chassis. Remove Interface PCB. ••••

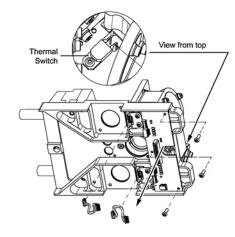


Figure 4-46



FAULTS, ERRORS, ADVISORIES, AND INFORMATION MESSAGES

System discrepancies are classified as Faults, Errors, Advisories, and Information, in order of severity.

The display of Faults has priority over Errors, and Errors have priority over Advisories, which have priority over Information messages. When more than one discrepancy exists within any one classification, the first discrepancy is displayed.

Faults

Discrepancies which require system shutdown are classified as Faults. When a fault condition is detected, the following actions are performed:

- All functions are placed in a safe state.
- The fault tone is activated.
- The fault message is displayed with a red background.
- All requests for functions are ignored, including button closures.

Errors

Discrepancies that require partial system shutdown, and can't be reversed until the next power cycle, are classified as Errors. When an Error condition is detected, the following actions are performed:

- Affected functions are placed in a safe state.
- The error tone is activated.
- The error message is displayed with a yellow background.
- Requests for affected functions, including button closures, are ignored until the error condition no longer exists or the operator acknowledges the error by pressing the dedicated button.

Advisories

When an Advisory condition exists, the operator is informed of a condition that requires corrective action. When an Advisory condition is detected, the following actions are performed:

- The advisory tone is activated.
- The advisory message is displayed with a green background.

Advisory messages are displayed until the condition no longer exists, the condition no longer applies to the current operating mode, or a dedicated button has been pressed to acknowledge the advisory. Advisory messages that only present a single user response button may be configured to automatically fade away. A fading advisory message is displayed for 20 seconds, after which, in the absence of a user response, it fades away.

Information

When an Information condition exists, the operator is informed of the useful information. When an Information condition is detected, the following action is performed:

• The information message is displayed with a blue background.

Information messages are displayed until the condition no longer exists, the condition no longer applies to the current operating mode, or a dedicated button is pressed to acknowledge the message. Information messages that only present a single user response button may be configured to automatically fade away. A fading information message is displayed for 20 seconds after which, in the absence of a user response, it fades away.

System Response to Discrepancies

Discrepancies in the following table are identified by a unique 4-digit decimal error code. The first digit of the error code encodes the submodule. The remaining three digits encode the discrepancy. Refer to the table below for each submodule's discrepancy code number range.

| Submodule | Discrepancy | Number Range |
|-----------------------|--------------|--------------|
| | Start Offset | End Offset |
| Reserved | 0 | 999 |
| Host | 1000 | 1999 |
| Supervisor | 2000 | 2999 |
| Fluidics | 3000 | 3999 |
| US/Diathermy | 4000 | 4999 |
| Table Top Illuminator | 5000 | 5999 |
| Pnuematics | 6000 | 6999 |
| Auxiliary Illuminator | 7000 | 7999 |
| Laser | 8000 | 8999 |

Faults, Errors, Advisories, and Information messages produce an appropriate popup on the display panel, and the system takes specific actions as specified in the following discrepancy tables.



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|------------------------------------|---|------------|----------------|--|---|
| 1001 | Fault | Fault - 1001 Call Field Service | The OSE Gateway exited unexpectedly. | 1017 | Fault | Fault - 1017 Call Field Service | A failure has occurred during the playback of an audio file. |
| 1002 | Fault | Fault - 1002 Call Field Service | The OSE Gateway has reported that the Supervisor process has gone down. | 1103 | Error | Voice Activation not available. | The user tried activate voice activation, but the voice activation process could not be found. |
| 1003 | Fault | Fault - 1003 Call Field Service | Something has failed in the communication between the Host and the Supervisor. | 1107 | Error | Unable to load one or more language packs. | An error occurred while attempting to load a non-English language. |
| 1004 | Fault | Fault - 1004 Call Field Service | The Main Application exited un- expectedly. | 1108 | Error | Incompatible version numbers within the Fluidics submodule. Fluidics functions will be dis- | The Fluidics module was shut down due to an incompatible version. The log file shows ex- |
| 1005 | Fault | Fault - 1005 Call Field Service | The Host Controller checksum validation failed to pass all files under its control. | 4400 | _ | abled. | actly what version information was incompatible. |
| 1006 | Fault | Fault - 1006 Call Field Service | The Host has failed to connect to the Supervisor process. | 1109 | Error | Incompatible version numbers within the Pneumatics submodule. Pneumatics functions will be disabled. | The Pneumatics module was shut down due to an incompatible version. The log file shows exactly what version information |
| 1008 | Fault | Fault - 1008 Call Field Service | The Host Controller failed to launch an executable image during startup. | 1110 | Error | Incompatible version numbers | was incompatible. The Ultrasound module was |
| 1009 | Fault | Fault - 1009 Call Field Service | The Host Controller could not communicate with the Power Module over the serial link. | | | within the Ultrasound submod- ule. Ultrasound and Diathermy functions will be disabled. | shut down due to an incompatible version. The log file shows exactly what version information was incompatible. |
| 1010 | Fault | Fault - 1010 Call Field Service | Component or Submodule reported an incorrect software, hardware, firmware or other. | 1111 | Error | Incompatible version numbers within the Auxiliary Illuminator submodule. Auxiliary Illuminator functions will be disabled. | ule was shut down due to an |
| 1011 | Fault | Fault - 1011 Call Field Service | Host Controller communications was lost as the result of a .NET IPC failure. | 1112 | Error | Incompatible version numbers | information was incompatible. The Laser module was shut |
| 1012 | Fault | Fault - 1012 Call Field Service | The Host has not received any heartbeats from the Supervisor within the required timeframe. | | | within the Laser submodule. Laser functions will be disabled. | down due to an incompatible version. The log file shows exactly what version information was incompatible. |
| 1013 | Fault | Fault - 1013 Call Field Service | The Host has detected that the User Interface thread has not responded within the required timeframe (i.e. the UI is considered locked up). | 1200 | Advisory | Function is not allowed when the fluidics subsystem is not functional. | The user tried to invoke a command which is only allowed when the fluidics subsystem is functional. |
| 1014 | Fault | Fault - 1014 Call Field Service | The system has detected a software error. | 1202 | Advisory | Function is not allowed when the Laser is in Ready Mode. | The user tried to invoke a command which is not allowed when the laser is in Ready Mode or Firing. |
| 1015 | Fault | Fault - 1015 Call Field Service | The Host has received a message from the Supervisor that it doesn't recognize (this is a specific type of software error). | 1203 | Advisory | | The user tried to invoke a command which is only allowed when the treadle is up and no buttons pressed. |
| 1016 | Fault | Fault - 1016 Call Field Service | The Host application's display fonts can not be loaded. | 1204 | Advisory | Flow mode is not available until the probe or handpiece has been primed. | Flow mode is unavailable because a probe or handpiece hasn't been primed. |
| Table 4-3 | Faults, Errors | , Advisories, and Inform | nation messages | | | | |



| Error Code Classification Displayed Text Discrepancy Error Code Classification Displayed Text | F is a VFC Step while Auto Gas Filling is in progress. The user attempts to eject the cassette while the treadle is down. The user attempts to eject the cassette while infusion is on. |
|--|---|
| able for 20 gauge probes / cause a non 20 gauge probe or handpieces. 1206 Advisory Please prime the Vit probe. The user presses the treadle in a Vit Step when the Vit Probe hasn't been primed. 1207 Advisory Please connect a Phaco handpiece. The user presses the treadle in a Vit Step when the Vit Probe hasn't been primed. The user presses the treadle in a Phaco Step when no Phaco lowed while infusion is on. | F is a VFC Step while Auto Gas Filling is in progress. The user attempts to eject the cassette while the treadle is down. The user attempts to eject the cassette while infusion is on. |
| a Vit Step when the Vit Probe hasn't been primed. 1207 Advisory Please connect a Phaco handpiece. 1208 Advisory Please connect a Phaco handpiece. 1209 Advisory Please connect a Phaco handpiece. 1200 Advisory Please connect a Phaco handpiece. 1201 Advisory Ejecting the cassette is not lowed while infusion is on. | itch cassette while the treadle is down. t al- The user attempts to eject the cassette while infusion is on. |
| piece. a Phaco Step when no Phaco lowed while infusion is on. | cassette while infusion is on. |
| | |
| 1208 Advisory Please tune the Phaco hand- piece. Ejecting the cassette is not a Phaco Step when the Phaco handpiece isn't tuned. | cassette while irrigation is on. |
| 1209 Advisory Please connect a Frag hand- The user presses the treadle in a Frag Step when no Frag handpiece is connected. 1223 Advisory Ejecting the cassette is not lowed while priming, tuning testing. | |
| 1210 Advisory Please tune the Frag hand-piece. 1210 Advisory Please tune the Frag hand-piece. 1224 Advisory Cleaning the cassette is not lowed while infusion, irrigation or FAX is on. 1224 Advisory Cleaning the cassette is not lowed while infusion, irrigation or FAX is on. | t al- ion, The user attempts to start Cas- sette Cleaning when either Infu- sion, Irrigation or FAX is on. |
| 1211 Advisory Function is not allowed when the Ultrasound submodule is not functional. 1225 Advisory Cleaning the cassette is allowed without a function and which is only allowed when the ultrasound subsystem is functional. | |
| 1212 Advisory Function is not allowed when the cassette is not ready. The user tried to invoke a command which is only allowed when the cassette is ready. 1226 Advisory Priming the cassette is not lowed without a functional cassette. | |
| 1213 Advisory Infusion must be on to use VFC Extract. Press [Ignore] to allow VFC sion is off. Extract without infusion for this case. The user presses the treadle in a VFC Extract Step when infusion infusion is off. 1227 Advisory An error occurred loading device settings. The syst will revert to default values. | tem device settings from the file |
| 1214 Advisory Please connect a VFC sy- The user presses the treadle in a VFC Step when no VFC Sy-ringe is connected. 1228 Advisory Command is not allowed when the connected in a VFC Step when no VFC Sy-ringe is connected. | hile The user tried to invoke a com- mand which is only allowed when infusion is not on. |
| 1215 Advisory Please connect Forceps. The user presses the treadle in a Forceps Step when no forceps are connected. | hile The user tried to invoke a com- mand which is only allowed when irrigation is not on. |
| 1216 Advisory Please connect Scissors. The user presses the treadle in a Scissors Step when no Scissors are connected. The user presses the treadle in a Scissors Step when no Scissors are connected. 1230 Advisory The selected step is not settle type. | |
| 1217 Advisory Please connect an AGF sy- ringe. The user presses the "Start" but- ton in the Auto Gas Filling dialog when no AGF syringe has been connected. 1231 Advisory The connected probe is supported with the curr cassette type. | not The user connects a probe (with rent RFID) that's not compatible with the current operating mode |
| 1218 Advisory Forceps not available during The user presses the treadle in AGF: please try again when AGF is complete. The user presses the treadle in a Forceps Step while Auto Gas Filling is in progress. | (e.g. an Ultra Vit probe when an Anterior cassette is connected or Ultra Vit Anterior probe when a Posterior cassette is con- nected). |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------------|--|--|------------|----------------|--|--|
| 1232 | Advisory Advisory | Please connect footswitch. The connected footswitch is | The Supervisor has reported that no footswitch is connected. The Supervisor has detected | 1245 | Advisory | Please connect handpiece. | The user attempts to perform an action, e.g. priming, that requires a handpiece but no handpiece is connected. |
| 1233 | Advisory | not supported. | the connection of an unknown footswitch. | | | | Note: This is only applicable to handpieces the system can de- |
| 1234 | Advisory | Flow limit is currently not available due to flow mode being unavailabe. | Vacuum mode flow limit depends on the availability of flow mode. If flow mode becomes unavailable then the flow limit function can not be performed by the fluidics submodule. | 1247 | Advisory | Connected handpiece is not supported with the current cassette type. | User connects a handpiece that's not compatible with the current Cassette type. (e.g., a Frag handpiece is connected when an Anterior Cassette is |
| 1235 | Advisory | IV Pole pressure mode is currently not available. | User attempts to select IV Pole as the infusion source but the IV Pole is not available (not configured, not working or Cassette is of Premium type) | 1248 | Advisory | Is the inserted cassette new? | inserted) The user has inserted a Cassette which the system can't determine whether it's new or the same Cassette that was previ- |
| 1236 | Advisory | Gravity pressure mode is currently not available. | User attempts to select Gravity as the infusion source when a Premium Cassette is inserted. | 1249 | Advisory | An error occurred parsing the log file. | ously ejected. An error occurred parsing one of more lines of the log file. |
| 1237 | Advisory | IOP Compensation is currently not available. | User attempts to turn IOP Compensation on when it's not available. | 1250 | Advisory | Multi-Cut is not available when proportional scissors | The user has selected scissors of type Proportional and |
| 1238 | | An error occurred saving the device settings. | User attempt to save device settings fails. | | | are selected. Press [Multi-Cut] to indicate that multi-cut scissors are currently connected. | attempts to select the Multi- Cut submode or attempt to use momentary cutting in Extrusion Mode. |
| 1239 | Advisory | Proportional reflux mode is currently not available. | User attempts to toggle into proportional reflux mode when the fluid level in the cassette chamber is out of range or the fluid level gets out of range while in | 1251 | Advisory | Command is not allowed while the cassette is being cleaned. | The user tried to turn Infusion, Irrigation or FAX on while the cassette is being cleaned. |
| 1240 | Advisory | Extraction flow mode is cur- | proportional reflux. User attempts to toggle into | 1252 | Advisory | The scanned barcode is not recognized. | The user has scanned an item that the system doesn't recognize. |
| | · | rently not available. | flow mode when the fluid level in the cassette chamber is out of range or the fluid level gets out of range while in flow mode. | 1255 | Advisory | Illuminator fiber is not connected. | User has attempted to turn on an illuminator with no illuminator fiber connected. |
| 1241 | Advisory | Infusion source is getting low: please check the bottle. | The infusion container fluid level is getting low. | 1256 | Advisory | Proportional reflux mode is not available when the footswitch treadle is de- | User attempts to enter Proportional Reflux mode when the treadle is down |
| 1242 | Advisory | Command is not allowed due to instrument not being available. | The user tried to invoke a command which is not allowed when no instrument is available for the command to work with. | 1257 | Advisory | pressed. The report's header or footer has too many rows to fit | The user has added too many |
| 1243 | Advisory | Infusion / Irrigation source is empty: please press [Change] and replace the bottle. | The infusion fluid container is empty but there's still fluid in the cassette chambers. | | | on the page. | being edited in an End Case report. As a result, the table will not be printed out in its entirety on the various pages compris- ing the report. |
| 1244 | Advisory | Command is not allowed while priming, tuning, or testing. | The user attempts to do something, e.g. change Steps, that's not allowed when tests are in progress. | | | | ing the report. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|--|---|-------------------|----------------|--|---|
| 1258 | Advisory | The report's current table has too many rows to fit on the page. | The user has added too many rows to the current table being edited in an End Case report. As a result, the table will not be printed out in its entirety on the various pages comprising the report. | 1268 | Advisory | The laser remote interlock is open. | Shown in any of the following situations: Laser Step entered and the Interlock is open Interlock opened in a Laser Step User tries to go to Ready Mode when the Interlock is |
| 1259 | Advisory | Command is not allowed while proportional diathermy is active. | The user attempts to enter proportional reflux while proportional diathermy is active. | 1269 | Advisory | Laser Dr. Filters are not connected to the console. | open Shown in any of the following situations: |
| 1260 | Advisory | Command is not allowed while proportional reflux is active. | The user attempts to enter proportional diathermy while proportional reflux is active. | | | Are all necessary Dr. Filters properly installed and connected? | Laser Step entered and the Dr. Filters haven't been veri- fied for the active port Endo Probe inserted to the |
| 1261 | Advisory | Cassette can't be ejected while being cleaned. | The user attempts to eject the cassette while it's being cleaned. | | | necieu? | active port while in a Laser Step • User tries to go to Ready Mode when Dr. Filters haven't |
| 1262 | Advisory | Invalid handpiece tip. | The system attempts to select a tip that's not valid for the specific handpiece. This will only happen if an incorrect tip is specified for a scanned pak, i.e. the user will never be able to select an invalid tip from the UI. | 1270 | Advisory | One Laser Dr. Filter is connected to the console. Are all necessary Dr. Filters properly installed and connected? | been verified for the active port. Same as above |
| 1263 | Advisory | Port can't be selected: there is no probe connected. | The user tries to make a laser port the active port but there's no probe connected to that port. | 1271 | Advisory | Two Laser Dr. Filters are connected to the console. Are all necessary Dr. Filters properly installed and con- | Same as above |
| 1264 | Advisory | Port can't be selected: the probe type for the port isn't valid. | The user tries to make a laser port the active port but the currently selected probe type for that port is invalid. | 1273 | Advisory | nected? Laser Dr. Filter 1 is disengaged | The user has disengaged the (connected) Dr. Filter 1 while in a Laser Step. |
| 1266 | Advisory | A laser probe is not connected to the active port. | Shown in any of the following situations: • Laser Step entered and no | 1275 | Advisory | Laser Dr. Filter 2 is disengaged | Same as 1273 but for Dr. Filter 2 |
| | | | probe connected to the active port Probe removed from active port | 1276 | Advisory | Command is not allowed when Laser is firing. | User has attempted to change one of the laser's settings while the laser is firing. |
| | | | User tries to go to Ready Mode when no probe is con- nected to the active port | 1277 | Advisory | Port can't be selected: it's not functional. | User has attempted to select a laser port that's not functional. |
| 1267 | | A valid laser probe is not selected for the active port. | Shown in any of the following situations: Laser Step entered and no valid probe type selected for the active port User tries to go to Ready Mode when no valid probe type is selected for the active port | 1278 | Advisory | Cannot go to Laser Ready Mode while the current screen is being displayed. | User has pressed the Ready button from the footswitch when a "conflicting screen" is active. |
| | | | | 1279 | Advisory | No laser footswitch is connected. | User enters a Laser Step when no laser footswitch is connected or the laser footswitch is disconnected in a Laser Step. |
| | 000575445 | | r | 1280 | Advisory | Unable to write to the report file. | A problem has occurred when trying to write to the specified Report file. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|--|---|------------|----------------|--|--|
| 1281 | Advisory | Unable to read from the report file. | trying to read from the specified Report file. | 1304 | Advisory | The Laser is currently unable to deliver the maximum power level of 2 Watts. The maximum Laser power (Watts) currently | Is generated when the power available from the laser drops below the maximum level (2 Watts). |
| 1285 | Advisory | The report file and its associated CRC value do not match. | The Report file and its associated CRC value do not match. | 1305 | Advisory | available is: An error occurred loading a | A database attempt to load a |
| 1288 | 1288 Advisory | Can't eject the cassette while reflux is active. | The user attempts to eject the cassette while reflux (of any type) is active. | 1000 | Advisory | surgeon. The system will revert to default values. | surgeon from the file system has failed. Reverting to defaults. |
| | | | For proportional reflux, this advisory is displayed when the user attempts cassette ejection while proportional reflux mode | 1306 | Advisory | An error occurred setting the printer port. The system will revert to the previous value. | Attempt to set the printer IP address failed. |
| | | | is active with the treadle not depressed. Cassette ejection while the treadle is depressed will generate advisory 1220. | 1307 | Advisory | An error occurred loading a procedure. The system will revert to default values. | A database attempt to load a procedure from the file system has failed. Reverting to defaults. |
| 1289 | Advisory | Extraction flow mode is not available when FAX is turned on. | FAX was turned on while in Flow Mode or a Posterior Step with Flow Mode preference was selected when FAX was on. The system then changed to Vacu- | 1308 | Advisory | An error occurred loading the system settings. The system will revert to default values. | A database attempt to load the system settings from the file system has failed. Reverting to defaults. |
| | | | um Mode. | 1309 | Advisory | An error occurred saving a surgeon's settings. Changes | A database attempt to save a surgeon to the file system has |
| 1290 | | The surgical function is currently unavailable. | The user has requested surgi- cal functionality that is currently unavailable. This is a default ad- | | | will be reverted at the start of the next case. | failed. |
| | | | visory that is only displayed for cases in which a more meaningful explanation is not available. | 1310 | Advisory | An error occurred saving a procedure. Changes will be reverted at the start of the next case. | A database attempt to save a procedure from the file system has failed. Reverting to defaults. |
| 1296 | Advisory | The barcode reader failed to initialize. | The bar code reader failed to initialize during startup. | 1311 | Advisory | An error occurred saving the system settings. The system | A database attempt to save the system settings from the file |
| 1297 | Advisory | The system is currently low on free disk space. Please backup or remove non-critical files. | During startup, free space was detected at less than 15%. | | | will use default values. | system has failed. Reverting to defaults. |
| 1298 | Advisory | A printer is not installed. | The user tried to print but no printer is installed. | 1312 | Advisory | An error has occurred initializ- ing Video Overlay. Video Over- lay functions will be disabled. | An error happened during VideoOverlay initialization. |
| 1299 | Advisory | The printer is out of paper. | The user sent a print job but the printer is out of, or ran out of paper. | 1313 | Advisory | An error has occurred in the Video Overlay component. Video Overlay functions will be disabled. | An error happened during VideoOverlay processing. |
| 1300 | Advisory | The printer is off line. | The user requested a print job, but the printer is off line. | 1314 | Advisory | There was an error saving surgeon data. | There was an error saving surgeon data. |
| 1302 | Advisory | An unknown error occurred while printing. | Generated by any printer error other the errors above. | 1317 | Advisory | There was an error renaming the surgeon. | There was an error renaming the surgeon. |
| 1303 | 1303 Advisory | The Illuminators are currently turned off from the footswitch and cannot be turned on or off at this time. | turned off from the footswitch on or off an endo illuminator and cannot be turned on or off when the footswitch Momentary | 1318 | Advisory | There was an error renaming the procedure. | There was an error renaming the procedure. |
| | | | Endo Illuminators Off function is active. | 1319 | Advisory | There was an error renaming the case data. | There was an error renaming the case data. |
| | | | | | | | |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|--|--|------------|----------------|--|---|
| 1320 | Advisory | There was an error deleting the surgeon. | There was an error deleting the surgeon. | 1341 | Advisory | Further increasing the output level in air can damage fiber tips. Would you like to con- | The user has exceeded Threshold 1 (see SRS-5687.1) illuminator value by either turning |
| 1321 | Advisory | There was an error deleting the procedure. | There was an error deleting the procedure. | | | tinue? | on the illuminator, changing the setpoint while the illuminator is on, or changing Procedures |
| 1322 | Advisory | There was an error deleting the case data. | There was an error deleting the case data. | 1342 | Advisory | Further increasing the output | while the illuminator is on. The user has exceeded Thresh- |
| 1323 | Advisory | There was an error loading the surgeon. | There was an error loading the surgeon. | | | level will reduce exposure time by 35%. Would you like to con- tinue? | old 2 (see SRS-5687.3) illuminator value by either turning on the illuminator, changing the |
| 1324 | Advisory | There was an error loading the procedure. | There was an error loading the procedure. | | | | setpoint, or changing Procedures. |
| 1325 | Advisory | There was an error loading the case data. | There was an error loading the case data. | 1343 | Advisory | Further increasing the output level in air can damage fiber tips. Also, further increasing | The user has exceeded both Threshold 1 and Threshold 2 (see SRS-5687.1 and SRS- |
| 1326 | Advisory | Unable to load the case report template. | There was an error loading the Case Report Template. | | | the output level will reduce exposure time by 35%. Would you like to continue? | 5687.3) illuminator value by either turning on the illuminator, changing the setpoint while the |
| 1329 | Advisory | Unable to save the technician's log. | There was an error saving the Technician's Log. | | | , | illuminator is on, or changing Procedures while the illumina- tor is on. |
| 1330 | Advisory | Unable to load the video table. | There was an error loading the Video Table. | 1344 | Advisory | Only two illuminators can be turned on simultaneously. | User attempts to turn on an illuminator port when two ports are |
| 1331 | Advisory | Unable to play the video. | There was an error loading and\ or playing the Video file. | 1345 | Advisory | AGF not allowed while For- | already on. This is not allowed. User attempts to start Auto Gas |
| 1332 | Advisory | Unable to load Help. | There was an error opening the Help pdf file. | 1343 | Advisory | ceps or VFC is in use. | Filling when either Forceps or VFC is in use (i.e. selected and treadle down). |
| 1333 | Advisory | Unable to save the case info. | There was an error saving the Case Info file. | 1346 | Advisory | An error occurred trying to access the wireless network. | An error occurs when the user attempts to access the wireless |
| 1334 | Advisory | Unable to update the log file. | There was an error writing to the Log File. | 1349 | Advisory | A RAID hard drive has failed or | network. One Disk in a redundant RAID |
| 1335 | Advisory | Unable to read the log file. | There was an error reading from the Log File. | | ravicory | is missing | volume is missing or has failed but the volume is still function- al. |
| 1336 | Advisory | Unable to write the incident file. | There was an error writing to the Incident File. | 1350 | Advisory | The probe in the current laser port is not supported. | The type of probe in the current port is not supported by NGVS |
| 1337 | Advisory | Unable to read the incident file. | There was an error reading from the Incident File. | | | | but might be supported by NGL (slit lamp for example). |
| 1338 | Advisory | Unable to write the system metrics file. | There was an error writing to the System Metrics File. | 1355 | Advisory | Command is not allowed when the Pneumatics submodule is not functional. | The user tried to invoke a command which is only allowed when the Pneumatics subsys- |
| 1339 | Advisory | Unable to read the system metrics file. | There was an error reading from the System Metrics File. | 1356 | Advisory | Command is not allowed when | tem is functional. The user tried to invoke a com- |
| 1340 | Advisory | Unable to write to the removable drive. | There was an error while attempting to write to the removable drive. | 1000 | Advisory | an Anterior Only Cassette is being used. | mand which is not allowed with an Anterior Only Cassette. |
| | | | | 1357 | Advisory | Cannot switch to Infusion: the cassette has not been primed. | The user tried to switch to Infusion when the cassette was not primed. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|--|--|------------|----------------|--|---|
| 1358 | Advisory | Current probe type is unrecognized. Please select a valid probe type. | User has attempted to turn on an illuminator when the probe type is "unrecognized". | 1752 | Information | Infusion pressure will drop to zero during calibration. Continue? | User has pressed the "Calibrate" button on the advisory popup brought up when there's been an IV Pole error. Since I/V Pole calibration will change the |
| 1359 | Advisory | Power module communication error. When powering down the system, you will have to press the "Options/Shutdown" | Host controller failed to communicate with power module. | | | | current Infusion pressure, the user is warned before calibration is started. |
| 1361 | Advisory | button on the screen. Command is not allowed when | The user tried to invoke a com- | 1753 | Information | Power recovery is in progress. Please wait until surgical functions become available. | AC power has been restored and the recovery process has started. |
| | | Infusion backup pressure is active. | mand which is only allowed when Infusion backup pressure is not active. | 2100 | Fault | Fault - 2100 Call Field Service | A two second heart beat reply from the host was missed. |
| 1362 | Advisory | Command is not allowed when the probe type has been identified by RFID. | The user tried to change the type of a laser probe that has been identified by RFID. | 2200 | Error | Communications failure with the Fluidics submodule. Fluidics functions will be disabled. | The supervisor cannot establish communicate with the Fluidics submodule. |
| 1363 | Advisory | Command is not allowed when the probe type has been pre- viously identified by the user. Disconnect and then recon- | The user tried to change the type of a laser probe that has been identified by a user selection. Only one selection is al- | 2201 | Error | Communications failure with the Fluidics submodule. Fluidics functions will be disabled. | The supervisor lost communicate with the Fluidics submodule |
| | | nect the probe to change its type. | lowed after connection. | 2202 | Advisory | Unable to perform this function without a primed cassette. | This advisory is produced when extraction is attempted without a primed cassette. |
| 1364 | Advisory | IOP Compensation is not allowed without a premium cassette inserted. Please insert a premium cassette and retry. | The user tried to turn on IOP compensation when a premium cassette is not inserted. | 2203 | Advisory | Unable to aspirate. Please turn on infusion. | This advisory is produced when extraction is attempted without infusion on. |
| 1365 | Advisory | IOP Compensation is not allowed with an uncalibrated cassette. Please calibrate cassette and retry. | The user tried to turn on IOP compensation with a cassette that has not been calibrated. | 2204 | Advisory | Unable to aspirate while infusion/irrigation is unavailable. | This advisory is produced when extraction is attempted without infusion being functional. |
| 1366 | Advisory | Command is not allowed when FAX is on and the cassette has not been primed. | The user tried to perform a Test Instrument command when FAX is on and the cassette is not primed. | 2205 | Advisory | Please wait: draining cassette. | This advisory is produced when extraction is attempted when the extraction chamber is in a overflow condition. |
| 1367 | Advisory | FAX is not allowed when the cassette is being primed. | The user tried to turn on FAX when the cassette is being primed. | 2206 | Advisory | Unable to turn on infusion without a primed cassette. | This advisory is produced when infusion is attempted with out a primed cassette. |
| 1369 | Advisory | Setting values is not allowed when the cassette is in the chamber overflow condition. | The cassette chamber is in an overflow condition and pressure cannot be controlled. | 2207 | Advisory | Unable to turn on infusion without a calibrated IV pole. | This advisory is produced when infusion is attempted with out a calibrated IV Pole. |
| 1370 | Advisory | Test instrument is not allowed in this mode. | User has attempted to perform a test instrument command in Setup or End Case. | 2208 | Advisory | Unable to turn on infusion without sufficient source pressure. | This advisory is produced when infusion is attempted with out source air pressure |
| 1751 | Information | The remote control battery is low. | User has pressed on a remote control button and the remote's battery is running out of power. | 2209 | Advisory | Unable to turn on irrigation without a primed cassette. | This advisory is produced when irrigation is attempted with out a primed cassette. |
| | | | battery is running out or power. | 2210 | Advisory | Unable to turn on infusion without a calibrated IV pole. | This advisory is produced when irrigation is attempted with out a calibrated IV Pole. |
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| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|---|---|------------|----------------|---|--|
| 2211 | Advisory | Unable to turn on irrigation without sufficient source pressure. | This advisory is produced when irrigation is attempted with out suitable source pressure. | 2302 | Error | US setpoint timeout. US and Diathermy functions will be disabled. | This error is produced when the US is active and the US proxy fails to get a footswitch update within 20 msec. |
| 2212 | Advisory | Irrigation unavailable: out of fluid. Please change the bottle. | This advisory is produced when irrigation is attempted with out sufficient irrigation fluid available | 2350 | Error | Communications failure with the Laser submodule. Laser functions will be disabled. | The supervisor cannot communicate with the Laser submodule. |
| 2213 | Advisory | FAX unavailable. Please insert a cassette. | This advisory is produced when F/AX is attempted with out a cassette inserted. | 2351 | Advisory | Communications failure with the Laser submodule. Laser functions will be disabled. | The supervisor lost communication with the Laser submodule. |
| 2214 | Error | Extraction setpoint timeout. In- fusion/Irrigation and Extraction functions will be disabled. | This error is produced when the extraction is active and the extraction proxy fails to get a footswitch update within 20 | 2400 | Advisory | Please insert the Table Top Illuminator drawer. | Supervisor detected a non -zero setpoint with the Table Top Illuminator drawer out. |
| 2215 | Advisory | Micro reflux is currently not available. | msec This error is produced when the the user attempt to activate mi- | 2401 | Advisory | The lamp in the Table Top Illuminator needs to be replaced. Please contact Field Service. | Supervisor detected a non–zero setpoint with the Table Top Illuminator Lamp bad. |
| 2250 | Fran | | cro reflux and the fluid level is out of range. | 2500 | Advisory | Communications failure with the Power Control submodule. Please contact Field Service. | Supervisor detected a serial I/O error when trying to talk to the Power Module. |
| 2250 | Error | Communications failure with the Pneumatics submodule. Pneumatics functions will be disabled. | The supervisor cannot communicate with the Pneumatics submodule. | 2550 | Error | Footswitch error. Footswitch treadle functions will be disabled. | The footswitch has an error. |
| 2251 | Error | Communications failure with the Pneumatics submodule. Pneumatics functions will be disabled. | This error is produced when the Supervisor losses communication with the pneumatics module. | 2600 | Advisory | IV Pole over-current error. IV Pole functions will be disabled. | IV Pole motor is drawing too much current. |
| 2252 | Advisory | Unable to turn on cutting without sufficient source pressure. | This advisory is produced when cutter or utility operation is requested with out sufficient source pressure. | 2700 | Error | Communications failure with the Auxiliary Illuminator sub- module. Auxiliary Illuminator functions will be disabled. | The supervisor cannot communicate with the Auxiliary Illuminator submodule. |
| 2253 | Advisory | Unable to turn on cutting with excessive source pressure. | This advisory is produced when cutter or utility operation is requested with source pressure that is too high. | 2701 | Advisory | Communications failure with the Auxiliary Illuminator sub- module. Auxiliary Illuminator functions will be disabled. | The supervisor lost communication with the Auxiliary Illuminator submodule. |
| 2254 | Error | Pneumatics setpoint timeout. Pneumatics functions will be disabled. | This error is produced when the pneumatics is active and the pneumatics proxy fails to get | 2702 | Advisory | The lamp in the Auxiliary Illuminator needs to be replaced. Please contact Field Service. | - Supervisor detected a non-zero setpoint with the Auxiliary Illuminator Lamp bad. |
| | | disabled. | a footswitch update within 20 msec. | 2750 | Fault | Fault - 2750 Call Field Service | The Supervisor could not assert reset control over all submodules. A module that was sup- |
| 2300 | Error | Communications failure with the Ultrasound submodule. Ultrasound functions will be | The supervisor cannot communicate with the Ultrasound submodule. | | | | posed to be reset responded with its module information. |
| 2301 | Error | disabled. Communications failure with the Ultrasound submodule. Ultrasound functions will be disabled. | The supervisor lost communication with the Ultrasound sub- | 2751 | Fault | Fault - 2751 Call Field Service | The Supervisor got duplicate slot ID for the submodules. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|--------------|----------------------|--|---|------------|----------------|--|---|
| 3100 | Advisory | Could not calibrate the fluid level sensors. Please eject and reinsert, or replace the cassette. | Level Sensor calibration failed. The calibration done status bit was not set by the FPGA within the specified timeout limit or the calculated required max/min pixel gain was outside the valid | 3306 | Advisory | Priming of the aspiration handpiece was unsuccessful. Please attempt to re-prime the handpiece. | Handpiece prime was unsuccessful. The required volume of fluid was not transferred through the aspiration tubing set within the specified timeout period. |
| 3200 | Error | Cassette latch error. Please remove and reinsert the cassette. | Cassette latch hardware feedback signals indicate a hardware problem. | 3307 | Error | Aspiration level sensor prob- lem detected. Infusion/irriga- tion and extraction functions will be disabled. | The level sensor status signals indicate a level sensor hardware problem. |
| 3201 | Advisory | Invalid cassette ID detected. Please eject and insert a valid cassette. | An invalid cassette id was read by the cassette id sensors. | 3308 | Advisory | Flow check failure: measured flow restriction is too high. Extraction and Ultrasound functions in Phaco/Frag will be disabled. | The handpiece failed the flow-check. Too high vacuum level was required to achieve the reference flow level. |
| 3202 | Advisory | Cassette test failed. Please eject and reinsert, or replace cassette. | Cassette pressure and/or vaccum tests failed. | 3309 | Advisory | Flow check failure: aspiration chamber could not be filled with fluid. Extraction and Ultra- | The handpiece failed the flow-check. Too high vacuum level was required to achieve the ref- |
| 3203 | Advisory | The cassette was not properly latched into position. Please remove and reinsert the cassette. | The cassette latch optical position sensor indicates that the latch did not reach its locked position. | 3325 | Advisory | sound functions in Phaco/Frag will be disabled. Drain bag is almost full. Please replace bag and press [Done]. | ~50 cc remaining volume in |
| 3204 | Error | Cassette ID sensor error. Infusion/irrigation and extraction functions will be disabled. | Cassette ID sensor test failed. The sensor output voltage is not within the expected range. | 3326 | Advisory | Drain bag is full. Please replace bag and press [Done]. | drain bag. ~0 cc remaining volume in drain bag. |
| 3205 | Advisory | The Fluidics module fan is not working. | The Fluidics module fan tachometer indicates that the Fluidics module fan is not operating. | 3327 | Advisory | Drain bag is critically full. Please replace bag and press [Done]. | Drain bag filled > 50 cc above capacity. |
| 3300 3302 | Advisory Advisory | Draining cassette. Please wait. | The cassette aspiration chamber is full of fluid. Not enough or too much fluid | 3329 | Error | Drain pump problem detected. Infusion/irrigation and extraction functions will be disabled. | The commanded pump rate does not correspond to the actual pump rate measured by the optical encoder. |
| | | | in the aspiration chamber to allow aspiration flow mode and reflux. NOTE: This advisory is never | 3330 | Advisory | The drain pump fan is not working. | · |
| | | | explicitly displayed. Instead advisory 1239 or 1240 might be displayed if appropriate. See 11239 and 11240 for details. | 3331 | Advisory | Could not drain the aspiration chamber. Please remove and insert a new cassette. | The aspiration chamber could not be drained within the specified timeout period. |
| 3304 | Advisory | Leak test failure. Please confirm the irrigation tubing; aspiration tubing , and the test chamber are properly connected to the handpiece. | A leak in the aspiration or irrigation tubing was detected during flow check of a handpiece. | 3350 | Error | Extraction pressure transducer offset error. Infusion/irrigation and extraction functions will be disabled. | Extraction pressure transducer 0 offset out of range. |
| 3305 | Advisory | Priming of the aspiration probe was unsuccessful. Please attempt to re-prime the probe. | Probe prime was unsuccessful. The required volume of fluid was not transferred through the aspiration tubing set within the | 3351 | Error | Extraction pressure transducer discrepancy error. Infusion/irrigation and extraction functions will be disabled. | A discrepancy between the primary and redundant extraction pressure transducers was detected. |
| | | | specified timeout period. | 3352 | Error | Extraction isolation valve error. Infusion/irrigation and extraction functions will be disabled. | Extraction isolation valve hardware error. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|---|--|------------|----------------|--|--|
| 3353 | Error | Reflux valve error. Infusion/irrigation and extraction functions will be disabled. | Extraction reflux valve hardware error. | 3401 | Error | Infusion source container isolation valve error. Infusion/irrigation and extraction functions will be disabled. | Infusion source container isolation valve error. |
| 3354 | Error | Extraction output valve (S1) error. Infusion/irrigation and extraction functions will be disabled. | Extraction output pincher valve (S1) error | 3402 | Error | Infusion source container transducer discrepancy error. Infusion/irrigation and extraction functions will be disabled. | A dispcrepancy between the source container and LPAS pressure transducers was detected. |
| 3355 | Error | Extraction output valve (S11) error. Infusion/irrigation and extraction functions will be disabled. | Extraction output port 1 pincher valve error. | 3403 | Error | Infusion source container pressure too high. Infusion/irrigation and extraction functions will be disabled. | Infusion source container pressure too high. |
| 3356 | Error | Extraction output valve (S22) error. Infusion/irrigation and extraction functions will be disabled. | Extraction output port 2 pincher valve error. | 3420 | Error | Infusion pressure transducer offset error. Infusion/irrigation and extraction functions will be disabled. | Infusion pressure transducer 0 offset out of range |
| 3357 | Error | Extraction cross-connection valve (SC) error. Infusion/irrigation and extraction functions will be disabled. | Extraction "normally open" cross-connection valve error. | 3421 | Error | Infusion pressure transducer discrepancy error. Infusion/irrigation and extraction functions will be disabled. | A dispcrepancy between the primary and redundant infusion pressure transducers was detected. |
| 3358 | Error | Extraction cross-connection valve (SC2) error. Infusion/irrigation and extraction functions will be disabled. | Extraction "normally closed" cross-connection valve error. | 3422 | Error | Infusion isolation valve error. Infusion/irrigation and extraction functions will be disabled. | Infusion isolation valve error. |
| 3359 | Advisory | Suction pressure surges detected. Vacuum will be disabled. Please release the footswitch treadle to reset. | Extraction pressure oscillations detected. | 3423 | Error | Infusion FAX valve error. Infusion/irrigation and extraction functions will be disabled. | Infusion FAX valve error. |
| 3360 | Advisory | Suction flow surges detected. Flow will be disabled. Please release the footswitch treadle | Extraction flow oscillations detected. | 3424 | Error | Infusion input valve error. Infusion/irrigation and extraction functions will be disabled. | Infusion chamber input pincher valve error. |
| 3361 | Advisory | to reset. Suction pressure is too high. Vacuum will be disabled. | Extraction pressure overshoot detected. | 3425 | Error | Infusion output valve error. In- fusion/irrigation and extraction functions will be disabled. | Infusion chamber output pincher valve error. |
| | | Please release the footswitch treadle to reset. | | 3426 | Error | Irrigation output valve error. In- fusion/irrigation and extraction functions will be disabled. | Irrigation output pincher valve error. |
| 3362 | Advisory | Aspiration flow too high. Flow will be disabled. Please release the footswitch treadle to reset. | Extraction flow overshoot detected. | 3427 | Error | Infusion pressure surges detected. Infusion/irrigation and extraction functions will be disabled. | Infusion pressure oscillations detected. |
| 3363 | Error | Extraction pressure transducer reference voltage out of range. Infusion/irrigation and extraction functions will be disabled. | Extraction transducer reference voltage error. | 3428 | Error | Infusion pressure too high. In- fusion/irrigation and extraction functions will be disabled. | Infusion high pressure detected. |
| 3400 | Error | Infusion source container pressure transducer offset error. Infusion/irrigation and extraction functions will be disabled. | Infusion source container pressure transducer 0 offset out of range. | 3429 | Advisory | Low infusion pressure detected. Please check infusion connections. Select 30 mmHg backup pressure, or ignore low pressure condition. | Infusion pressure too low. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|--|--|------------|----------------|---|---|
| 3431 | Advisory | Low irrigation pressure detected. Please check irrigation connections. | Irrigation pressure too low. | 3466 | Advisory | Infusion flow sensor accuracy error. IOP Compensation functions will be disabled. | Infusion flow sensor accuracy error. Flow sensor and chamber fluid volume measurements are out of range of each other. |
| 3433 | Error | Infusion chamber isolation valve error. Infusion/irrigation and extraction functions will be disabled. | Infusion chamber isolation valve detected to be stuck closed during power up diagnostics. | 3467 | Advisory | Infusion flow sensor signal am- | Detected during flow sensor calibration. Infusion flow sensor signal am- |
| 3434 | Advisory | Infusion chamber overflow error. Control of infusion pressure has possibly been lost. The current pressure, in | Infusion chamber overflow error. The fluid level in the infusion chamber reached above the overflow level. | 3407 | Advisory | plitude is low IOP Compensa- tion functions will be disabled. Please eject and reinsert the cassette. | plitude error. Detected during flow sensor calibration |
| | | mmHg, could be as high as: | the overnow level. | 3469 | Advisory | Tubing calibration offset error. IOP Compensation functions | Infusion tubing calibration 0 off- set advisory. The infusion can- |
| 3436 | Error | FAX valve error. Infusion/irrigation and extraction functions will be disabled. | F/AX valve detected to be stuck closed during power up diagnostics. | | | will be disabled. Please position the infusion cannula at the height of the center of the cassette and re-prime. | nula was not positioned within the correct vertical range of the cassette during calibration. |
| 3437 | Error | linfusion level sensor error. In- fusion/irrigation and extraction functions will be disabled. | The level sensor status signals indicate a level sensor hardware problem. | 3470 | Advisory | Calibration verification error: calculated pressures using the acquired calibration profile are | Infusion tubing calibration check point advisory. The pressure drop calculated using the |
| 3438 | Advisory | No more infusion fluid available. Press [Change] to change the infusion bottle. | The infusion chamber in the cassette is empty. | | | not within the expected range for the selected infusion can- nula. IOP Compensation func- tions will be disabled. Please | e acquired calibration profile was not within the expected range. |
| 3440 | Advisory | No more irrigation fluid available. Press [Change] to change the infusion/irrigation bottle. | The irrigation chamber in the cassette is empty. | 3471 | Advisory | re-prime. Noisy calibration flow readings. IOP Compensation func- | Infusion tubing calibration standard deviation advisory. The |
| 3442 | Advisory | Irrigation chamber overflow detected. Control of irrigation pressure has possibly been lost. The current pressure, in mmHq, could be as high as: | Irrigation chamber overflow error. The fluid level in the irrigation chamber reached above the overflow level. | | | tions will be disabled. Please re-prime. | standard deviation between the acquired flow measurements and the calculated calibration profile was larger than the specified max limit. |
| 3460 | Error | Infusion backup valve error. Infusion/irrigation, extraction, and Ultrasound functions will | Infusion backup valve error. | 3472 | Advisory | Infusion chamber leak detected. Please eject and replace the cassette. | A leak in the infusion chambers was detected during priming. |
| | | be disabled. | | 3473 | Error | Infusion pressure transducer reference voltage out of range. | Infusion transducer reference voltage error. |
| 3461 | Error | Infusion LPAS pump error detected. Infusion/irrigation, extraction, and Ultrasound func- | The infusion LPAS pump ta- chometer indicate that the LPAS pump is not operating correctly. | | | Infusion/irrigation and extraction functions will be disabled. | · · |
| 3462 | Advisory | tions will be disabled. Infusion flow sensor commu- | Infusion flow sensor communi- | 3474 | Error | Infusion NIFS valve error detected. Infusion/irrigation and extraction functions will be | Infusion NIFS valve error. |
| | | nication error. IOP Compensation functions will be disabled. | cation error. | | | disabled. | |
| 3464 | Advisory | Infusion flow data invalid: IOP | Infusion flow sensor readings | 3475 | Advisory | Infusion prime failed. | Infusion prime failed. |
| | | Compensation functions will be disabled. Check infusion tubing for air bubbles. | are not valid. | 3476 | Advisory | The infusion chambers did not fill with fluid. Please check the infusion bottle and connections or press [Change] to replace the infusion bottle. | Infusion chamber did not fill within the specified timeout period. Source container is out of fluid. |
| | | | | | | | |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|--|--|------------|----------------|--|---|
| 3477 | Error | Infusion LPAS pressure transducer offset error. Infusion/irrigation and extraction functions will be disabled. | Infusion LPAS pressure transducer 0 offset out of range. | 4206 | Advisory | Handpiece power DC2DC output was out of range. Please release the footswitch treadle to reset. If problem persists, please contact Field Services. | While powering the handpiece, the DC2DC voltage for handpiece power is out of range. |
| 3478 | Error | Infusion LPAS pressure error. Infusion/irrigation and extraction functions will be disabled. | Infusion LPAS source pressure too high. | 4207 | Advisory | Handpiece was removed while powered. Please reconnect handpiece and re-tune. | User has disconnected the handpiece while it's being powered. |
| 3479 | Advisory | Infusion LPAS pressure is low. Infusion pressure loss is possible. | Infusion LPAS pump output pressure is low. | 4208 | Advisory | Data in handpiece EEPROM is out of range. Please replace the handpiece. | Data contained in the handpiece is out of range. |
| 3481 | Advisory | Infusion flow sensor is disconnected. IOP Compensation functions will be disabled. | Infusion flow sensor is disconnected or the sensor connection has failed. | 4209 | Advisory | Unknown US handpiece connected. Please connect a known handpiece. | The system has detected that a US handpiece was connected but it cannot determine its type. |
| 4100 | Error | U/S voltage failure (+5 analog). Ultrasound and Diathermy functions will be disabled. | US Kernel Analog 5 volt feed-back is bad. US Submodule is non-functional. | 4210 | Advisory | Unsupported US handpiece connected. Please connect a | The system has detected the connection of a recognized US handpiece but that handpiece |
| 4101 | Error | U/S voltage failure (+2.5). Ultrasound and Diathermy functions will be disabled. | US Kernel +2.5 volt feedback is bad. US submodule is non-functional. | 4000 | | supported handpiece. | is not supported by this system. Handpiece is not tuned. |
| 4102 | Error | U/S voltage failure (-2.5). Ultrasound and Diathermy functions will be disabled. | US Kernel -2.5 volt feedback is bad. US submodule is non-functional. | 4220 | Advisory | Tune failure – attempted while handpiece was in air. Please re-tune the handpiece. | The handpiece was tuned while in air. Handpiece is not tuned. |
| 4103 | Error | U/S voltage failure (+8.5). Ultrasound and Diathermy functions will be disabled. | US Kernel 2.5 volt feedback is bad. US submodule is non-functional. | 4221 | Advisory | Tune failure: handpiece was removed before tuning. Please connect a handpiece and retune. | A handpiece tune was requested but no handpiece is connected. |
| 4111 | Error | US failure: SPI driver write timeout. Ultrasound and Diathermy functions will be disabled. | SPI driver timed out waiting for a write to complete. US submodule is non-functional. | 4222 | Advisory | Tune failure: handpiece is an unknown type. Please connect a known handpiece and re-tune. | A handpiece tune was requested but an unknown type of handpiece is connected. |
| 4200 | Advisory | Handpiece EEPROM CRC is invalid. Please replace the handpiece. | The handpiece EEPROM CRC is invalid. Handpiece needs to be replaced. | 4223 | Advisory | Tune failure: handpiece has a loose tip. Please tighten the tip and re-tune. | The handpiece tip was loose when tuned. Handpiece is not tuned. |
| 4201 | Advisory | Only one US handpiece may be connected at a time. Please remove one of the handpieces. | Two US handpieces are connected. One of the handpieces must be removed before the other handpiece can be used. | 4224 | Advisory | Tune failure: handpiece current is low. Please replace handpiece and re-tune. | The handpiece current was too low (open circuit). Handpiece is not tuned. |
| 4202 | Advisory | Handpiece current is too low. Please replace handpiece and re-tune. | U/S handpiece current is too low. A short circuit in the handpiece can cause this. | 4225 | Advisory | Tune failure: handpiece voltage is low. Please replace handpiece and re-tune. | The handpiece voltage was too low when tuned (short circuit). Handpiece is not tuned. |
| 4203 | Advisory | Handpiece voltage is too low. Please replace handpiece and re-tune. | U/S handpiece voltage is too low. An open circuit in the handpiece can cause this. | 4226 | Advisory | Tune failure: handpiece frequency order error. Please re-tune. | The series (low impedance) and parallel (high impedance) frequencies were out of order when the handpiece was tuned. |
| 4204 | Advisory | Handpiece power is too high. Please replace handpiece and re-tune. | U/S handpiece power output is too high. | 4228 | Advisory | Tune failure: handpiece series frequency margin error. Please re-tune. | The series tune frequency was too close to the tune start frequency while tuning the handpiece. The handpiece is not tuned. |



| | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------|----------------|---|--|-------------------|----------------|--|--|
| 4229 | Advisory | Tune failure: handpiece par- allel frequency margin error. Please re-tune. | The parallel tune frequency was too close to the tune end frequency while tuning the handpiece. The handpiece is not tuned. | 5102 | Advisory | Lamp calibration data is corrupted: lamp needs to be calibrated. Please contact Field Service. | |
| 4231 | Advisory | Tune failure: handpiece frequency bandwidth too low. Please re-tune. | The difference between the series and parallel tune frequencies was too small while tuning | 5103 | Advisory | Failure to turn lamp on: lamp needs to be replaced. Please contact Field Service. | Lamp status reported by hardware is not the same as software status. |
| | | riease re-turie. | the handpiece. The handpiece is not tuned. | 5104 | Advisory | The lamp has exceeded its rated life. Please replace the lamp. | The lamp has exceeded its rated life. The new lamp is expected. |
| 4232 | Advisory | Tune failure: handpiece frequency bandwidth too high. Please re-tune | The difference between the series and parallel tune frequencies was too large while tuning the handpiece. The handpiece is not tuned. | 5105 | Advisory | The lamp has exceeded its rated maximum life. Please install a new lamp immediately. | The lamp has exceeded its rated safe life. The new lamp should be installed immediately. |
| 4234 | Advisory | Tune failure: handpiece DC2DC output out of range. Please re-tune. If problem | The DC2DC voltage was out of range while tuning the hand-piece. The handpiece is not | 5107 | Advisory | The Table-Top Illuminator drawer is ejected. Please close the drawer to continue. | The module has been pulled out of drawer. |
| | | persists, please contact Field Service. | tuned. | 5109 | Information | The calibration data for the Illuminator has changed: due to recalibration or replacement | The calibration data is changed. |
| 4235 | Advisory | Tune failure: handpiece removed while tuning. Please connect handpiece and retune. | The handpiece was removed while tuning. The handpiece is not tuned. | 5200 | Advisory | with a new unit. Illuminator optics temperature is high. The lamp will be turned off if the temperature continues | Optics temperature is too high. Lamp is going to be shut down if temperature continues to rise. |
| 4240 | Advisory | The requested Frag continuous power is too high. The Power level will be limited. | A request for more than 60% frag power was made while not in a pulsed mode. The power will be limited to 60%. | 5201 | Error | to rise. Illuminator optics temperature has exceeded its limit. Illu- | Illuminator is shut down because Optics temperature is too |
| 4250 | Error | Ultrasound failure: ADC calibration. Ultrasound functions will be disabled. | The ADC feedback reading with power off for DC2DC voltage, handpiece voltage, or handpiece current was too high. | 5202 | Advisory | minator functions will be disabled. Illuminator optics fan is at full speed. Optics unit may be | Warning that the Optics fan is full on. |
| 4300 | Error | Diathermy failure: DC2DC output was out of range. Diathermy functions will be disabled. | While powering the handpiece, the DC2DC voltage for handpiece power is out of range. | 5203 | Error | overheating. Illuminator optics thermo-cut- off has been triggered. Illu- minator functions will be dis- | Lamp is turned off because thermo cut-off. |
| 4301 | Advisory | Diathermy power is too high. Please release the footswitch treadle / button and try again. | Too much power was being delivered to the diathermy handpiece. Diathermy power is turned off. The operator must release the treadle/switch and | 5204 | Advisory | abled. Communication failure with the Illuminator optics fan. The fan may not work properly. | Communication Error with optics fan. |
| 5100 | Error | Ballast failure (voltage). Illu- | the depress the treadle/switch to re-activate power. Ballast transducer has reading that is out of appointed activities. | 5300 | Advisory | Illuminator ballast temperature is high. The lamp will be turned off if the temperature continues | Ballast temperature is too high. Lamp is going to be shut down if temperature continues to rise. |
| 5101 | Error | minator functions will be disabled. Ballast failure (current). Illuminator functions will be disabled. | that is out of specified safety range. Ballast transducer has reading that is out of specified safety | 5301 | Error | to rise. Illuminator ballast temperature has exceeded its limit. Illuminator functions will be disabled. | Illuminator is shut down because Ballast temperature is too high. |
| | | abled. | range. | 5302 | Advisory | Illuminator ballast fan is at full speed. Ballast unit may be overheating. | Warning that the Ballast fan is full on. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|--|---|------------|----------------|--|---|
| 5303 | Error | Illuminator ballast thermo- cut-off has been triggered. Illuminator functions will be disabled. | Lamp is turned off because thermo cut-off. | 6208 | Error | Inlet pressure is unstable. Pneumatics functions will be disabled. Please restart the system. | The Air source pressure (wall pressure) is unstable to cause the system unexpected to turn On/Off pressure. |
| 5304 | Advisory | Communication failure with the Illuminator ballast fan. The fan may not work properly. | Communication Error with ballast fan. | 6301 | Error | Cutting errors; valves have high transition faults (failed to open). Cutting functions will be disabled. | Cutters valves have high level faults (fail to open). |
| 5400 | Error | Lamp louver failure at port 1: unable to move to home position. Port 1 will be disabled. | Step motor at port 1 failed to move to home position. | 6302 | Error | Cutting errors; valves have low transition faults (failed to close). Cutting functions will | Cutters valves have low level faults (fail to close). |
| 5401 | Error | Lamp Louver failure at port 2: unable to move to home position. Port 2 will be disabled. | Step motor at port 2 failed to move to home position. | 6303 | Error | be disabled. Cutting error: redundant trans- | Cutters redundant transducers |
| 5402 | Error | Lamp Louver failure at port 1: unable to move to specified position. Port 1 will be disabled. | Step motor at port 1 failed to move to specified position. | | | ducers discrepancy error. Cutting functions will be disabled. Please contact Field Service. | discrepancy error. |
| 5403 | Error | Lamp Louver failure at port 2: unable to move to specified position. Port 2 will be disabled. | Step motor at port 2 failed to move to specified position. | 6304 | Error | Cutting error: redundant transducers calibration. Cutting functions will be disabled. Please contact Field Service. | Cutters redundant transducers calibration error. |
| 6101 | Error | Pressure reading is too high. Cutting and Pneumatics func- tions will be disabled. | Pneumatics pressure is too high. | 6305 | Advisory | Cutting pressure is oscillating beyond the specified range. Please release the footswitch treadle to reset. | Cutters actual pressure is oscillating beyond the specified tolerance. |
| 6201 | Error | Air Pressure valves have high transition faults. Cutting and Pneumatics functions will be disabled. | AirPressure valves have high level faults (fail to open). | 6306 | Advisory | Cutting pressure is surging beyond the specified tolerance. Please release the footswitch treadle to reset. | Cutters actual pressure is surging beyond the specified tolerance. |
| 6202 | Error | Air Pressure valves have low transition faults. Cutting and Pneumatics functionals will be disabled. | AirPressure valves have low level faults (fail to close). | 6401 | Error | Utilities valves have high transition faults (failed to open). Pneumatics functions will be disabled. | Utilities valves have high level faults (fail to open). |
| 6203 | Advisory | Air Pressure inlet filter may be dirty and needs to be replaced. Please contact Field Service. | The unusual high pressure drop cross the Air Filter. This is caused by either the Air Filter is too dirty and need to be replaced or the system may be leaking air. | 6402 | Error | Utilities valves have low transition faults (failed to close). Pneumatics functions will be disabled. | Utilities valves have low level faults (fail to close). |
| 6204 | Advisory | Inlet pressure is too low for the system. Please adjust the inlet pressure to higher than 58 psi. | The Air source (wall pressure) is too low (below 58 psi) to turn on. On startup, Pneumatics turns on | 6403 | Error | Utilities redundant transducers discrepancy error. Pneumatics functions will be disabled. Please contact Field Service. | Utilities redundant transducers discrepancy error. |
| 6206 | Advisory | Inlet pressure is too high for | the pressure automatically if the pressure is high enough (above 58 psi). The Air source (wall pressure) | 6404 | Error | Utilities redundant transduc- ers calibration error. Pneumat- ics functions will be disabled. Please contact Field Service. | Utilities redundant transducers calibration error. |
| 3200 | Advisory | the system. Please adjust the inlet pressure to less than 140 psi. | is too high (above 120 psi) to turn on. On startup, Pneumatics turns on the pressure automatically if the pressure is high enough (above 58 psi). | 6405 | Error | Vacuum redundant transducers discrepancy error. Pneumatics functions will be disabled. Please contact Field Service. | Vacuum redundant transducers discrepancy error. |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|---|--|------------|----------------|---|--|
| 6406 | Error | Vacuum redundant transducers calibration error. Pneumatics functions will be disabled. Please contact Field Service. | Vacuum redundant transducers calibration error. | 7103 | Advisory | Failure to turn lamp on: lamp needs to be replaced. Please contact Field Service. | Lamp status reported by hard- ware is not the same as soft- ware status. |
| 6407 | Advisory | Utilities pressure is oscillating | Utilities actual pressure is oscil- | 7104 | Advisory | The lamp has exceeded its rated life: lamp needs to be replaced. Please contact Field Service. | The lamp has exceeded its rated life. The new lamp is expected. |
| 0401 | Advisory | beyond the specified range. Please release the footswitch treadle to reset. | lating beyond the specified tolerance. | 7105 | Advisory | The lamp has exceeded its rated maximum life: lamp needs to be replaced. Please contact | The lamp has exceeded its rated safe life. The new lamp should be installed immediately. |
| 6408 | Advisory | Utilities pressure is surging be- yond the specified tolerance. Please release the footswitch treadle to reset. | Utilities actual pressure is surging beyond the specified tolerance. | 7200 | Advisory | Field Service. Illuminator optics temperature is high. The lamp will be turned | Optics temperature is too high. Lamp is going to be shut down if |
| 6501 | Error | Auto Gas valves have high transition faults (failed to open). Pneumatics functions | Auto Gas valves have high level faults (fail to open). | 7201 | Error | off if the temperature continues to rise. Illuminator optics temperature | temperature continues to rise. Illuminator is shut down be- |
| 6502 | Error | will be disabled. Auto Gas valves have low tran- | Auto Gas valves have low level | 7201 | LIIOI | has exceeded its limit. Illuminator functions will be disabled. | cause Optics temperature is too high. |
| | _ | sition faults (failed to close). Pneumatics functions will be disabled. | faults (fail to close). | 7202 | Advisory | Illuminator optics fan is at full speed. Optics unit may be overheating. | Warning that the Optics fan is full on. |
| 6503 | Error | Auto Gas redundant transducers discrepancy error. Pneumatics functions will be disabled. Please contact Field Service. | Auto Gas redundant transducers discrepancy error. | 7203 | Error | Illuminator optics thermo-cut- off has been triggered. Illu- minator functions will be dis- abled. | Lamp is turned off because thermo cut-off. |
| 6504 | Error | Auto Gas redundant transduc- ers calibration error. Pneumat- ics functions will be disabled. Please contact Field Service. | Auto Gas redundant transducers calibration error. | 7204 | Advisory | Communication failure with the Illuminator optics fan. The fan may not work properly. | Communication Error with optics fan. |
| 6505 | Advisory | C3F8 bottle may be empty and needs to be replaced. Please press [Replaced] to confirm bottle replacement. | Gas 1 bottle may be empty and needs to be filled up. | 7300 | Advisory | Illuminator ballast temperature is high. The lamp will be turned off if the temperature continues to rise. | Ballast temperature is too high. Lamp is going to be shut down if temperature continues to rise. |
| 6506 | Advisory | SF6 bottle may be empty and needs to be replaced. Please press [Replaced] to confirm | Gas 2 bottle may be empty and needs to be filled up. | 7301 | Error | Illuminator ballast temperature has exceeded its limit. Illuminator functions will be disabled. | Illuminator is shut down because Ballast temperature is too high. |
| 7100 | Error | bottle replacement. Ballast failure (voltage). Illu- | Ballast transducer has reading | 7302 | Advisory | Illuminator ballast fan is at full speed. Ballast unit may be overheating. | Warning that the Ballast fan is full on. |
| 7101 | Error | minator functions will be disabled. Ballast failure (current). Illu- | that is out of specified safety range. Ballast transducer has reading | 7303 | Error | Illuminator ballast thermo- cut-off has been triggered. Illuminator functions will be | Lamp is turned off because thermo cut-off. |
| | | minator functions will be disabled. | that is out of specified safety range. | 7304 | Advisory | disabled. | Communication Error with bal- |
| 7102 | Advisory | Lamp calibration data is corrupted: lamp needs to be calibrated. Please contact Field Service | the flash contains incorrect | 7304 | Auvisory | Illuminator ballast fan. The fan may not work properly. | |



| | | VISION SYSTEM | | | | | |
|------------|----------------|---|--|------------|----------------|--|-------------------|
| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
| 7400 | Error | Lamp louver failure at port 3: unable to move to home position. Port 3 will be disabled. | Step motor at port 1 failed to move to home position. | 8111 | Error | Laser controller LBO crystal limit error. Laser functions will be disabled. | Need description. |
| 7401 | Error | Lamp louver failure at port 4: unable to move to home position. Port 4 will be disabled. | Step motor at port 2 failed to move to home position. | 8112 | Error | Laser controller pump temperature limit error. Laser functions will be disabled. | Need description. |
| 7402 | Error | Lamp louver failure at port 3: unable to move to specified position. Port 3 will be disabled. | Step motor at port 1 failed to move to specified position. | 8113 | Error | Laser controller power detect digital I/O mismatch error. Laser functions will be disabled. | Need description. |
| 7403 | Error | Lamp louver failure at port 4: unable to move to specified position. Port 4 will be dis- | Step motor at port 2 failed to move to specified position. | 8114 | Error | Laser controller footswitch digital I/O mismatch error. Laser functions will be disabled. | Need description. |
| 8100 | Error | abled. Laser controller software er- | Need description. | 8115 | Error | Laser controller footswitch no NC (normally closed) error. Laser functions will be disabled. | Need description. |
| | _ | ror. Laser functions will be disabled. | · | 8117 | Advisory | Laser controller internal parameter error. | Need description. |
| 8101 | Error | Laser controller shutter open for too long error. Laser functions will be disabled. | Need description. | 8118 | Error | Laser controller process hunt error. Laser functions will be disabled. | Need description. |
| 8102 | Error | Laser controller shutter unexpected error. Laser functions will be disabled. | Need description. | 8119 | Error | Laser controller process attach error. Laser functions will be disabled. | Need description. |
| 8103 | Error | Laser controller shutter open between firing error. Laser functions will be disabled. | Need description. | 8120 | Error | Laser controller start up time out error. Laser functions will be disabled. | Need description. |
| 8104 | Error | Laser controller mirror incorrect position error. Laser functions will be disabled. | Need description. | 8121 | Error | Laser controller JEM CRC error. Laser functions will be disabled. | Need description. |
| 8105 | Error | Laser controller mirror position unexpected error. Laser functions will be disabled. | Need description. | 8122 | Error | Laser controller kernel CRC error. Laser functions will be disabled. | Need description. |
| 8106 | Error | Laser controller power over the limit error. Laser functions will be disabled. | Need description. | 8123 | Error | Laser controller flash file er- ror. Laser functions will be dis- | Need description. |
| 8107 | Advisory | Laser controller maximum current exceeded error. Laser functions will be disabled. | Need description. | 8124 | Advisory | abled. Laser LBO diode over temperature error. | Need description. |
| 8108 | Error | Laser controller port power detection error. Laser functions will be disabled. | Need description. | 8125 | Advisory | Laser LBO diode under temperature error. | Need description. |
| 8109 | Error | Laser controller power detected at wrong port error. Laser | Need description. | 8126 | Advisory | Laser controller crystal over-temperature error. | Need description. |
| | | functions will be disabled. | | 8127 | Advisory | Laser controller crystal under- temperature error. | Need description. |
| 8110 | Error | Laser controller power reading mismatch error. Laser functions will be disabled. | Need description. | 8129 | Advisory | Laser controller probe connection error. | Need Description |
| | 806575115 | 3 | | | | | 4 29 |



| Error Code | Classification | Displayed Text | Discrepancy | Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|---|-----------------------|------------|----------------|---|-------------------|
| 8131 | Error | Laser controller power monitor POST error. Laser functions will be disabled. | Need description. | 8149 | Error | Laser controller Dr Filter error. Laser functions will be disabled. | Need description. |
| 8132 | Error | Laser controller +2.5 volt out- of-range error. Laser functions will be disabled. | Need description. | 8150 | Error | Laser controller invalid maximum power error. Laser functions will be disabled. | Need description. |
| 8134 | Error | Laser controller 12 volt power error. Laser functions will be disabled. | Need description. | 8153 | Error | Laser controller load module CRC error. Laser functions will be disabled. | Need description. |
| 8135 | Error | Laser shutter timer expired error. Laser functions will be disabled. | Need description. | 8154 | Error | Laser controller module requires calibration. Laser functions will be disabled. | Need description. |
| 8138 | Error | Laser controller diode thermal electric cooler error. Laser functions will be disabled. | Need description. | 8200 | Advisory | Laser controller probe removed while firing. | Need description. |
| 8139 | Error | Laser probe port process POST error. Laser functions | Need description. | 8202 | Advisory | Laser controller Dr. Filter disengaged while firing. | Need description. |
| 0440 | 5 | will be disabled. | No addes a significan | 8203 | Advisory | Laser controller Dr. Filter disconnected while firing. | Need description. |
| 8140 | Error | Laser controller startup time- out error (laser engine). Laser functions will be disabled. | Need description. | 8204 | Advisory | Laser controller interlock opened while firing. | Need description. |
| 8141 | Error | Laser controller startup tim- eout error (shutter control pro- cess). Laser functions will be | Need description. | 8205 | Advisory | Laser controller footswitch disconnected while firing. | Need description. |
| 0440 | _ | disabled. | N. 11 | 8207 | Advisory | Laser controller port changed in Ready State. | Need description. |
| 8142 | Error | Laser controller startup timeout error (supervisor process). Laser functions will be disabled. | Need description. | 8208 | Advisory | Laser controller Dr. Filter disengaged in Ready State. | Need description. |
| 8143 | Error | Laser controller startup timeout error (peripheral management process). Laser functions will | Need description. | 8209 | Advisory | Laser controller Dr. Filter disconnected in Ready State. | Need description. |
| 8144 | Error | be disabled. Laser controller startup timeout | Need description. | 8210 | Advisory | Laser controller interlock opened in Ready State. | Need description. |
| 0144 | EIIUI | error (probe port process). La- ser functions will be disabled. | Need description. | 8211 | Advisory | Laser controller footswitch removed in Ready State. | Need description. |
| 8145 | Error | Laser controller startup timeout error (laser system controller). Laser functions will be disabled. | Need description. | 8212 | Advisory | Laser controller footswitch engaged when Ready requested. | Need description. |
| 8147 | Error | Laser controller TMP crystal startup timeout error. Laser | Need description. | 8213 | Advisory | Laser controller user data CRC error. | Need description. |
| 8148 | Error | functions will be disabled. Laser controller TMP diode | Need description. | 8214 | Advisory | Laser controller Ready State denied: the filter is disengaged. | Need description. |
| | | startup timeout error. Laser functions will be disabled. | · | 8215 | Advisory | Laser controller Ready State denied: there is no interlock. | Need description. |
| | | | | I | | | |



| Error Code | Classification | Displayed Text | Discrepancy |
|------------|----------------|---|--|
| 8216 | Advisory | Laser controller Ready State denied: there is no valid probe for the active port. | Need description. |
| 8217 | Advisory | Laser controller Ready State denied: the footswitch is depressed. | Need description. |
| 8218 | Advisory | Are all necessary Dr. Filters properly installed and connected? | User requests going to Ready Mode when the doctor filters haven't been verified. |
| 8219 | Advisory | Laser controller Ready State denied: there is no footswitch present. | User presses the Laser Ready button when no footswitch is connected. |
| 8220 | Advisory | Laser controller Dr. Filter con- nected while in Transition, Ready or Firing State. | User connects an engaged Dr. Filter while in Transition / Ready or Firing mode and and Endo probe is connected to the active port. |



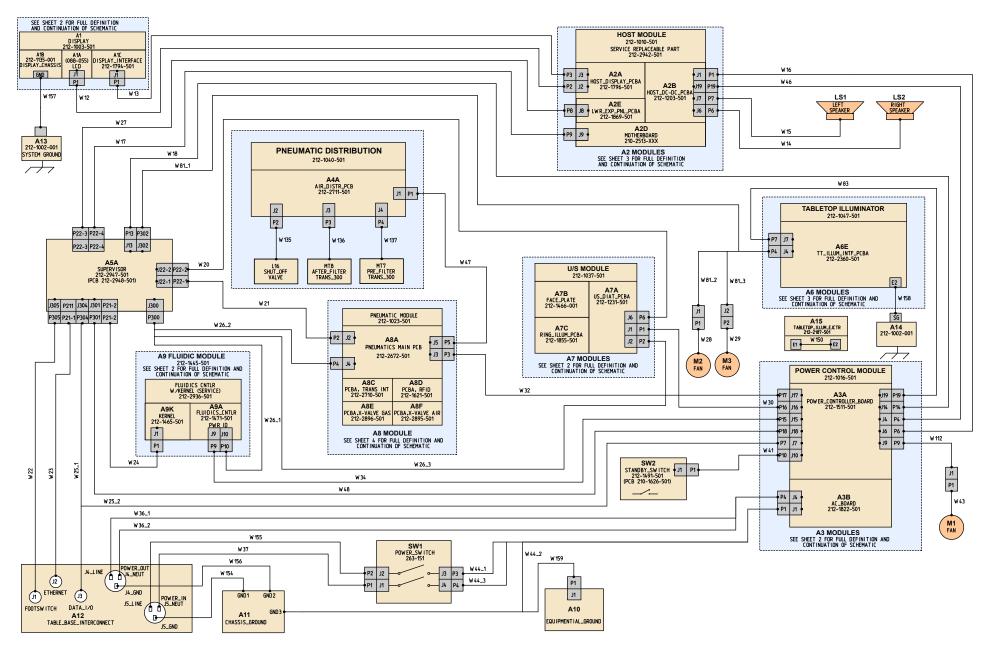
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SECTION FIVE SCHEMATICS

| DESCRIPTION | PART NUMBER | PAGE# |
|-------------------------------------|--------------|-------|
| SYSTEM CONSOLE INTERCONNECT DIAGRAM | 212-5002-801 | 5.2 |
| SYSTEM BASE INTERCONNECT DIAGRAM | | |
| FLUIDICS DIAGRAM | 212-1445-801 | 5.9 |
| PNEUMATICS DIAGRAM | 212-1445-801 | 5.14 |
| FOOTSWITCH | 212-1083-501 | 5.16 |
| CABLES, INTERCONNECT, CONSTELLATION | | 5.17 |

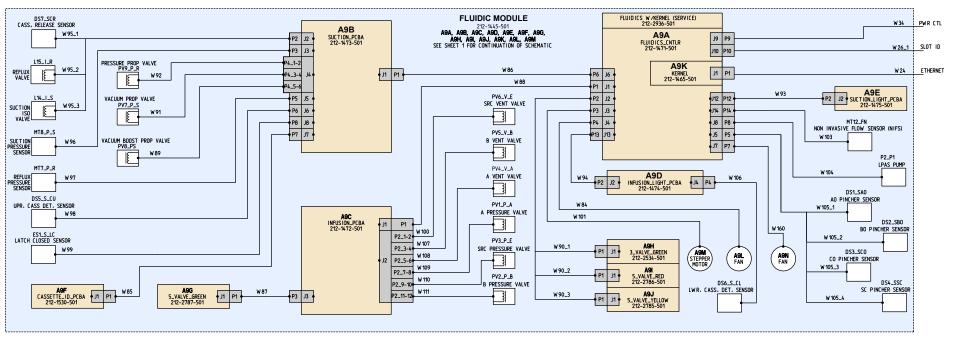


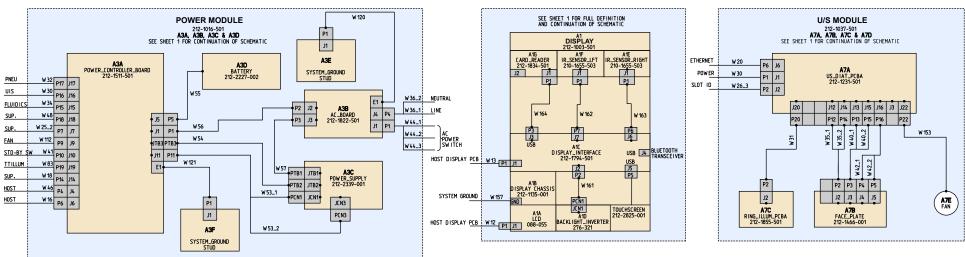


212-5002-801

System Console Interconnect Diagram (1 of 5)

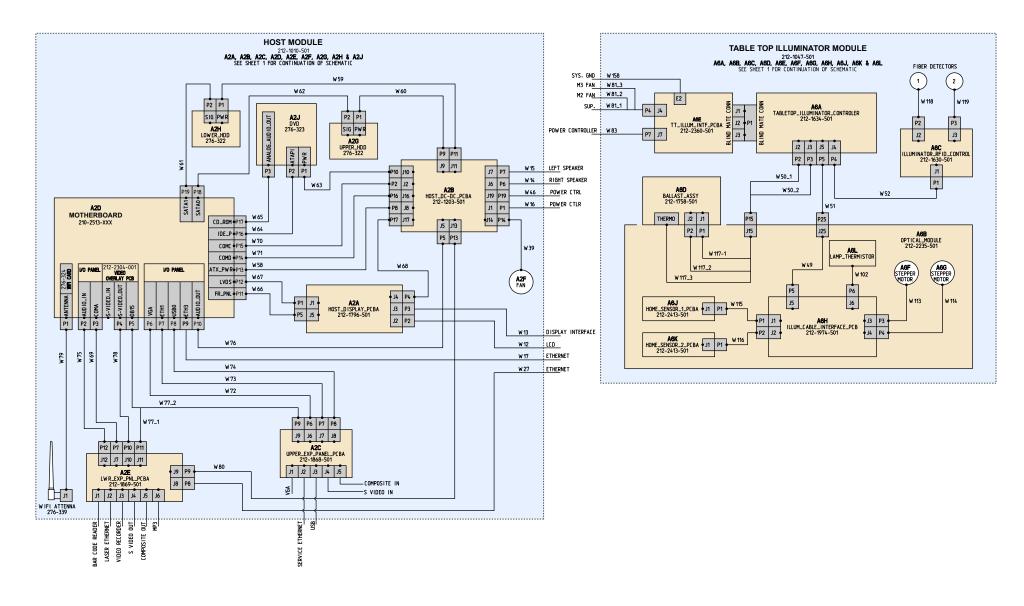




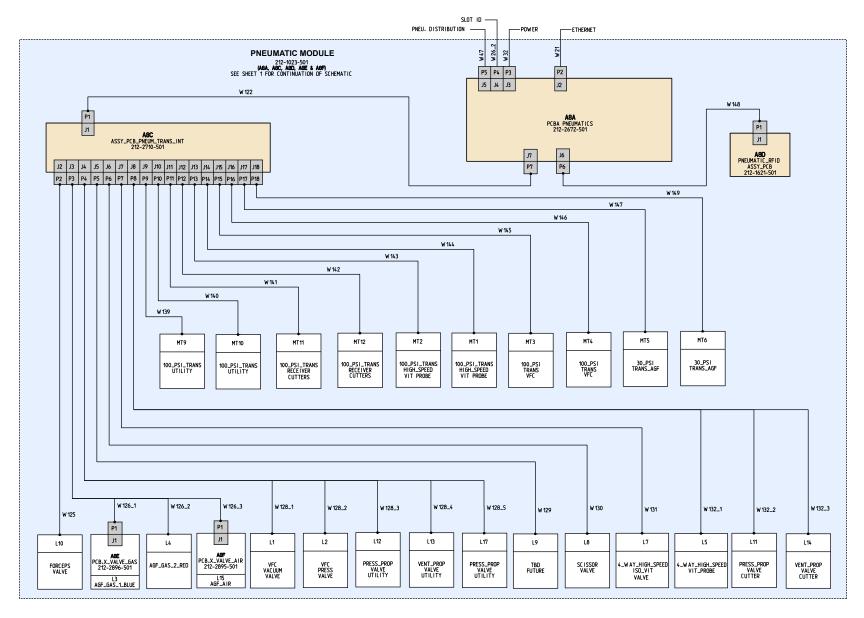


212-5002-801 System Console Interconnect Diagram (2 of 5)











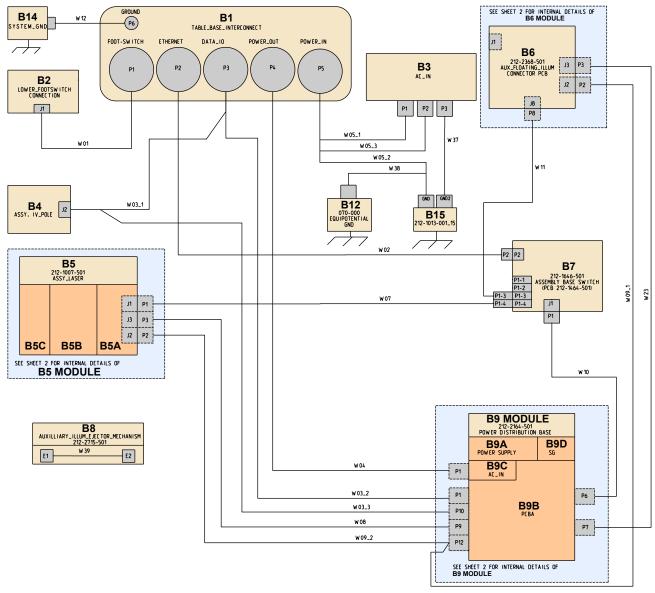
| D | | TOR REF DES | 41 0001 | |
|------------------|-------------------------|------------------------------|------------------------------|---|
| REF DES | FROM | TO | ALCON PART NUMBER | DESCRIPTION |
| | MODULE/CONNECTOR | MODULE/CONNECTOR | | |
| W 100 | A9CP2_1-2 | PV6_V_E_VALVE | 212-2634-001 | CABLE ASSY.PROP VALVE.LW |
| W 101 | A9AP3 | A9M_MOTOR | 212-2575-001 | MOTOR, STEPPER W / ENCODER, W 101 |
| W 102 | A6HP6 | A6L_SENSOR | 212-2623-001 | ASSY.CABLE.THERMISTOR.ILLUM |
| W 103 | A9AP14 | MT12_FN_SENSOR | 212-2308-001 | CABLE ASSY.SENSOR.FLOW.W 103 |
| W 104 W 105_1 | A9AP8 A9AP5 | P2_P1_PUMP DS1_SA0_SENSOR | 212-2290-001 212-2284-001 | CABLE ASSY, LPAS PUMP, W 104 CABLE ASSY, SENS, PINCHER W 105 |
| W 105_1 | A9AP5 | DS2_SB0_SENSOR | 212-2284-001 | CABLE ASSY.SENS.PINCHER W 105 CABLE ASSY.SENS.PINCHER W 105 |
| W 105_2 | A9AP5 | DS3_SCO_SENSOR | 212-2284-001 | CABLE ASSY.SENS.PINCHER W 105 |
| W 105_4 | A9AP5 | DS4_SSC_SENSOR | 212-2284-001 | CABLE ASSY.SENS.PINCHER W 105 |
| W 105_4 | A9DP4 | DS6_S_CL_SENSOR | 212-2292-002 | CABLE ASSY.CASS IN SENSOR.W 106 |
| W 107 | A9CP2_3-4 | PV5_V_B_VALVE | 212-2634-001 | CABLE ASSY.PROP VALVE.LW |
| W 108 | A9CP2_5-6 | PV4_V_A_VALVE | 212-2634-001 | CABLE ASSY.PROP VALVE.LW |
| W 109 | A9CP2_7-8 | PV1_P_A_VALVE | 212-2632-001 | CABLE ASSY.PROP VALVE.3S |
| W 110 | A9CP2_9-10 | PV3_P_E_VALVE | 212-2632-001 | CABLE ASSY.PROP VALVE.3S |
| W 111 | A9CP2_11-12 | PV2_P_B_VALVE | 212-2632-001 | CABLE ASSY.PROP VALVE.3S |
| W 112 | A3AP9 | M1J1 | 212-2604-001 | CABLE ASSY.FAN |
| W 113 | A6HP3 | A6F_MOTOR | 212-2656-001 | ASSY.CABLE.STEPPER MOTOR |
| W 114 | A6HP4 | A6G_MOTOR | 212-2656-001 | ASSY.CABLE.STEPPER MOTOR |
| W 115 | A6HP1 | A6JP1 | 212-2658-001 | ASSY.CABLE.HOME SENSOR |
| W 116 | A6HP2 | A6KP1 | 212-2658-001 | ASSY.CABLE.HOME SENSOR |
| W 117-1 | A6BJ15 | A6DP1 | 212-2655-001 | ASSY,CABLE,BALLAST INTFC |
| W 117_2 | A6BJ15 | A6DP2 | 212-2655-001 | ASSY,CABLE.BALLAST INTFC |
| W 117_3 | A6BJ15 | A6D_THERMO | 212-2655-001 | ASSY.CABLE.BALLAST INTFC |
| W 118 | A6CP2 | 1_FIBER_DETECT | 212-2266-001 | ASSY.CABLE.FIBER.DETECT |
| W 119 W 12 | A6CP3 A2AP2 | 2_FIBER_DETECT A1AP1 | 212-2266-001 | ASSY.CABLE.FIBER.DETECT ASSY.CABLE.VIDEO.LVDS |
| W 120 | AZAPZ A3BF1 | A3EP1 | 212-1871-001 | |
| W 120 | A3AE1 | A3FP1 | 212-2223-002 | CABLE. GND CABLE. GND |
| W 121 | ASAP7 | A8CP1 | 212-223-003 | CABLE ASSY, PNEU, INTERFACE, W 122 |
| W 125 | A8CP2 | L10_ | 212-2591-001 | CABLE ASSY.SMC VALVE |
| W 126_1 | A8CP3 | A8EP1 | 212-2747-001 | CABLE ASSY.W 126 |
| W 126_2 | A8CP3 | L4_ | 212-2747-001 | CABLE ASSY.W126 |
| W 126_3 | A8CP3 | A8FP1 | 212-2747-001 | CABLE ASSY.W126 |
| W 128_1 | A8CP4 | L1_ | 212-2748-001 | CABLE ASSY.W128 |
| W 128_2 | A8CP4 | L2_ | 212-2748-001 | CABLE ASSY.W128 |
| W 128_3 | A8CP4 | L12_ | 212-2748-001 | CABLE ASSY.W 128 |
| W 128_4 | A8CP4 | L13_ | 212-2748-001 | CABLE ASSY.W 128 |
| W 128_5 | A8CP4 | L17_ | 212-2748-001 | CABLE ASSY.W128 |
| W 129 | A8CP5 | L9_ | 212-2591-001 | CABLE ASSY.SMC VALVE |
| W 13 | A1CP1 | A2AP3 | 212-1872-001 | ASSY.CABLE.INTERFACE.DISPLAY |
| W 130 | A8CP6 | L8_ | 212-2591-001 | CABLE ASSY.SMC VALVE |
| W 131 | A8CP7 | L7_ | 212-2594-001 | CABLE ASSY, VIT, W 131 |
| W 132_1 | A8CP8 | L5_ 11 | 212-2749-001 | CABLE ASSY.W132 |
| W 132_2 | A8CP8 A8CP8 | | 212-2749-001 | CABLE ASSY.W132 |
| W 132_3 W 135 | A4AP2 | L14_ L16_ | 212-2749-001 212-2593-001 | CABLE ASSY.W132 CABLE ASSY.SMC VALVE |
| W 136 | A4AP2 A4AP3 | MT8 | 212-2588-001 | CABLE ASSY.PRESS SNSR 300 |
| W 137 | A4AP4 | MT7_ | 212-2588-001 | CABLE ASSY, PRESS SNSR 300 |
| W 139 | A8CP9 | MT9_ | 212-2590-001 | ASSY.CABLE.PRESS SNSR 100 |
| W 14 | A2BP6 | SPEAKER_LS2 | 212-2383-001 | CABLE ASSY.SATA SIG.W61/W62 |
| W 140 | A8CP10 | MT10_ | 212-2590-001 | ASSY,CABLE,PRESS SNSR 100 |
| W 141 | A8CP11 | MT11_ | 212-2590-001 | ASSY.CABLE.PRESS SNSR 100 |
| W 142 | A8CP12 | MT12_ | 212-2590-001 | ASSY.CABLE.PRESS SNSR 100 |
| W 143 | A8CP13 | MT2_ | 212-2590-001 | ASSY.CABLE.PRESS SNSR 100 |
| W 144 | A8CP14 | MT1_ | 212-2590-001 | ASSY.CABLE.PRESS SNSR 100 |
| W 145 | A8CP15 | MT3_ | 212-2590-001 | ASSY.CABLE.PRESS SNSR 100 |
| W 146 | A8C P16 | MT4_ | 212-2590-001 | ASSY.CABLE.PRESS SNSR 100 |
| W 147 | A8CP17 | MT5_ | 212-2589-001 | CABLE ASSY PRESS SNSR 30 |
| W 148 | A8AP6 | A8DP1 | 212-2595-001 | CABLE ASSY,RFID,W148 |
| W 149 | A8CP18 | MT6_ | 212-2589-001 | CABLE ASSY.PRESS SNSR 30 |
| W 15 | A2BP7 | SPEAKER_LS1 | 212-1557-002 | ASSY, CABLE, LEFT SPEAKER |
| W 150 W 153 | A15E1 A7E_FAN | A15E2 A7AP22 | 212-2957-002 212-2274-002 | CABLE ASSY.GND.TT ILLUM EJCTR ASSY.CABLE.FAN |
| W 153 W 154 | A7E_FAN A12J5_GND | A7AP22 A11GND1 | 212-2274-002 | ASSY.CABLE.FAN ASSY.CABLE.W 154.AC IN |
| W 154 W 155 | A12.J5_LINE | SW 1P2 | 212-1580-002 | ASSY,CABLE,W155,AC IN |
| W 156 | A1235_LINE A1234_GND | SW 1PZ A11GND2 | 212-1580-003 | ASSY.CABLE.W155.AC IN |
| W 157 | A 12 J4 _ UND | A13SG | 212-2281-001 | ASSY,GROUND STRAP.DISPLAY |
| W 157 | A IBUND A6EE2 | A145G | 212-2667-001 | ASSY.CABLE.ILLUM GROUND STRAP |
| W 159 | A11GND3 | A10P1 | 212-1580-005 | ASSY.CABLE.W 159.GROUND |
| W 16 | A3AP6 | A2BP1 | 212-1559-001 | ASSY.CABLE.HOST INTERFACE W 16 |
| W 160 | A9AP7 | A9N_FAN | 212-2937-001 | CABLE ASSY.FLUIDICS FAN |
| W 161 | A1CP2 | A1DPCN1 | 212-1873-001 | CABLE ASSY, DISPLAY, BLT INVERT |
| W 162 | A1C P7 | A1FP1 | 212-1874-001 | CABLE ASSY. DISPLAY.IR SNSR RT |
| W 163 | A1CP6 | A1EP1 | 212-1874-002 | CABLE ASSY. DISPLAY.IR SNSR LFT |
| W 164 | A1CP3 | A1GP1 | 212-1876-001 | CABLE ASSY. DISP. SD CARD READER |
| W 17 | A2DP9 | A5AP22-4 | 212-1560-001 | ASSY.CABLE.ETHERNET W 17 |
| W 17 | | | | |
| W 18 W 20 | A5AP13 A5AP22-2 | A3AP14 A7AP6 | 212-1561-001 212-1560-002 | CABLE ASSY.24V.DC W 18 ASSY.CABLE.ETHERNET.U/S |

| REF | | TOR REF DES | ALCON | | | |
|-------------|------------------|------------------|--------------|--|--|--|
| DES | FROM | TO | PART NUMBER | DESCRIPTION | | |
| | MODULE/CONNECTOR | MODULE/CONNECTOR | | | | |
| W 21 | A8AP2 | A5AP22-1 | 212-1560-003 | ASSY.CABLE.ETHERNET.PNEU | | |
| W 22 | A5AP305 | A12J1 | 212-1565-001 | ASSY.CABLE.W 22.F00TSW ITCH | | |
| W 23 | A5AP21-1 | A12J2 | 212-1566-001 | ASSY.CABLE.W 23.ETHERNET TO BAS | | |
| W 24 | A5AP21-2 | A9KP1 | 212-1560-004 | ASSY.CABLE.ETHERNET.FLUIDICS | | |
| w 25_1 | A5AP304 | A12J3 | 212-1568-001 | ASSY.CABLE.W 25.DATA I/O | | |
| v 25_2 | A12J3 | A3AP7 | 212-1568-001 | ASSY.CABLE.W 25.DATA I/O | | |
| W 26_1 | A9AP10 | A5AP300 | 212-1569-001 | ASSY.CABLE.SLOT ID | | |
| 126_2 | A8AP4 | A5AP300 | 212-1569-001 | ASSY,CABLE,SLOT ID | | |
| | | | | | | |
| 126_3 | A7AP2 | A5AP300 | 212-1569-001 | ASSY.CABLE.SLOT ID | | |
| W 27 | A2EP8 | A5AP22-3 | 212-1560-008 | ASSY.CABLE.ETHERNET W 27 | | |
| W 28 | M2_FAN | M2P1 | 212-2267-001 | CABLE ASSY,FAN,W28 | | |
| W 29 | M3_FAN | M3P2 | 212-2268-001 | CABLE ASSY,FAN,W29 | | |
| W 30 | A3AP16 | A7AP1 | 212-1561-004 | CABLE ASSY.24V.DC W 30 | | |
| W 31 | A7AP20 | A7CP1 | 212-2269-001 | ASSY. CABLE.U/S RING ILLUM.W 31 | | |
| W 32 | A8AP3 | A3AP17 | 212-1561-005 | CABLE ASSY,24V.DC W32 | | |
| W 34 | A3AP15 | A9AP9 | 212-1561-006 | CABLE ASSY,24V.DC W34 | | |
| /35_1 | A7BP2 | A7AP12 | 212-2271-001 | | | |
| | | | | ASSY, CABLE, U/S.W35 | | |
| 35_2 | A7BP2 | A7AP14 | 212-2271-001 | ASSY, CABLE, U/S,W35 | | |
| 36_1 | A3BP4 | A12 J4 _L INE | 212-1579-001 | CABLE ASSY.W36.AC OUTPUT | | |
| 36_2 | A3BP4 | A12 J4 _NEUT | 212-1579-001 | CABLE ASSY.W 36.AC OUTPUT | | |
| W 37 | A12J5_NEUT | SW 1P1 | 212-1580-001 | ASSY.CABLE.W 37.AC IN | | |
| W 39 | A2F_FAN | A2BP14 | 212-2332-001 | ASSY.CABLE.HOST FAN.W 39 | | |
| 40_1 | A7BP3 | A7AP13 | 212-2271-002 | ASSY, CABLE, U/S.W40 | | |
| 40_2 | A7AP15 | A7BP3 | 212-2271-002 | ASSY. CABLE. U/S.W40 ASSY. CABLE. U/S.W40 | | |
| W 41 | A3AP10 | SW 2P1 | 212-1584-001 | ASSY.CABLE.STANDBY SW W41 | | |
| | | | 212-1304-001 | | | |
| 42_1 | A7BP4 | A7AP16 | 212-2273-001 | ASSY, CABLE, DIATHERMY,W42 | | |
| 42_2 | A7BP5 | | 212-2273-001 | ASSY. CABLE. DIATHERMY.W42 | | |
| W 43 | M1_FAN | M1P1 | 212-1586-001 | CABLE ASSY.FAN.W43 | | |
| 44_1 | A3BP1 | SW 1P3 | 212-1587-001 | CABLE ASSY.W 44.AC IN BREAKER | | |
| 44_2 | A3BP1 | A11GND 3 | 212-1587-001 | CABLE ASSY.W 44.AC IN BREAKER | | |
| 44_3 | A3BP1 | SW 1P4 | 212-1587-001 | CABLE ASSY,W44.AC IN BREAKER | | |
| W 46 | A3AP4 | A2BP19 | 212-1589-001 | ASSY.CABLE.24V DC W46 | | |
| W 47 | ARAPS | ALAP1 | 212-2062-001 | ASSY.CABLE.PNEU DIST W47 | | |
| W 47 | A3AP18 | A5AP301 | | | | |
| | | | 212-2063-001 | | | |
| W 49 | A6HP5 | A6BJ25 | 212-2531-001 | CABLE.CIRCUIT.FLEX ILLUM TT | | |
| 50_1 | A6BP15 | A6AP2 | 212-2198-001 | ASSY.CABLE.ILLUM BALLAST TOP | | |
| 50_2 | A6BP15 | A6AP3 | 212-2198-001 | ASSY.CABLE.ILLUM BALLAST TOP | | |
| W 51 | A6AP5 | A6BP25 | 212-2196-001 | ASSY.CABLE.ILLUM OPT INTEC | | |
| W 52 | A6AP4 | A6CP1 | 212-2199-001 | ASSY.CABLE.ILLUM RFID INTF W 52 | | |
| /53_1 | A3AP11 | A3CPCN1 | 212-2257-001 | ASSY.CABLE.W53.PWR SUP CNTRL | | |
| 53.2 | | A3CPCN3 | 212-2257-001 | ASSY.CABLE.W53.PWR SUP CNTRL | | |
| W 54 | A3APTB3 | A3CPTB2 | 212-2258-001 | ASSY.CABLE.W54.DC POWER.MAIN | | |
| | | | | | | |
| W 55 | A3AP5 | A3D_BATT | 212-2227-001 | BATTERY, POWER MODULE | | |
| W 56 | A3AP1 | A3BP2 | 212-2260-001 | ASSY.CABLE.W56.AC CONTROL | | |
| W 57 | A3BP3 | A3CPTB1 | 212-2261-001 | ASSY.CABLE.W57.AC POWER | | |
| W 58 | A2DP13 | A2BP8 | 212-2381-001 | ASSY.CABLE.ATX POWER W58 | | |
| W 59 | A2BP11 | A2HP1 | 212-2382-001 | CABLE ASSY.SATA PWR.W59/W60 | | |
| W 60 | A2BP9 | A2GP1 | 212-2382-001 | CABLE ASSY,SATA PWR,W59/W60 | | |
| W 61 | A2DP19 | A2HP2 | 212-2383-001 | CABLE ASSY.SATA SIG.W61/W62 | | |
| W 62 | A2DP18 | A2GP2 | 212-2383-001 | CABLE ASSY.SATA SIG.W61/W62 | | |
| W 63 | A2JP10 A2JP1 | A2BP10 | 212-2384-001 | ASSY.CABLE.DVD POWER, W63 | | |
| | | AZDY IU | | ACCY CADLE IDE CICHA INT | | |
| W 64 | A2DP16 | A2JP2 | 212-2385-001 | ASSY, CABLE, IDE SIGNAL, W 64 | | |
| W 65 | A2DP17 | A2JP3 | 212-2386-001 | ASSY, CABLE, CD-ROM AUDIO, W6 | | |
| W 66 | A2DP11 | A2AP5 | 212-2387-001 | ASSY.CABLE.FRONT PANEL USB W 66 | | |
| N 67 | A2DP12 | A2AP1 | 212-2388-001 | CABLE ASSY.LVDS SIGNAL.W 67 | | |
| W 68 | A2BP17 | A2AP4 | 212-2389-001 | ASSY.CABLE.PWR FR PNL W68 | | |
| W 69 | A2DP3 | A2EP7 | 212-2390-001 | CABLE ASSY.SERIAL.IO EXT W69 | | |
| w 70 | A2DP15 | A2BP2 | 212-2391-001 | CABLE ASSY, SERIAL, EXT 12.5 W 70 | | |
| W 71 | A20113 | A2BP16 | 212-2391-002 | ASSY.CABLE.SERIAL.EXT 16.0 W 71 | | |
| w 72 | A2DP6 | A20P10 | 212-2391-002 | CABLE ASSY.VGA.EXT W72 | | |
| | | | | | | |
| W 73 | A2DP7 | A2CP7 | 212-2393-001 | CABLE ASSY,ETHRNT EXTN.W73 | | |
| N 74 | A2DP8 | A2CP8 | 212-2394-001 | CABLE ASSY,USB,PORT EXT W 74 | | |
| <i>N</i> 75 | A2DP2 | A2EP12 | 212-2395-001 | CABLE ASSY.AUDIO EXT W75/W76 | | |
| N 76 | A2DP10 | A2BP5 | 212-2395-001 | CABLE ASSY, AUDIO EXT W 75/W 76 | | |
| 77_1 | A2DP5 | A2EP11 | 212-2396-001 | CABLE ASSY.VOM SIGNAL.EXT W77 | | |
| 77_2 | A2DP5 | A2CP9 | 212-2396-001 | CABLE ASSY.VOM SIGNAL.EXT W 77 | | |
| N 78 | A20P3 | A2EP10 | 212-2397-001 | CABLE ASSY.S-VIDEO.OUT EXT W7 | | |
| N 79 | A2DP4 | ANT_J1 | 212-2389-001 | ASSY.CABLE.PWR FR PNL W68 | | |
| | | | | | | |
| W 80 | A2BP13 | A2EP9 | 212-2399-001 | ASSY.CABLE.EXPNSN PWR SGNL.W8 | | |
| / 81_1 | A5AP302 | A6EP4 | 212-2499-001 | CABLE ASSY.I/O CONTROL W81 | | |
| 81_2 | A6EP4 | M2J1 | 212-2499-001 | CABLE ASSY, I/O CONTROL W 81 | | |
| 81_3 | A6EP4 | M3J2 | 212-2499-001 | CABLE ASSY.I/O CONTROL W 81 | | |
| W 83 | A6EP7 | A3AP19 | 212-1561-002 | CABLE ASSY.24V.DC W83 | | |
| W 84 | A9AP4 | | 212-2937-001 | | | |
| | | A9L_FAN | | CABLE ASSY, FLUIDICS FAN | | |
| W 85 | A9BP7 | A9FP1 | 212-2293-001 | CABLE ASSY.CASSETTE ID.W85 | | |
| W 86 | A9AP6 | A9BP1 | 212-2291-001 | CABLE ASSY, SUCTION CONTR., W 86 | | |
| W 87 | A9CP3 | A9GP1 | 023-095 | CABLE,FLAT.IDC SOCKET.2MM | | |
| W 88 | A9AP1 | A9CP1 | 212-2252-001 | CABLE ASSY, INF CONTROLLER W 88 | | |

| | CONNEC | TOR REF DES | ALCON PART NUMBER | | |
|--------|--------------------|--------------------|----------------------|---------------------------------|--|
| | FROM | то | | DESCRIPTION | |
| | MODULE / CONNECTOR | MODULE / CONNECTOR | | | |
| W 89 | A9BP4_5-6 | PV8_PS_VALVE | 212-2633-001 | CABLE ASSY.PROP VALVE.5S | |
| w 90_1 | A9AP2 | A9HP1 | 212-2288-001 | CABLE ASSY.X-VALVE | |
| w 90_2 | A9AP2 | A9IP1 | 212-2288-001 | CABLE ASSY.X-VALVE | |
| W 90_3 | A9AP2 | A9JP1 | 212-2288-001 | CABLE ASSY.X-VALVE | |
| W 91 | A9BP4_3-4 | PV7_P_S_VALVE | 212-2633-001 | CABLE ASSY.PROP VALVE.5S | |
| W 92 | A9BP4_1-2 | PV9_P_R_VALVE | 212-2632-001 | CABLE ASSY,PROP VALVE.3S | |
| W 93 | A9AP12 | A9EP2 | 023-091 | CABLE.RIBBON.20 COND.20 INCH | |
| W 94 | A9AP13 | A9DP2 | 023-092 | CABLE, RIBBON, 26 COND, 20 INCH | |
| W 95_1 | A9BP2 | DS7_SCR_SENSOR | 212-2294-001 | CABLE ASSY.SMC CASS-REL.W 95 | |
| W 95_2 | A9BP2 | L15_I_R_ | 212-2294-001 | CABLE ASSY.SMC CASS-REL.W 95 | |
| W 95_3 | A9BP2 | L14_I_S_ | 212-2294-001 | CABLE ASSY.SMC CASS-REL.W 95 | |
| W 96 | A9BP3 | MT8_P_S_ | 212-2580-001 | SENSOR.PRESSURE.ABS 30 | |
| W 97 | A9BP5 | MT7_P_R_ | 212-2579-001 | SENSOR.PRESSURE.ABS 100 | |
| W 98 | A9BP6 | DS5_S_CU_SENSOR | 212-2292-001 | CABLE ASSY.CASS IN SENSOR.W98 | |
| W 99 | A9BP8 | ES1_S_LC_SENSOR | 212-2272-001 | CABLE ASSY,LATCH POS.W 99 | |
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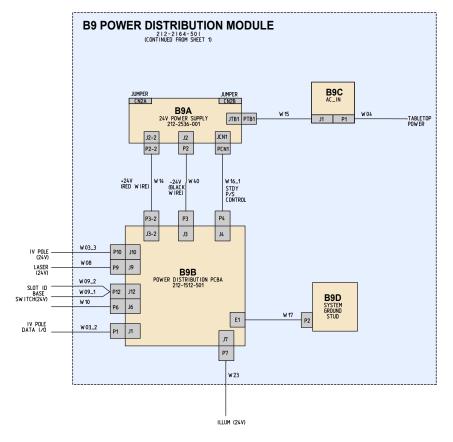
212-5002-801 System Console Interconnect Diagram (5 of 5)

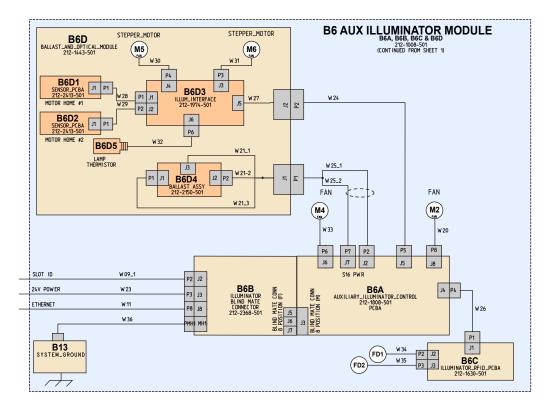


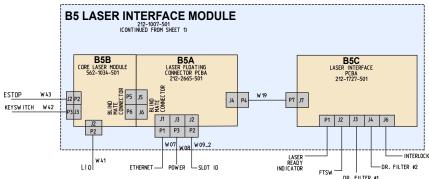


| | CONNECTOR | R REF DES | ALCON | DESCRIPTION |
|--------|------------------|------------------|--------------|----------------------------------|
| REF | FROM | TO | PART NUMBER | |
| DEO | MODULE/CONNECTOR | MODULE/CONNECTOR | | |
| W 01 | B1P1 | B2J1 | 212-1678-001 | CABLE, WO1, FOOT SWITCH |
| W 02 | B1P2 | B7P2 | 212-1560-009 | CABLE, W 02, ETHERNET |
| W 03_1 | B1P3 | B4J2 | 212-1680-001 | CABLE, WO3, DATA 10 |
| W 03_2 | B1P3 | B9BP1 | 212-1680-001 | CABLE, WO3, DATA IO |
| W 03_3 | B4 J2 | B9BP10 | 212-1680-001 | CABLE, WO3, DATA 10 |
| W 04 | B1P4 | B9CP1 | 212-1681-001 | CABLE, W 04, POWER_OUT |
| W 05_1 | B1P5 | B3P1 | 212-2201-001 | CABLE, W 05,AC POWER IN |
| W 05_2 | B1P5 | B15GND | 212-2201-001 | CABLE, W 05,AC POWER IN |
| W 05_3 | B3P2 | B1P5 | 212-2201-001 | CABLE, W 05,AC POWER IN |
| W 07 | B7P1-4 | B5AP1 | 212-1560-007 | CABLE, W 07, ETHERNET |
| W 08 | B5AP3 | B9BP9 | 212-1561-008 | CABLE, W 08, 24V DC |
| W 09_1 | B6BP2 | B9BP12 | 212-1689-001 | CABLE, W 09, SLOT ID |
| W 09_2 | B9BP12 | B5AP2 | 212-1689-001 | CABLE, W 09, SLOT ID |
| W 10 | B7P1 | B9BP6 | 212-1561-009 | CABLE, W 10, 24V DC |
| W 11 | B6BP8 | B7P1-3 | 212-1560-006 | CABLE, W 11, ETHERNET |
| W 12 | B14SG | B1P6 | 212-2019-001 | EQUI GROUND CABLE |
| W 14 | B9BP3-2 | B9AP2-2 | 212-2220-001 | CABLE, W14, DC POWER |
| W 15 | B9APTB1 | B9CJ1 | 212-2221-001 | CABLE, W15, AC IN |
| W 16_1 | B9BP4 | B9APCN1 | 212-2222-001 | CABLE, W16, PS CONTROL |
| W 17 | B9BE1 | B9DP2 | 212-2223-001 | CABLE, W 17, GROUND |
| W 19 | B5AP4 | B5CP7 | 212-1996-501 | CABLE, W 19, LASER INTERFACE |
| W 20 | M2FAN | B6AP8 | 212-2268-002 | CABLE, W 20, FAN OPTICS |
| W 21-2 | B6D J15 | B6D4P2 | 212-2655-001 | CABLE, W 21, BALLAST INTERFACE |
| W 21_1 | B6D J15 | B6D4J3 | 212-2655-001 | CABLE, W 21, BALLAST INTERFACE |
| W 21_3 | B6D J15 | B6D4P1 | 212-2655-001 | CABLE, W 21, BALLAST INTERFACE |
| W 23 | B6BP3 | B9BP7 | 212-1561-010 | CABLE, W 23, 24V DC |
| W 24 | B6DP7 | B6AP5 | 212-2196-001 | CABLE, W 24.ILLUM OPT INTF |
| W 25_1 | B6DP15 | B6AP2 | 212-2198-002 | CABLE, W 25, BALLAST INTERFACE |
| W 25_2 | B6DP15 | B6AP7 | 212-2198-002 | CABLE, W 25, BALLAST INTERFACE |
| W 26 | B6AP4 | B6CP1 | 212-2199-001 | CABLE, W 26, AUX ILLUM RFID |
| W 27 | B6D3J5 | B6D J7 | 212-2657-501 | CABLE, W 27, FLEX AUX ILLUM |
| W 28 | B6D1P1 | B6D3P1 | 212-2658-001 | CABLE, W 28, HOME POS. SENSOR |
| W 29 | B6D2P1 | B6D3P2 | 212-2658-001 | CABLE, W 29, HOME POS. SENSOR |
| W 30 | MSFAN | B6D3P4 | 212-2656-001 | CABLE, W 30, STEPPER MOTOR |
| W 31 | M6FAN | B6D3P3 | 212-2656-001 | CABLE, W 31, STEPPER MOTOR |
| W 32 | B6D3P6 | B6D5GND | 212-2623-001 | CABLE, W32, THERMAL SENSOR |
| W 33 | M4FAN | B6AP6 | 212-2267-003 | CABLE, W33, FAN BALLAST |
| W 34 | B6CP2 | FD1P1 | 212-2266-001 | CABLE, W34, FIBER DETECT |
| W 35 | B6CP3 | FD2P1 | 212-2266-001 | CABLE, W35, FIBER DETECT |
| W 36 | B6BPMH1 | B13SG | 212-2223-004 | CABLE, W36, GROUND |
| W 37 | B3P3 | B15GND2 | 212-2832-001 | CABLE, W 37, GROUND |
| W 38 | B15GND | B12SG | 212-2833-001 | CABLE, W38, GROUND |
| W 39 | B8E1 | B8E2 | 212-2957-001 | CABLE, W39, GND, AUX ILLUM EJCTR |
| W 40 | B9BP3 | B9AP2 | 212-2220-002 | CABLE,W40,DC POWER BLACK |
| W 41 | B5BP2 | LI0 | 212-2685-001 | CABLE,LIO |
| W 42 | B5BP3 | KEYSW ITCH | 212-2686-001 | CABLE, ASSY, KEYSW ITCH |
| W 43 | B5BJ2 | ESTOP | 212-2663-001 | CABLE, ASSY, ESTOP |



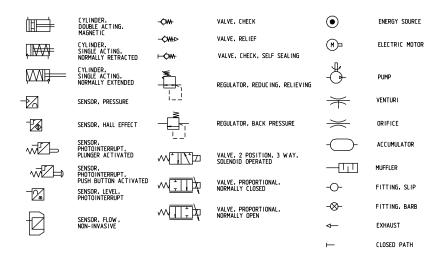


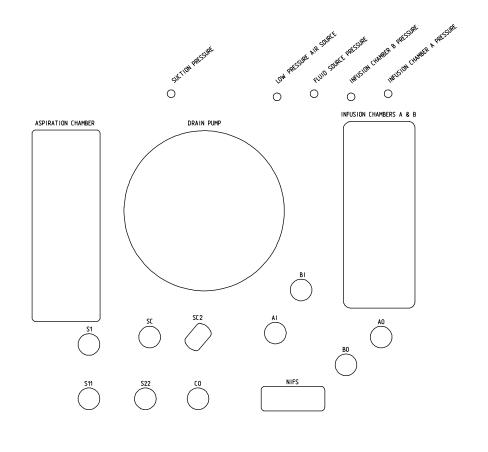






| COMPONENT DESCRIPTION TTNN_FF LL | | | | | | | | |
|----------------------------------|-----------|----------|------------|---------------|--|--|--|--|
| TT, TYPE | LAST USED | NOT USED | NN, NUMBER | FF, FUNCTION | LL, LOCATION | | | |
| AC = ACCUMULATOR | AC4 | | 1 | F = FLOW | A [1] [0] = INFUSION CIRCUIT A [IN] [OUT] | | | |
| CV = CHECK VALVE | CV1 | | 2 | I = ISOLATION | B [I] [O] = INFUSION CIRCUIT B [IN] [OUT] | | | |
| CY = CYLINDER | CY12 | | 3 | IN = INTAKE | BA = INFUSION BACKUP | | | |
| DS = INTERRUPT SENSOR | DS7 | | ETC | L = LEVEL | CO = IRRIGATION | | | |
| ES = HALL EFFECT SENSOR | ES1 | | | P = PRESSURE | C [L] [U] [R] = CASSETTE [LWR] [UPR] [RELEASE] | | | |
| L = SOLENOID VALVE | L20 | | | S = POSITION | D = DRAIN PUMP | | | |
| MF = MUFFLER | MF2 | | | V = VENT | E = SOURCE PRESSURIZATION | | | |
| MT = MEASURING TRANSDUCER | MT12 | | | | F = F/AX | | | |
| P = PUMP | P2 | | | | I = INFUSION SUPPLY | | | |
| PV = PROPORTIONAL VALVE | PV9 | | | | L [0] [C] = LATCH [OPEN] [CLOSED] | | | |
| RG = REGULATOR | RG5 | | | | N = NIFS | | | |
| RO = RESTRICTIVE ORIFICE | R02 | | | | P = PINCHER SUPPLY | | | |
| RV = RELIEF VALVE | RV3 | | | | R = REFLUX | | | |
| T = TUBING T7 | | | | S = SUCTION | | | | |
| TP = TEST POINT | TP5 | | | | SC = CROSS CONNECTION | | | |
| V = VENTURI | V1 | | | | SY = SYSTEM SUPPLY | | | |





FACEPLATE INTERFACE

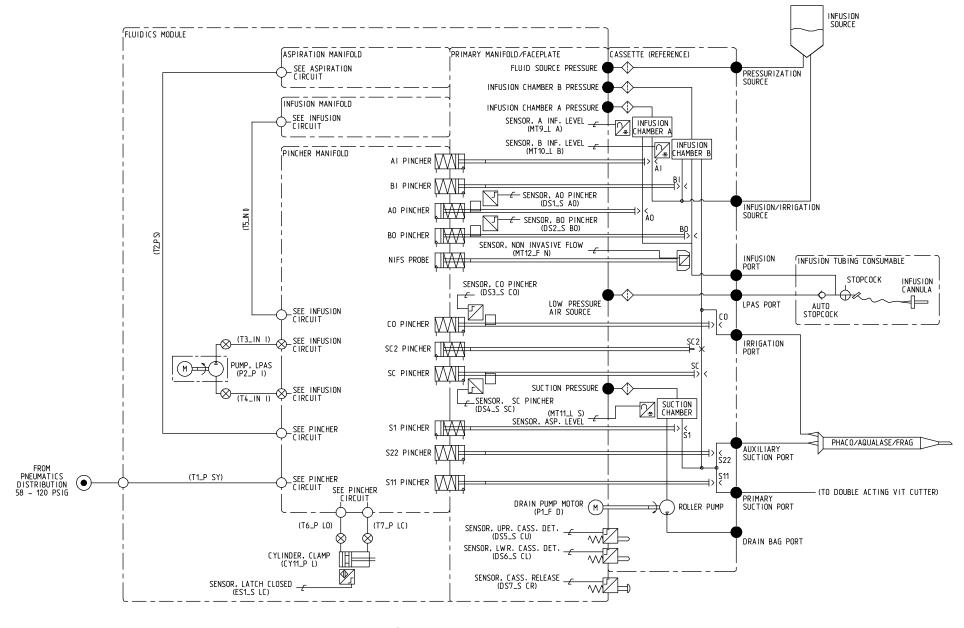
212-1445-801

Fluidics Diagram (1 of 5)

8065751153

5 9





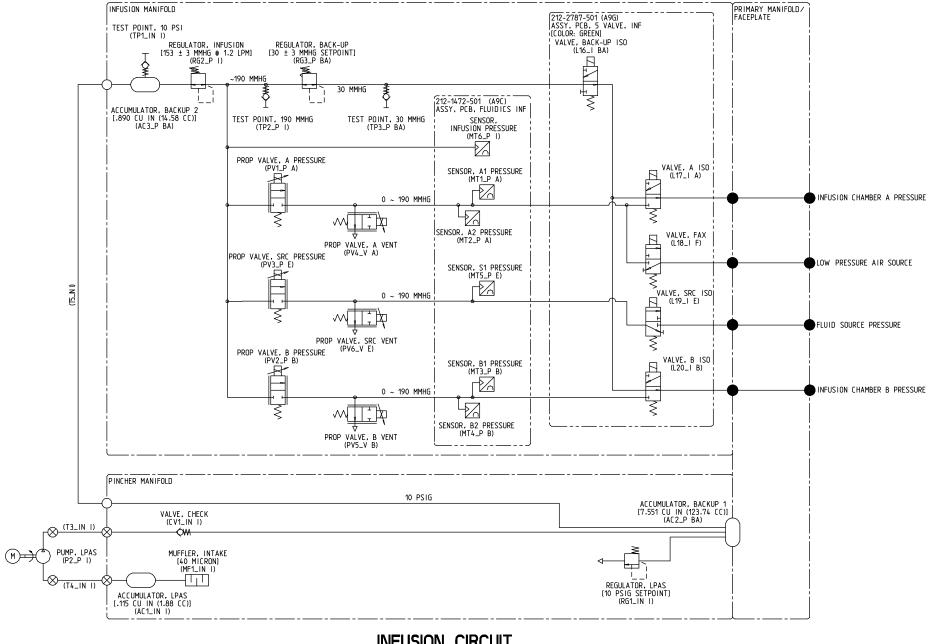
EXTERNAL CONNECTIONS

212-1445-801

Fluidics Diagram (2 of 5)

8065751153



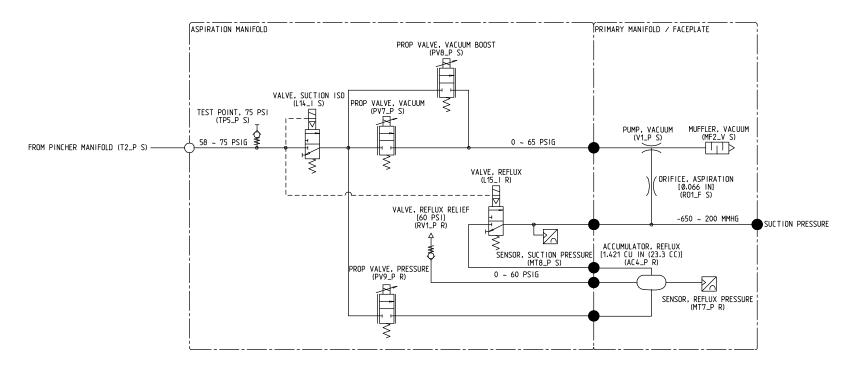


INFUSION CIRCUIT

212-1445-801

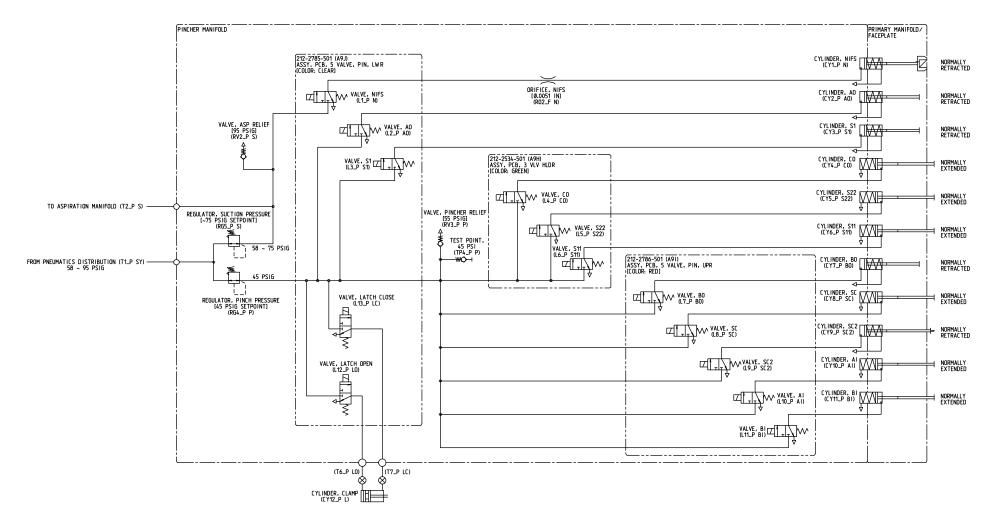
Fluidics Diagram (3 of 5)





ASPIRATION CIRCUIT

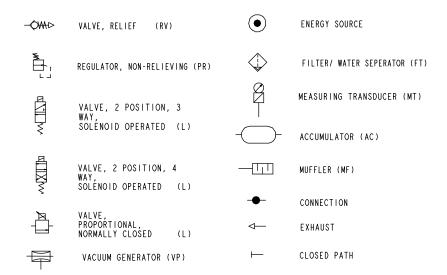


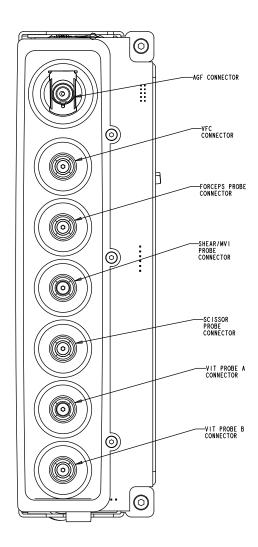


PINCHER CIRCUIT

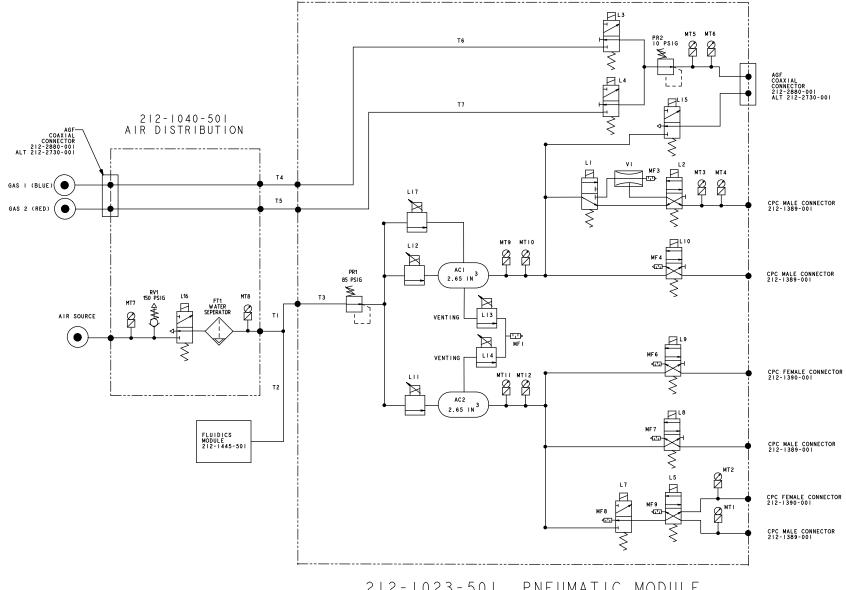


| COMPONENT TYPE | QTY USED |
|---------------------------|----------|
| AC = ACCUMULATOR | 2 |
| L = SOLENOID VALVE | 16 |
| MF = MUFFLER | 9 |
| MT = MEASURING TRANSDUCER | 12 |
| PR = PRESSURE REGULATOR | 2 |
| RV = RELIEF VALVE | 1 |
| T = TUBING | 7 |
| FT = FILTER | |
| VP = VACUUM PUMP | |



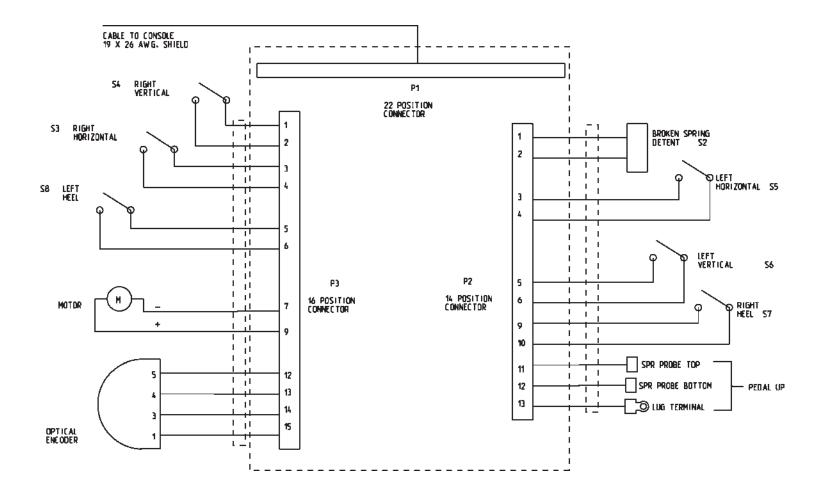






212-1023-501 PNEUMATIC MODULE





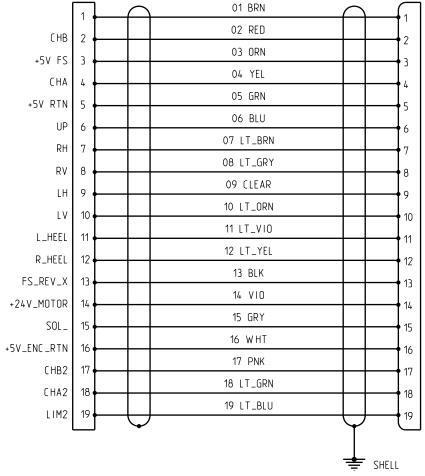
212-1083-501

Footswitch

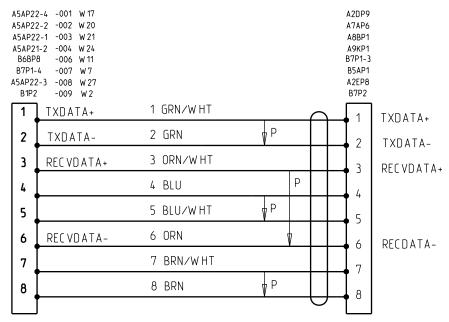


LOWER FOOTSWITCH CONNECTION
B2J1

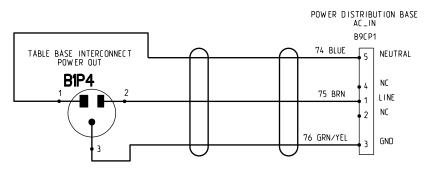
FOOTSWITCH INTERCONNECT
TABLE BASE
B1P1



W01 - Base 212-1678-001 Cable, Footswitch



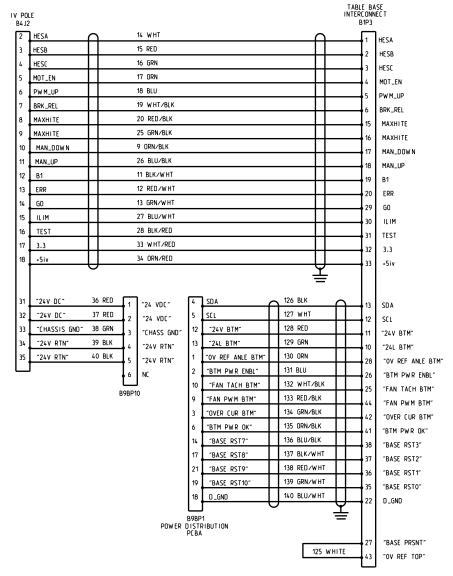
W17, 20, 21, 24, 27 - Console 212-1560-xxx Cable, Ethernet W02, 07, 11 - Base



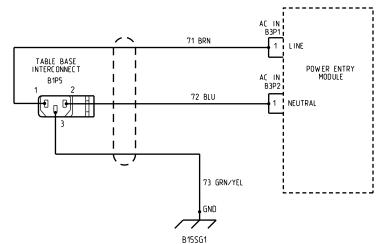
W04 - Base 212-1681-001 Cable, Power Out

Cables, Interconnect, Constellation Vision System

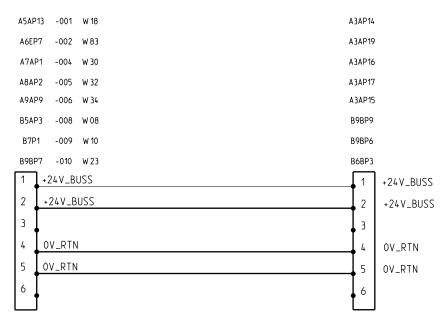




W03 - Base 212-1680-001 Cable, Data IO

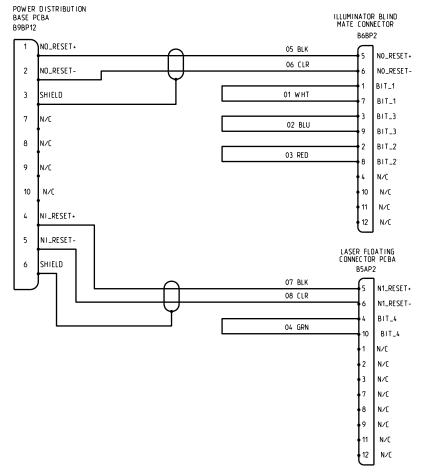


W05 - Base 212-2201-001 Cable, AC Power In

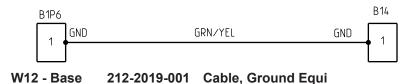


W18, 30, 32, 34, 83 - Console 212-1561-xxx Cable, 24V DC W08, 10, 23 - Base





W09 - Base 212-1689-001 Cable, Slot ID



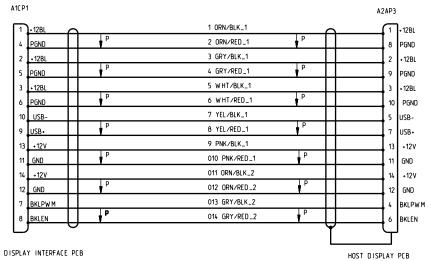
A1AP1 A2AP2 Rx00-01 ORN/BLK_1 LVDS_A0-02 ORN/RED_1 Rx00+ LVDS_A0+ Rx01-03 GRY/BLK_1 LVDS_A1-04 GRY/RED_1 Rx01+ LVDC_A1+ 05 WHT/BLK_1 Rx02-LVDS_A2-06 WHT/RED_1 Rx02+ LVDS_A2+ 07 YEL/BLK_1 RxOC -LVDS_AC -RxOC+ 08 YEL/RED_1 LVDS_AC+ Rx03-09 PNK/BLK_1 LVDS_A3-Rx03+ 10 PNK/RED_1 LVDS_A3+ RxE0-11 ORN/BLK_2 VDS_B0-12 ORN/RED_2 RxE0+ LVDS_B0 RxE1-13 GRY/BLK_2 LVDS_B1-RxE1• 14 GRY/RED_2 LVDS_B1+ 15 WHT/BLK_2 RxE2-LVDS_B2-RxE2+ 16 WHT/RED_2 LVDS_B2+ RxEC -17 YEL/BLK_2 LVDS_BC-18 YEL/RED_2 RxEC+ LVDS_BC+ 22 RxE3-19 PNK/BLK_2 LVDS_B3-23 RxE3+ 20 PNK/RED_2 LVDS_B3+ 21 ORN/BLK_3 GND GND 25 NC 22 ORN/RED_3 LCDVCC 23 GRY/BLK_3 26 NC GND 27 NC 24 GRY/RED_3 LCDVCC 25 WHT/BLK_3 GND GND 26 WHT/RED_3 VCC 28 LCDVCC GND VCC HOST DISPLAY PCB GND VCC

W12 - Console 212-1871-001 Cable, Video, LVDS

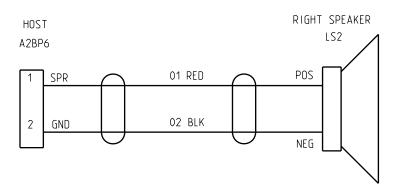
8065751153 5.19

LCD

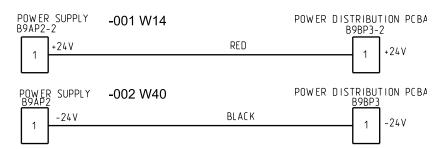




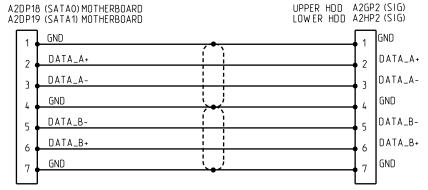
W13 - Console 212-1872-001 Cable, Interface, Display



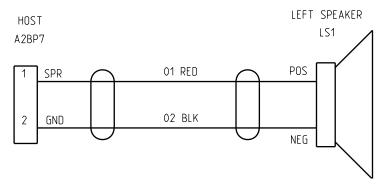
W14 - Console 212-1557-001 Cable, Speaker, Right



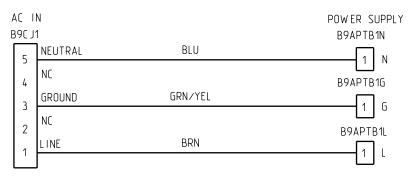
W14, 40 - Base 212-2220-xxx Cable, DC Power



W61, 62 - Console 212-2383-001 Cable, SATA SIG

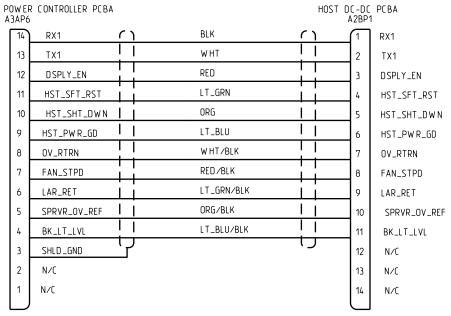


W15 - Console 212-1557-002 Cable, Speaker, Left

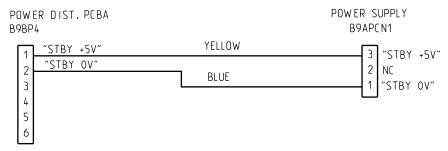


W15 - Base 212-2221-001 Cable, AC In





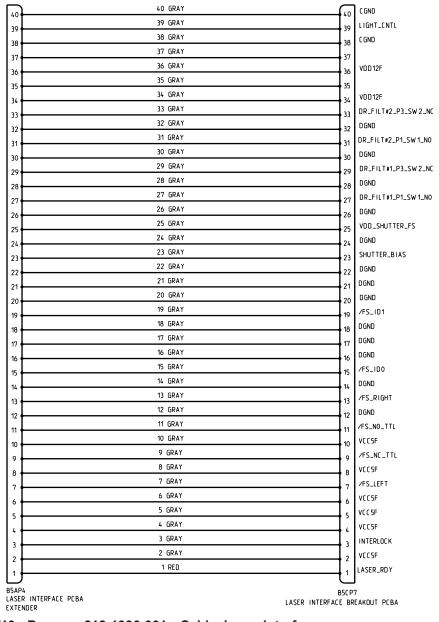
W16 - Console 212-1559-001 Cable, Host Interface



W16 - Base 212-2222-001 Cable, PS Control

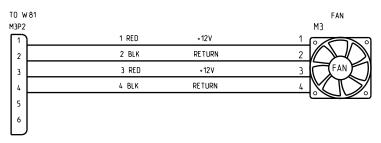


W120, 121 - Console 212-2223-XXX Cable, Ground W17, 36 - Base

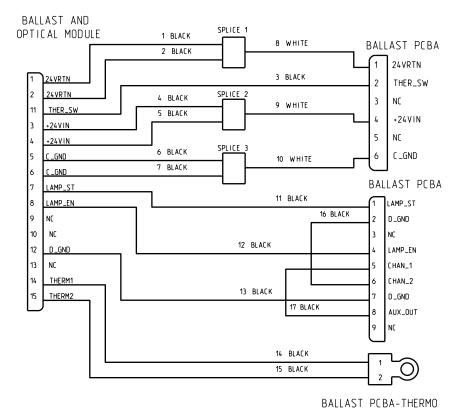


W19 - Base 212-1996-001 Cable, Laser Interface

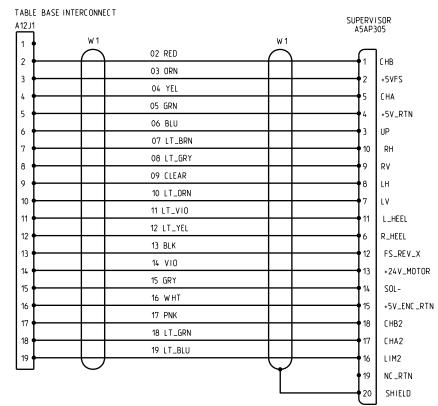




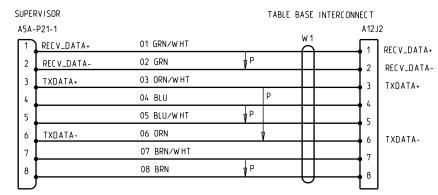
W29 - Console 212-2268-002 Cable, Fan W20 - Base



W117 - Console 212-2655-001 Cable, Ballast Interface W21 - Base

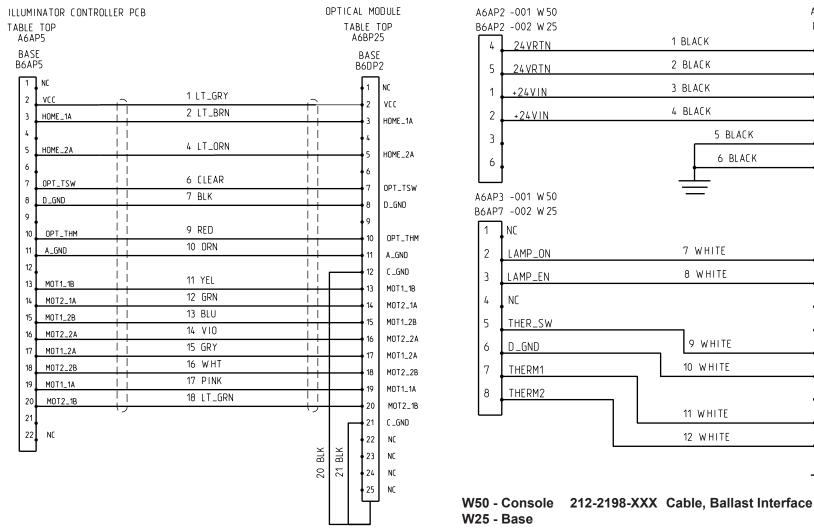


W22 - Console 212-1565-001 Cable, Footswitch



W23 - Console 212-1566-001 Cable, Ethernet to Base





W51 - Console 212-2196-001 Cable, Illum Opt Intfc

W24 - Base

Cables, Interconnect, Constellation Vision System

A6BP15

B6DP1

5 BLACK

6 BLACK

24VRTN

24VRTN

+24VIN

+24VIN

C_GND

C _GND

LAMP_ON

LAMP_EN

THER_SW

D_GND

THERM1

THERM2

NC

NC

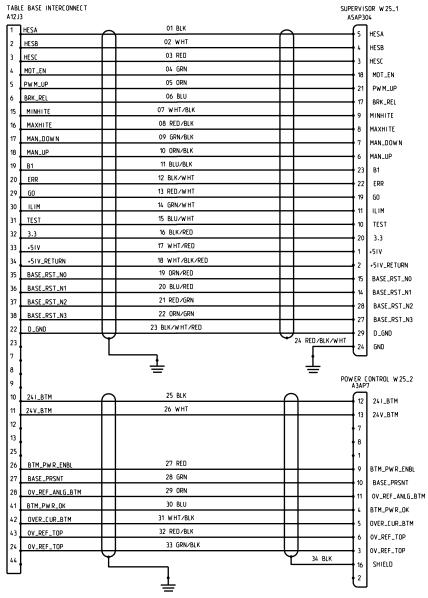
NC

10

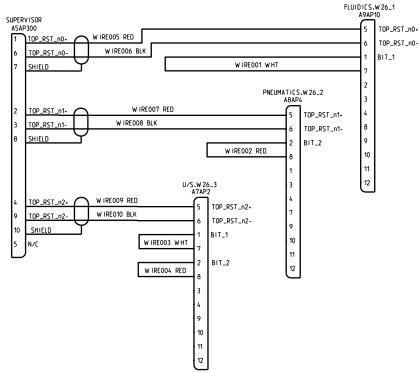
13

8065751153 5.23

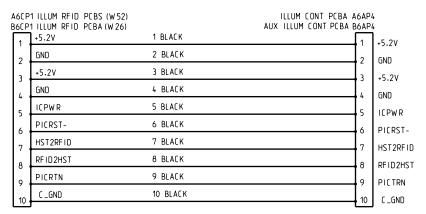




W25 - Console 212-1568-001 Cable, Data IO



W26 - Console 212-1569-001 Cable, Slot ID

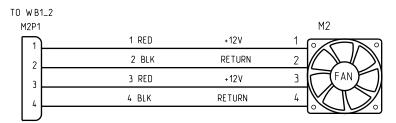


W52 - Console 212-2199-001 Cable, Illum RF ID INTFC W26 - Base



| REFERENCE I | | |
|-------------|-------|---------------|
| PIN T | O PIN | |
| B6D3J5 | B6DJ7 | |
| 1 | 14 | MOTOUT2_1A |
| 2 | 2 | +5V |
| 3 | 15 | MOTOUT1_2B |
| 4 | 3 | HOMESEN1A_IN |
| 5 | 16 | MOTOUT2_2A |
| 6 | 4 | HOMESEN1B_IN |
| 7 | 17 | MOTOUT1_2A |
| 8 | 5 | HOMESEN2A_IN |
| 9 | 18 | MOTOUT2_2B |
| 10 | 6 | HOMESEN2B_IN |
| 11 | 19 | MOTOUT1_1A |
| 12 | 7 | OPT_THERMALSW |
| 13 | 20 | MOTOUT2_1B |
| 14 | 8 | DGND |
| 15 | 21 | CGND 5 |
| 16, 17 | 22 | C GND |
| 18 | 10 | OPT_TEMP |
| 19 | 11 | AGND |
| 20 | 12 | CGND 5 |
| 21 | 25 | C GND |
| 22 | 13 | MOTOUT1_1B |
| NC | 23 |] |
| NC | 24 |] |
| NC | 1 |] |
| NC | 9 |] |

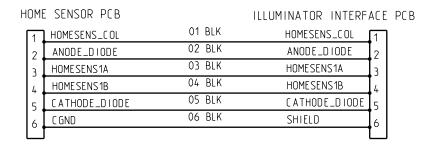
W27 - Base 212-2657-001 Cable, Flex Aux Illum



W28 - Console 212-2267-002 Cable, Fan

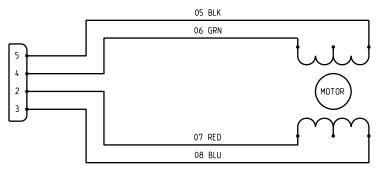
AUXILIARY ILLUMINATOR CONTROL PCBA B6AP8 1 RED 1 2 BLK RETURN 2 3 BLK RETURN 4 FAN 4 RED +12V 3

W33 - Base 212-2267-003 Cable, Fan Ballast



W115, 116 - Console 212-2658-001 Cable, Home Pos Sensor W28, 29 - Base





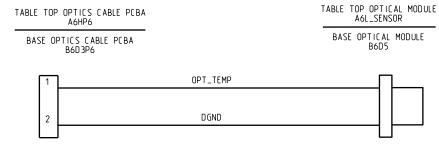
W113, 114 - Console 212-2658-001 Cable, Stepper Motor W30, 31 - Base

Cables, Interconnect, Constellation Vision System

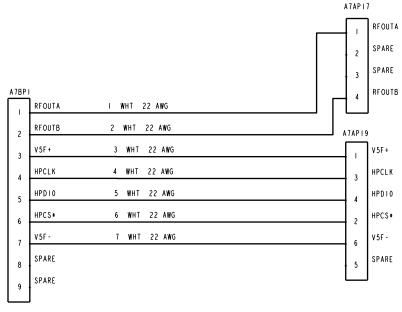




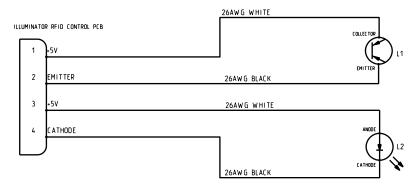
W31 - Console 212-2269-001 Cable, U/S Ring Illlum



W102 - Console 212-2623-001 Cable, Thermistor, Illum W32 - Base

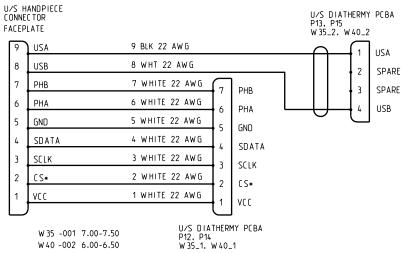


W33 - Console 212-2270-001 Cable, Aqua



W118, 119 - Console 212-2266-001 Cable, Fiber Detect W34, 35 - Base



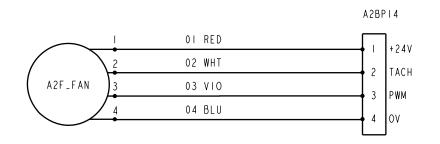


W35, 40 - Console 212-2271-001 Cable, U/S

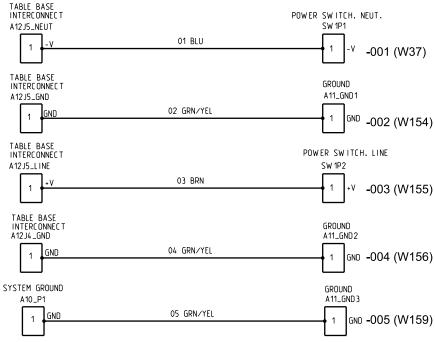


TABLE BASE INTERCONNECT, W 36_2

W36 - Console 212-1579-001 Cable, AC Output



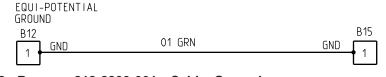
W39 - Console 212-2332-001 Cable, Host Fan



W37,154,155,156,159 - Console 212-1580-XXX Cable, AC Output



W37 - Base 212-2832-001 Cable, Ground



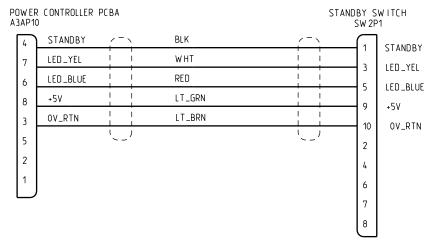
W38 - Base 212-2833-001 Cable, Ground

Cables, Interconnect, Constellation Vision System

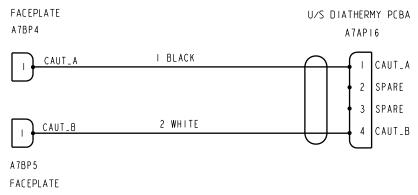




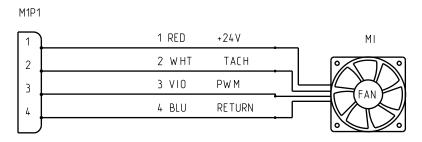
W150 - Console 212-2957-XXX Cable, Gnd, Illum Ejctr W39 - Base



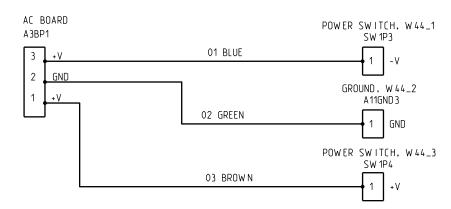
W41 - Console 212-1584-001 Cable, Standy Sw



W42 - Console 212-2273-001 Cable, Diathermy



W43 - Console 212-1586-001 Cable, Fan

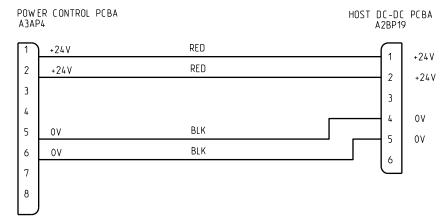


W44 - Console 212-1587-001 Cable, AC In Breaker

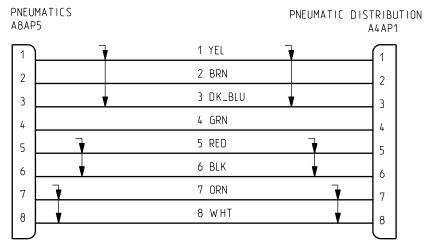


W45, 153 - Console 212-2274-XXX Cable, Fan

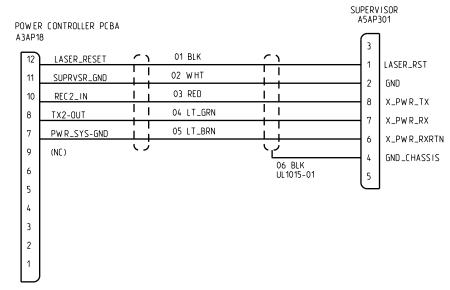




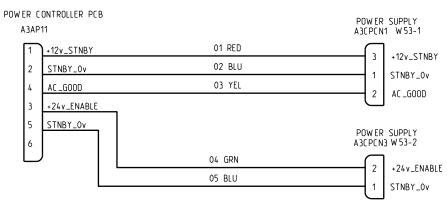
W46 - Console 212-1589-001 Cable, 24 VDC



W47 - Console 212-2062-001 Cable, Pneu Dist



W48 - Console 212-2063-001 Cable, Supervisor Inf

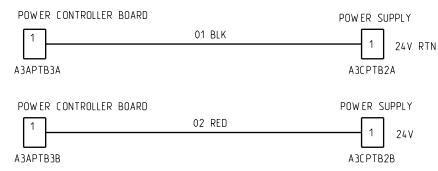


W53 - Console 212-2257-001 Cable, Pwr Sup Cntrl

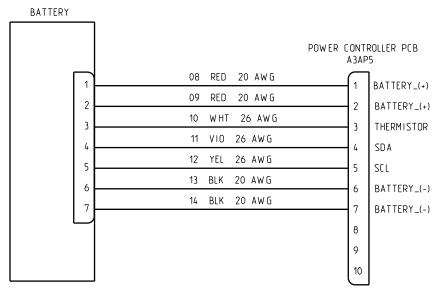


| REFERENCE I |] | |
|-------------|--------|---------------|
| PIN T |] | |
| A6HP5 | A6BJ25 | |
| 1 | 14 | MOTOUT2_1A |
| 2 | 2 | +5V |
| 3 | 15 | MOTOUT1_2B |
| 4 | 3 | HOMESEN1A_IN |
| 5 | 16 | MOTOUT2_2A |
| 6 | 4 | HOMESEN1B_IN |
| 7 | 17 | MOTOUT1_2A |
| 8 | 5 | HOMESEN2A_IN |
| 9 | 18 | MOTOUT2_2B |
| 10 | 6 | HOMESEN2B_IN |
| 11 | 19 | MOTOUT1_1A |
| 12 | 7 | OPT_THERMALSW |
| 13 | 20 | MOTOUT2_1B |
| 14 | 8 | DGND |
| 15 | 21 | C GND |
| 16. 17 | 22 | C GND |
| 18 | 10 | OPT_TEMP |
| 19 | 11 | AGND |
| 20 | 12 | C GND |
| 21 | 25 | C GND |
| 22 | 13 | MOTOUT1_1B |
| NC | 23 |] |
| NC | 24 | |
| NC | 1 | |
| NC | 9 | J |

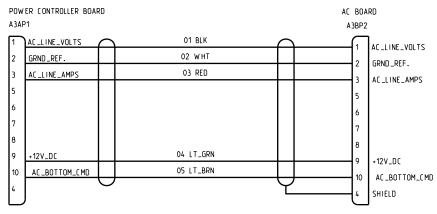
W49 - Console 212-2531-001 Cable, Circuit, Flex Illum



W54 - Console 212-2258-001 Cable, DC Power, Main

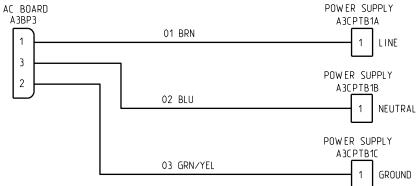


W55 - Console 212-2227-001 Battery, Power Module

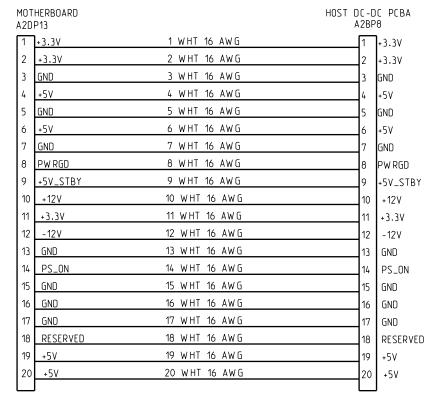


W56 - Console 212-2260-001 Cable, AC Control

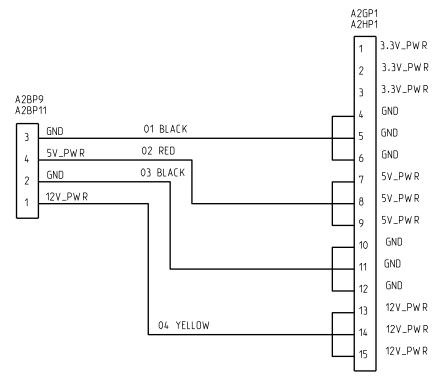




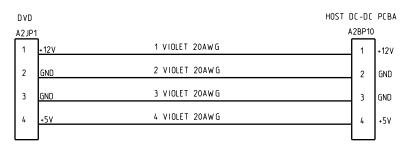
W57 - Console 212-2261-001 Cable, AC Power



W58 - Console 212-2381-001 Cable, ATX Power



W59, 60 - Console 212-2382-001 Cable, SATA Power



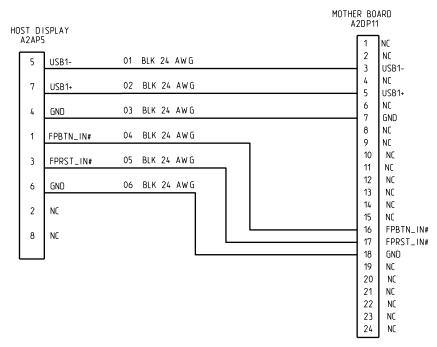
W63 - Console 212-2384-001 Cable, DVD Power

5.31

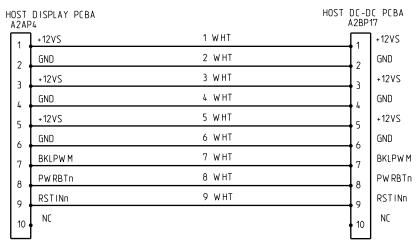


| | TABLE: CONNECTOR PIN OUT | | | | | | |
|---|--------------------------|----------------|----------------------|------------------|----------------|--|--|
| CONNECTOR PIN NO. | CONDUCTOR NO. | SIGNAL NAME | CONNECTOR PIN NO. | CONDUCTOR NO. | SIGNAL NAME | | |
| 1 | 1 | RESET | 2 | 3 | GROUND | | |
| 3 | 5 | DATA 7 | 4 | 7 | DATA 8 | | |
| 5 | 9 | DATA 6 | 6 | 11 | DATA 9 | | |
| 7 | 13 | DATA 5 | 8 | 15 | DATA 10 | | |
| 9 | 17 | DATA 4 | 10 | 19 | DATA 11 | | |
| 11 | 21 | DATA 3 | 12 | 23 | DATA 12 | | |
| 13 | 25 | DATA 2 | 14 | 27 | DATA 13 | | |
| 15 | 29 | DATA 1 | 16 | 31 | DATA 14 | | |
| 17 | 33 | DATA 0 | 18 | 35 | DATA 15 | | |
| 19 | 37 | GROUND | 20 | 39 | KEY | | |
| 21 | 41 | DMARQ | 22 | 43 | GROUND | | |
| 23 | 45 | DIOW - | 24 | 47 | GROUND | | |
| 25 | 49 | DIOR- | 26 | 51 | GROUND | | |
| 27 | 53 | IORDY | 28 | 55 | CSEL | | |
| 29 | 57 | DMARK- | 30 | 59 | GROUND | | |
| 31 | 61 | INTRQ | 32 | 63 | 10C S16- | | |
| 33 | 65 | DA1 | 34 | 67 | PDIAG-(GND) | | |
| 35 | 69 | DAO | 36 | 71 | DA2 | | |
| 37 | 73 | CS1FX- | 38 | 75 | CS3FX- | | |
| 39 | 77 | DASP- | 40 | 79 | GROUND | | |
| ALL EVEN CABLE CONDUCTOR NUMBERS ARE GROUND | | | | | | | |

W64 - Console 212-2385-001 Cable, IDE Signal

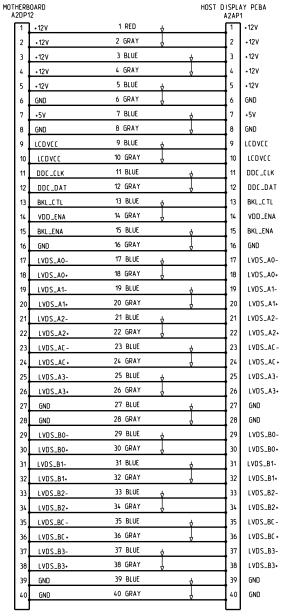


W66 - Console 212-2387-001 Cable, Front Panel USB

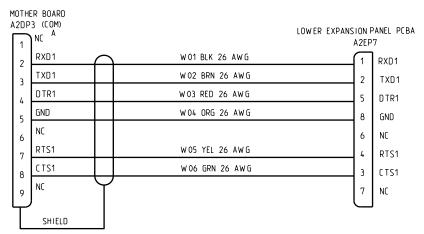


W68, 79 - Console 212-2389-001 Cable, Power Front Panel

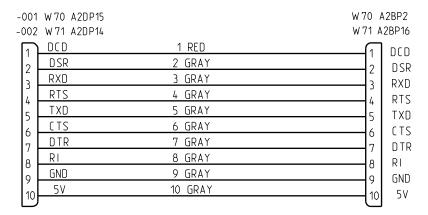




W67 - Console 212-2388-001 Cable, LVDS Signal

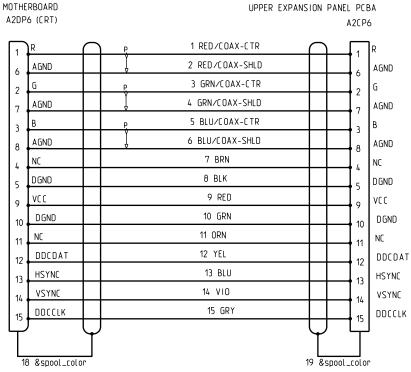


W69 - Console 212-2390-001 Cable, Serial, IO Ext

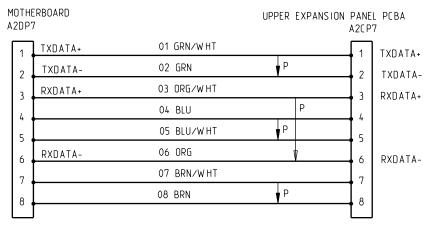


W70, 71 - Console 212-2391-XXX Cable, Serial, Ext

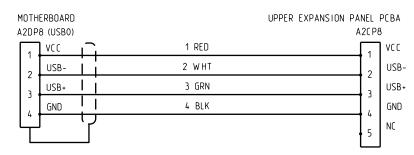




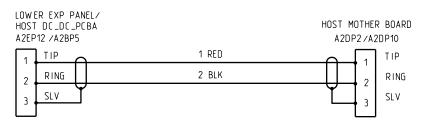
W72 - Console 212-2392-001 Cable, VGA, Ext



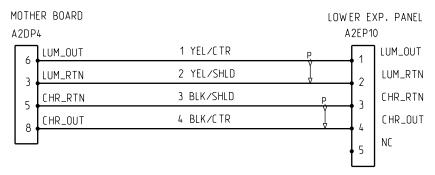
W73 - Console 212-2393-001 Cable, Ethernet Extn



W74 - Console 212-2394-001 Cable, USB, Port Ext

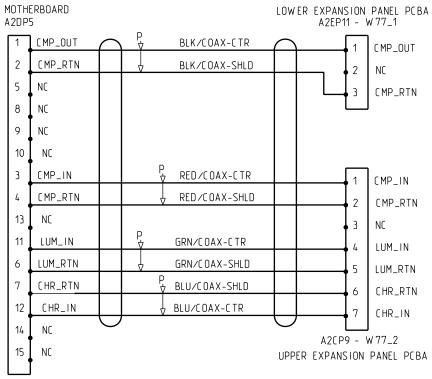


W75, 76 - Console 212-2395-001 Cable, Audio Ext



W78 - Console 212-2397-001 Cable, S-Video, Out Ext



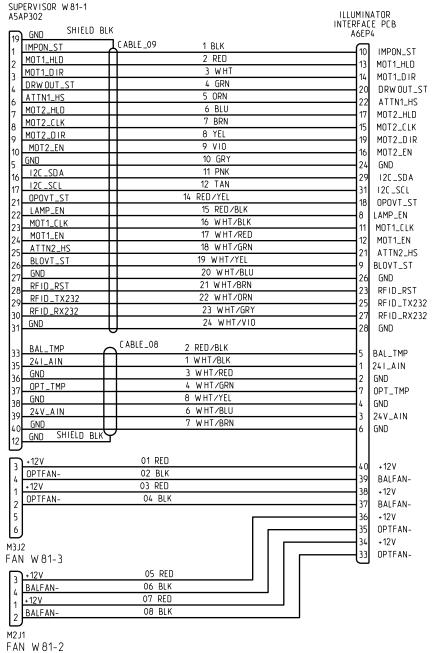


W77 - Console 212-2396-001 Cable, VOM Signal, Ext

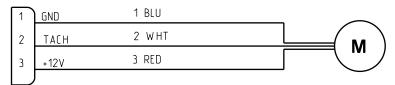
| | HOST DC-DC PCBA LOWER EXPANSION A2BP13 | | | | N PANEL PCBA A2EP9 | |
|----|--|----------|--|------|-----------------------|--|
| 1 | +5V | 1 WHITE | | 1 | +5V | |
| 7 | LSR_RST | 2 WHITE | | 2 | LSR_RST | |
| 2 | GND | 3 WHITE | | 3 | GND | |
| 8 | DCD | 4 WHITE | | 4 | DCD | |
| 3 | RxD | 5 WHITE | | 5 | RxD | |
| 9 | TxD | 6 WHITE | | 6 | TxD | |
| 4 | DTR | 7 WHITE | | 7 | DTR | |
| 10 | GND | 8 WHITE | | 8 | GND | |
| 5 | DSR | 9 WHITE | | 9 | DSR | |
| 11 | RTS | 10 WHITE | | 10 | RTS | |
| 6 | CTS | 11 WHITE | |] 11 | CTS | |
| 12 | R1 | 12 WHITE | | 12 | R1 | |
| | | | |] 13 | | |
| | | | | 14 | | |
| | | | | | | |

W80 - Console 212-2399-001 Cable, Expansion Pwr Sgnl

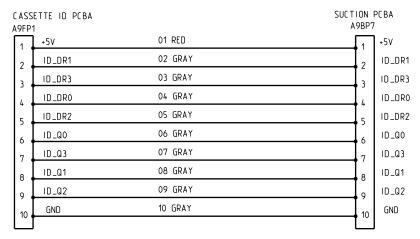




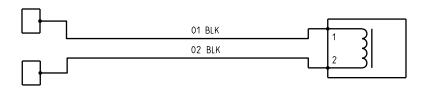
A9AP7/A9AP4



W84, 160 - Console 212-2937-001 Cable, Fluidics Fan



W85 - Console 212-2293-001 Cable, Cassette ID



W89, 91 - Console 212-2633-001 Cable, Prop Valve

W81 - Console 212-2499-001 Cable, I/O Control

Cables, Interconnect, Constellation Vision System

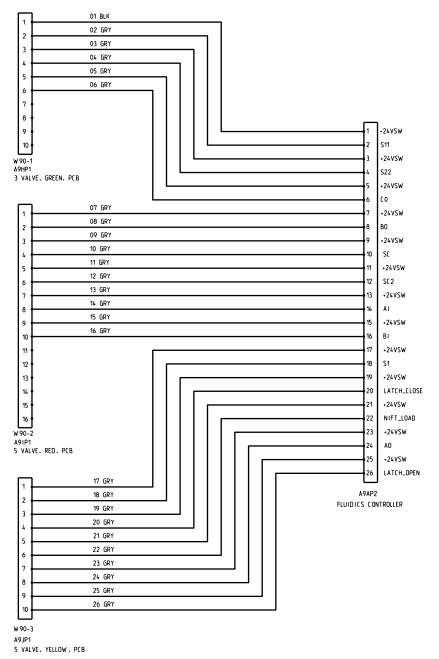


| C ID_ENO | 01 RED | C 612 512 | 1 +24VSW | 01 RED | |
|-----------|---------|-------------|-----------------------------|--------------------|-------------|
| | | 1 CID_ENO | 2 ISO_FAX | 02 GRAY | ; |
| C ID_EN3 | 02 GRAY | 2 CID_EN | 3 +24VSW | 03 GRAY | : |
| C ID_EN1 | 03 GRAY | | 4 I <u>SO_A</u> | 04 GRAY | <i>'</i> |
| CID_EN2 | 04 GRAY | | | 05 GRAY | |
| CID_AO | 05 GRAY | | 6 I <u>SO_SRC</u> | 06 GRAY 07 GRAY | |
| CID_A2 | 06 GRAY | L CID A2 | 7 → ±24VSW | O8 GRAY | |
| CID_A1 | 07 GRAY | ٥ ا دا١ ١ | 8 1 <u>SO_B</u> • +24VSW | 09 GRAY | |
| CID_A3 | 08 GRAY | 7 CID_A3 | 10 ISO_BKUP | 10 GRAY | 1 |
| PS30 | 09 GRAY | ° | 11 AGND | 11 GRAY | |
| PS100 | 10 GRAY | 9 PS30 | 12 AGND | 12 GRAY | |
| | | 10 PS100 | 13 AGND | 13 GRAY | |
| REF | 11 GRAY | 11 REF | 14 AGND | 14 GRAY | · |
| AGND | 12 GRAY | 12 AGND | 15 AGND | 15 GRAY | · |
| +12VA | 13 GRAY | 13 +12VA | 16 • 24VSW | 16 GRAY 17 GRAY | |
| +12VA | 14 GRAY | 14 +12VA | 17 PPV_VB | 18 GRAY | |
| AGND | 15 GRAY | 15 AGND | 18 | 19 GRAY | <u>†</u> |
| CASS_IN | 16 GRAY | ا د۵۶۷ ۱۱ | N .21.VSW | 20 GRAY | |
| C ASS_REL | 17 GRAY | 10 CASS D | 20 | 21 GRAY | |
| LATCH | 18 GRAY | 1/] | 22 +24VSW | 22 GRAY | |
| +24VSW | 19 GRAY | 18 LATCH | 23 PPV_VS | 23 GRAY | : |
| | | 19 +24VSW | 24 + +24VSW | 24 GRAY | : |
| PPV_VBST | 20 GRAY | 20 PPV_VB | 25 1 | 25 GRAY | |
| +24VSW | 21 GRAY | 21 +24VSW | 1 1 | 26 GRAY | <u></u> |
| PPV_VAC | 22 GRAY | | | 27 GRAY 28 GRAY | |
| +24VSW | 23 GRAY | 23 +24VSW | | 29 GRAY | |
| PPV_PRES | 24 GRAY | 24 PPV_PR | 29 AGND 30 +12VA | 30 GRAY | |
| +5VA | 25 GRAY | +5VA | 30 +12VA +12VA | 31 GRAY | |
| +5VA | 26 GRAY | 25 L5VA | 32 AGND | 32 GRAY | |
| AGND | 27 GRAY | ZO | 33 AGND | 33 GRAY | |
| AGND | 28 GRAY | 27 | 34 PS_REF | 34 GRAY | ; |
| DGND | 29 GRAY | 28 AGND | 35 PS_B2 | 35 GRAY | |
| | | | 36 PS_B1 | 36 GRAY | |
| +24VSW | 30 GRAY | 30 +24VSW | | 37 GRAY 38 GRAY | |
| SMC_SUC | 31 GRAY | 31 SMC_SU | l nc x2 | 39 GRAY | <u>-</u> |
| +24VSW | 32 GRAY | 32 +24VSW | 7 PS_A2 PS_A1 | 40 GRAY | |
| SMC _RFX | 33 GRAY | 33 SMC_RF | 1 *• ¥ | | |

W86 - Console 212-2291-001 Cable, Suction Control

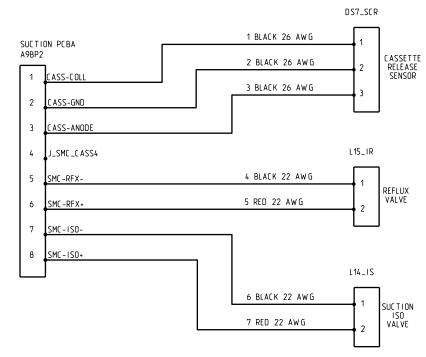
Cables, Interconnect, Constellation Vision System





01 BLK 1 1 2

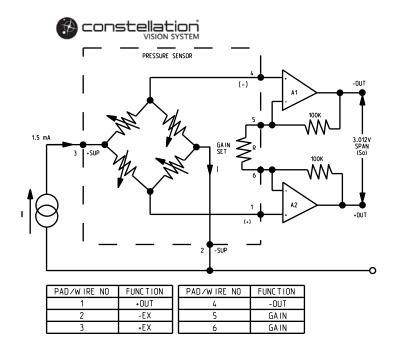
W92, 109, 110, 111 - Console 212-2632-001 Cable, Prop Valve



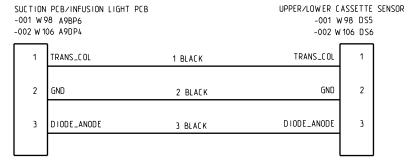
W95 - Console 212-2294-001 Cable, SMC Cass-Rel

Cables, Interconnect, Constellation Vision System

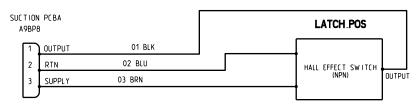
W90 - Console 212-2288-001 Cable, X Valve



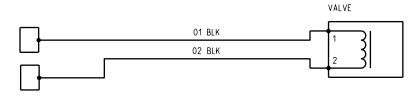
W96 - Console 212-2580-001 Sensor, Pressure, ABS 30 W97 - Console 212-2579-001 Sensor, Pressure, ABS 100



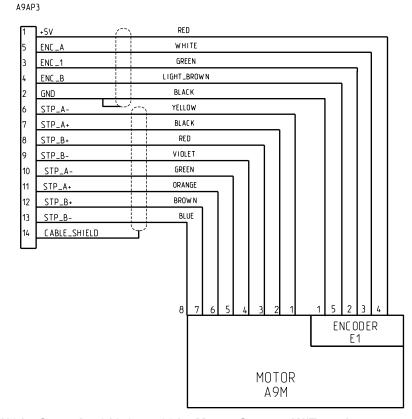
W98, 106 - Console 212-2292-xxx Cable, Cass In Sensor



W99 - Console 212-2272-001 Cable, Latch Pos

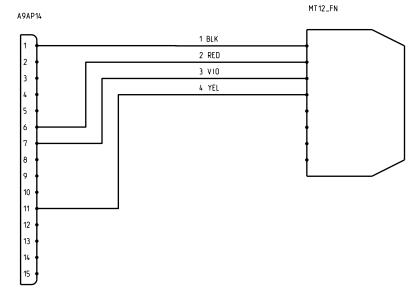


W100, 107, 108 - Console 212-2634-001 Cable, Prop Valve, LW

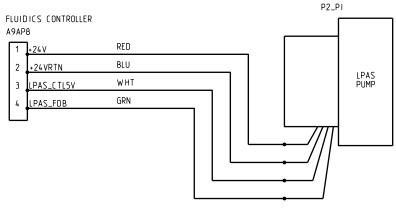


W101 - Console 212-2575-001 Motor, Stepper W/Encoder

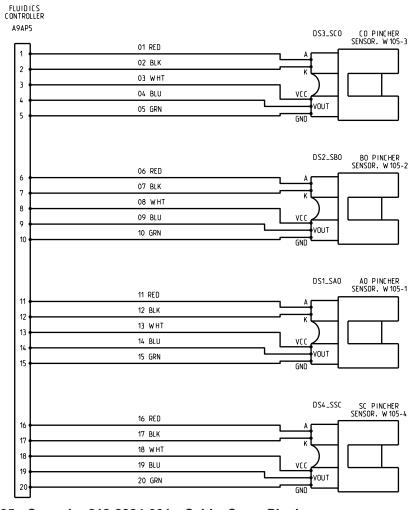




W103 - Console 212-2308-001 Cable, Sensor, Flow



W104 - Console 212-2290-001 Cable, LPAS Pump

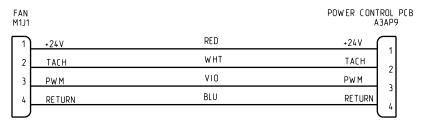


W105 - Console 212-2284-001 Cable, Sens, Pincher

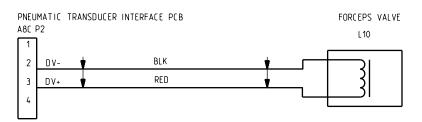


| A8AP7 | PNEUMATICS PCBA | PNEUMATICS TRANSDU | UCER A8CP1 |
|-------|------------------|----------------------|----------------|
| [1] | AGF1 | 01 RED INTERFACE PCB | П |
| 2 | AGF2 | 02 GRY | |
| 3 | VITB | O3 GRY | 3 |
| 4 | VFC1 | 04 GRY | 4 |
| 5 | VITA | 05 GRY | 5 |
| 6 | VFC 2 | 06 GRY | 6 |
| 7 | BIAS_REF | 07 GRY | , |
| 8 | CURRENT_REF | 08 GRY | |
| 9 | GND | 09 GRY | ٦, ا |
| 10 | GND | 10 GRY | 10 |
| 11 | GND | 011 GRY | 11 |
| 12 | GND | 012 GRY | 12 |
| 13 | GND | 013 GRY | 13 |
| 14 | FORCEP+ | 014 GRY | ۱٬۰ ۱٬۱ |
| 15 | | 015 GRY | 1 " |
| 16 | FORCEP- AGF1+ | 016 GRY | 15 |
| 17 | AGF1- | 017 GRY | 16 |
| 1 1 | | 018 GRY | 17 |
| 18 | AGF2+ | 019 GRY | 18 |
| 1 "1 | AGF2- | 020 GRY | 19 |
| 20 | AGFAIR+ | 021 GRY | 20 |
| 21 | AGFAIR- | 021 GRY | 21 |
| 22 | VFCP+ | | 22 |
| 23 | VFCP- | 023 GRY | 23 |
| 24 | VFC V+ | 024 GRY | 24 |
| 25 | VFC V- | 025 GRY | 25 |
| 26 | UTIL_PRESS+ | 026 GRY | 26 |
| 27 | UTIL_PRESS- | 027 GRY | 27 |
| 28 | UTIL_VENT+ | 028 GRY | 28 |
| 29 | UTIL_VENT- | 029 GRY | 29 |
| 30 | SHEAR+ | 030 GRY | 30 |
| 31 | SHEAR- | 031 GRY | 31 |
| 32 | SC ISSOR+ | 032 GRY | 32 |
| 33 | SC ISSOR- | 033 GRY | 33 |
| 34 | VIT_ISO+ | 034 GRY | 34 |
| 35 | VIT_ISO- | 035 GRY | 35 |
| 36 | VIT4W AY+ | 036 GRY | 36 |
| 37 | VIT4WAY- | 037 GRY | 37 |
| 38 | SPARE+ | 038 GRY | 38 |
| 39 | SPARE- | 039 GRY | 39 |
| 40 | CUT_VENT+ | 040 GRY | 40 |
| 41 | CUT_VENT- | 041 GRY | 41 |
| 42 | CUT_PRESS+ | 042 GRY | 42 |
| 43 | CUT_PRESS- | 043 GRY | 43 |
| 44 | GND | 044 GRY | 44 |
| 45 | GND | 045 GRY | 45 |
| 46 | +12VA | 046 GRY | 46 |
| 47 | CUT2 | 047 GRY | 47 |
| 48 | UTIL2 | 048 GRY | 48 |
| 49 | CUT1 | 049 GRY | 49 |
| 50 | UTIL1 | 050 GRY | 50 |
| Ι'n | 31161 | | — <u>[</u> 30] |

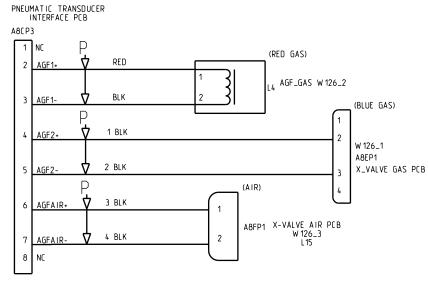
W122 - Console 212-2596-001 Cable, Pneu, Interface



W112 - Console 212-2504-001 Cable, Fan



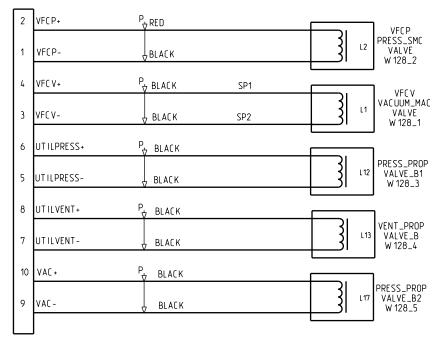
W125, 129, 130 - Console 212-2591-001 Cable, SMC Valve



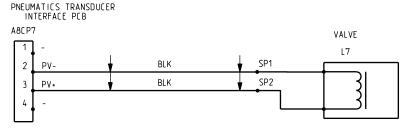
W126 - Console 212-2747-001 Cable, W126



PNEUMATICS TRANSDUCER INTERFACE PCB A8CP4

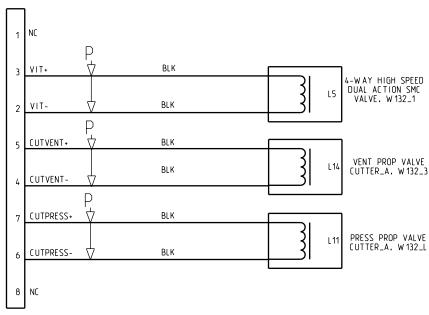


W128 - Console 212-2748-001 Cable, W128

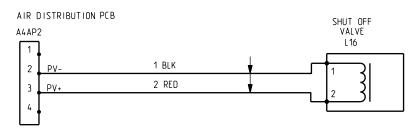


W131 - Console 212-2594-001 Cable, Vit

PNEUMATICS TRANSDUCER INTERFACE PCB A8CP8



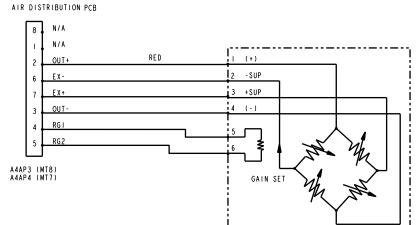
W132 - Console 212-2749-001 Cable, W132



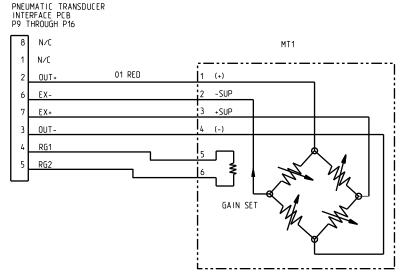
W135 - Console 212-2593-001 Cable, SMC Valve

Cables, Interconnect, Constellation Vision System

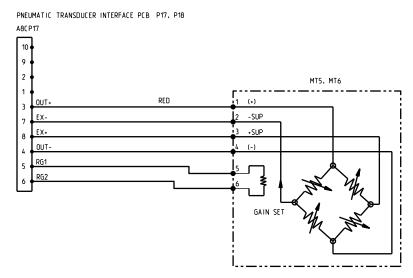




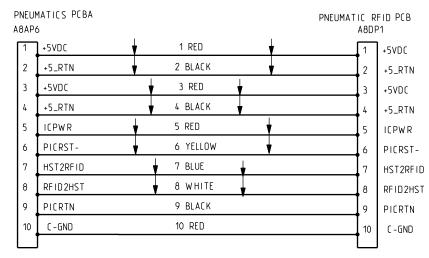
W136, 137 - Console 212-2588-001 Cable, Press Snsr 300



W139-146 - Console 212-2590-001 Cable, Press Snsr 100



W147, 149 - Console 212-2589-001 Cable, Press Snsr 30



W148 - Console 212-2595-001 Cable, RFID

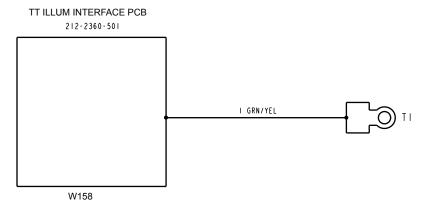
Cables, Interconnect, Constellation Vision System



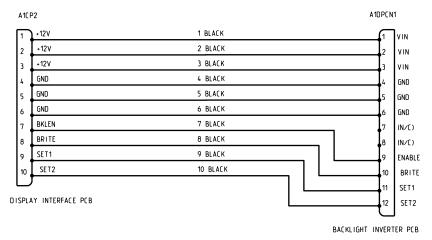


W162 - Console 212-1874-001 Cable, Display, IR Snsr Rt

W163 - Console 212-1874-002 Cable, Display, IR Snsr Lft



W158 - Console 212-2667-001 Cable, Illum Ground Strap



W161 - Console 212-1873-001 Cable, Display, BLT Invert



W164 - Console 212-1876-001 Cable, Disp, SD Card Reader

Cables, Interconnect, Constellation Vision System



SECTION SIX PARTS LISTS & DRAWINGS

CONTENTS

| DESCRIPTION | PART NUMBER PAGE# |
|------------------------------|--------------------|
| | _ |
| ASSY, CONSTELLATION, PREMIUM | .212-0000-501 6.2 |
| ASSY, TABLETOP | .212-5002-501 6.7 |
| ASSY, BASE UNIT, PREMIUM | .212-5003-501 6.19 |
| ASSY, IV POLE | .212-5004-501 6.26 |

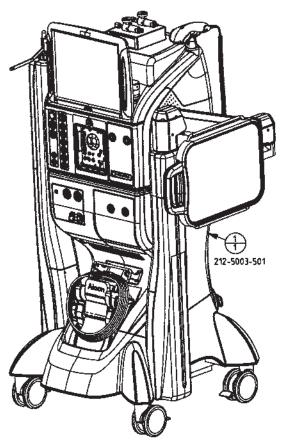


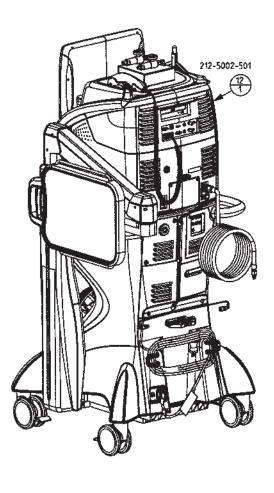
ITEM PART# DESCRIPTION QTY

| | 212-0000-501 | ASSY, CONSTELLATION, PREMIUM | |
|-----|--------------|------------------------------|---------|
| 001 | 212-5003-501 | ASSY,BASE UNIT,PREMIUM | 1.00 EA |
| 003 | 212-1478-001 | BALLAST,BASE UNIT | 4.00 EA |
| 004 | 807-063 | SCREW,CAP HD SKT,M8X35 SST | 4.00 EA |
| 005 | 212-2538-001 | TRAY,BALLAST,MACHINE | 1.00 EA |
| 006 | 807-061 | SCREW,CAP HD SKT,M8X25 SST | 4.00 EA |
| 007 | 801-008 | WASHER,FLAT,M8 SST | 6.00 EA |
| 800 | 212-1190-501 | ASSY,COLUMN,TRAY ARM | 1.00 EA |
| 009 | 782-262 | SCREW,SHOULDER,M6X1 303 SST | 4.00 EA |
| 010 | 212-1004-501 | ASSY,ARM,TRAY | 1.00 EA |
| 011 | 212-5004-501 | ASSY,IV POLE | 1.00 EA |
| 012 | 212-5002-501 | ASSY,TABLE TOP | 1.00 EA |
| 013 | 212-2959-501 | ASSY,HANGER,STATIONARY | 1.00 EA |
| 015 | 212-2248-001 | SCANNER,BAR CODE | 1.00 EA |
| 016 | 8065750977 | ASSY,FOOTSWITCH,CONSTEL | 1.00 EA |
| 017 | 212-2650-001 | HOSE ASSY,SUPPY,GAS | 1.00 EA |
| 018 | 212-1448-001 | PANEL, TABLETOP, REAR CONN | 1.00 EA |
| 019 | 825-020 | SCREW,CAP HD SKT,M4X35 SST | 2.00 EA |
| 020 | 212-2690-501 | ASSY,HOLDER,SCANNER | 1.00 EA |
| 024 | 212-2981-501 | ASSY,GAS AGF,EXTERNAL | 1.00 EA |
| 027 | 8065750968 | ASSY,SHIP,REMOTE CONSTEL | 1.00 EA |
| 028 | 212-2988-001 | LABEL,NOT FOR SALE | 1.00 EA |
| 029 | 212-2960-001 | COVER.DUST.MONOLITH | 1.00 EA |

| TABULATION | | |
|--------------|---------------------------------|--|
| PART NUMBER | DESCRIPTION | |
| 212-0000-501 | ASSY, CONTELLATION, PREMIUM | |
| 212-0000-502 | ASSY, CONTELLATION, NO IV POLE | |
| 212-0000-503 | CONSTELLATION. NO IV POLEALASER | |



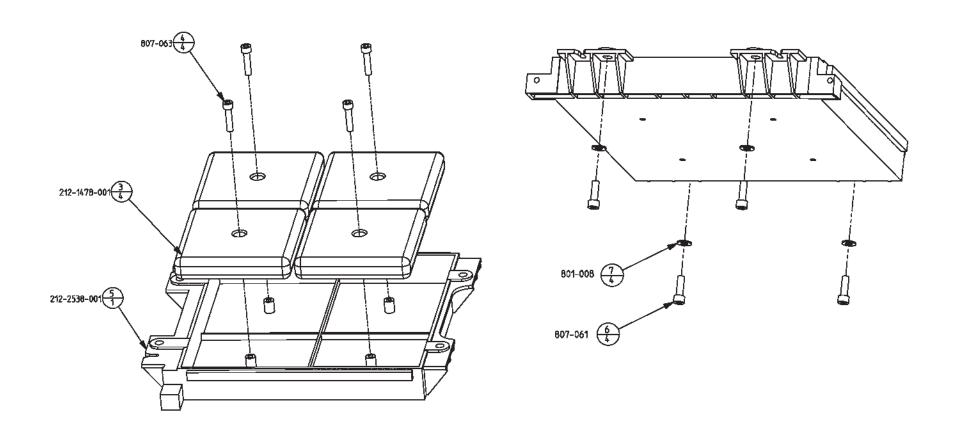




212-0000-501 SHOW N

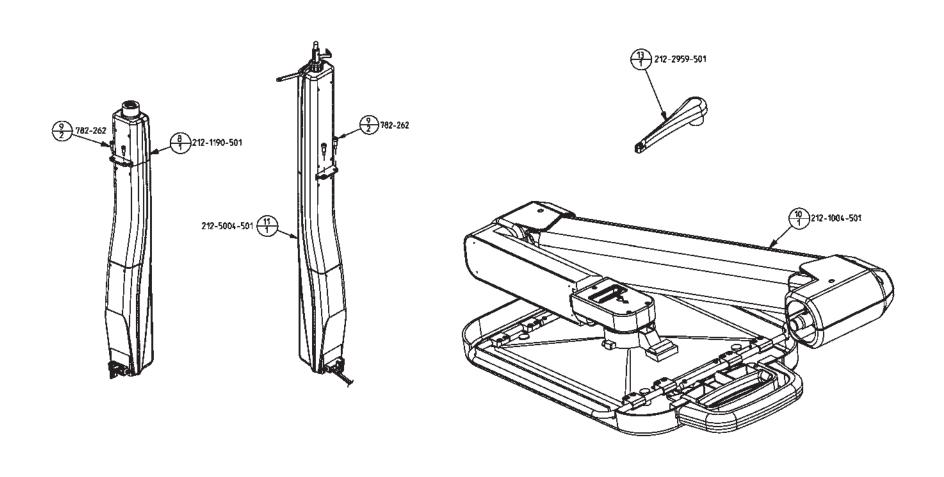
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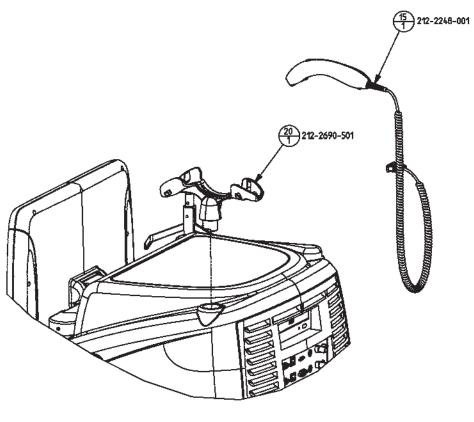


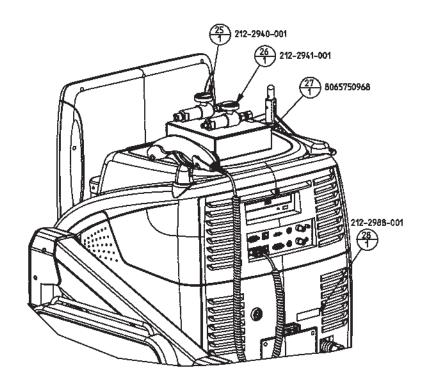
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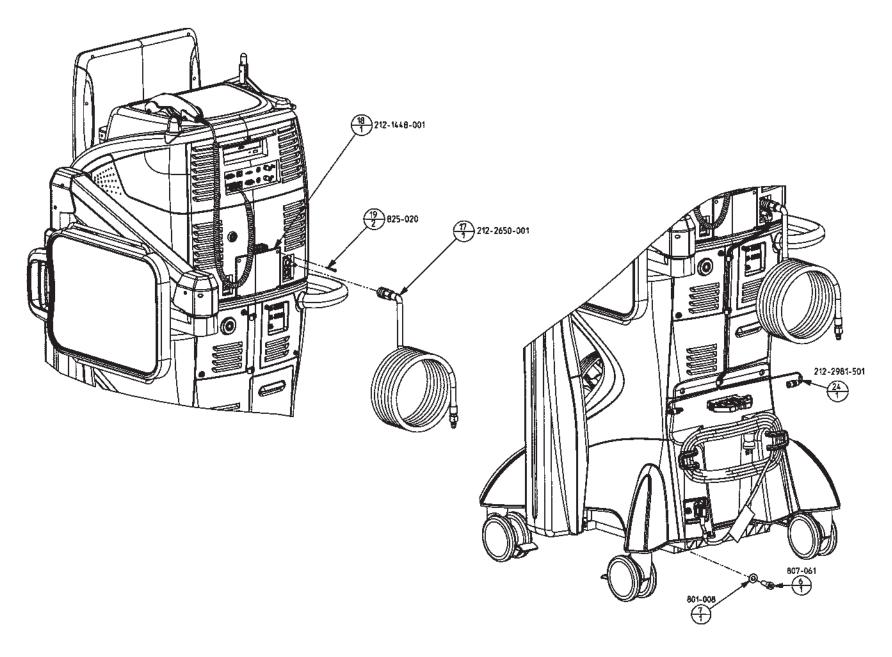










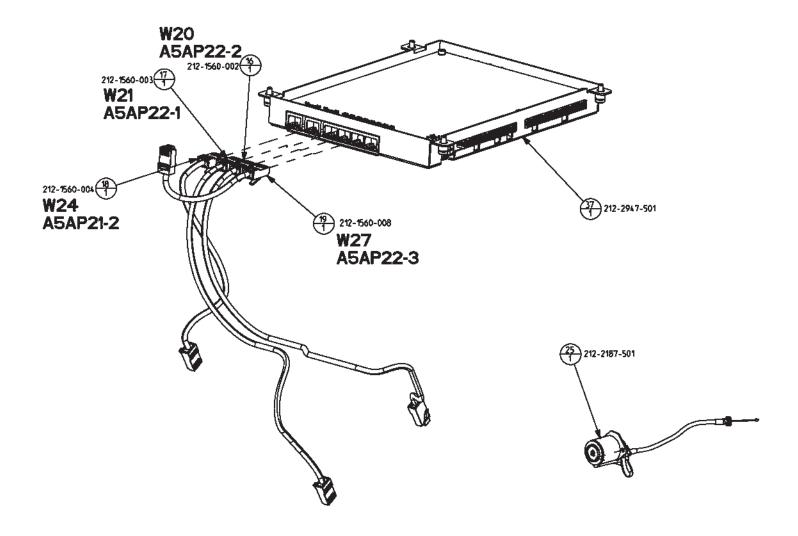


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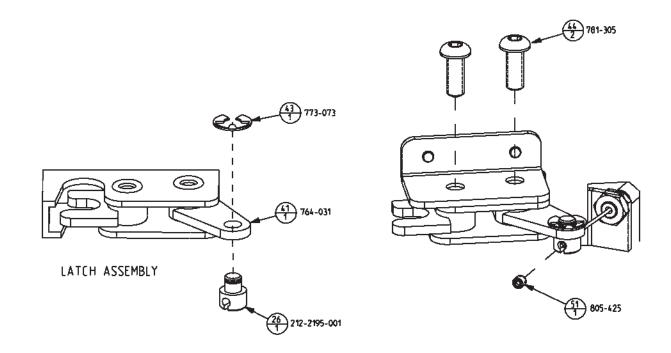
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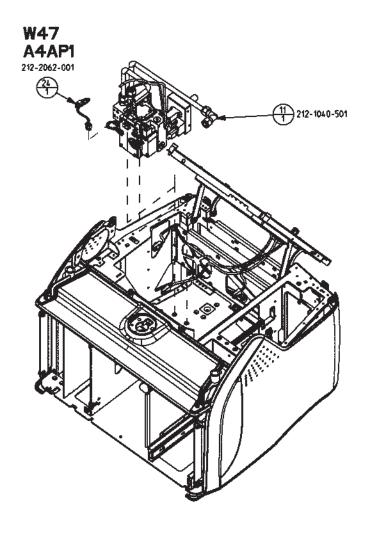


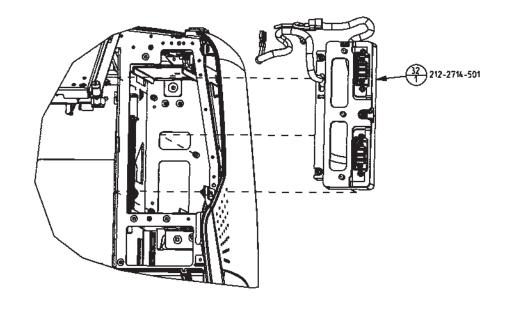
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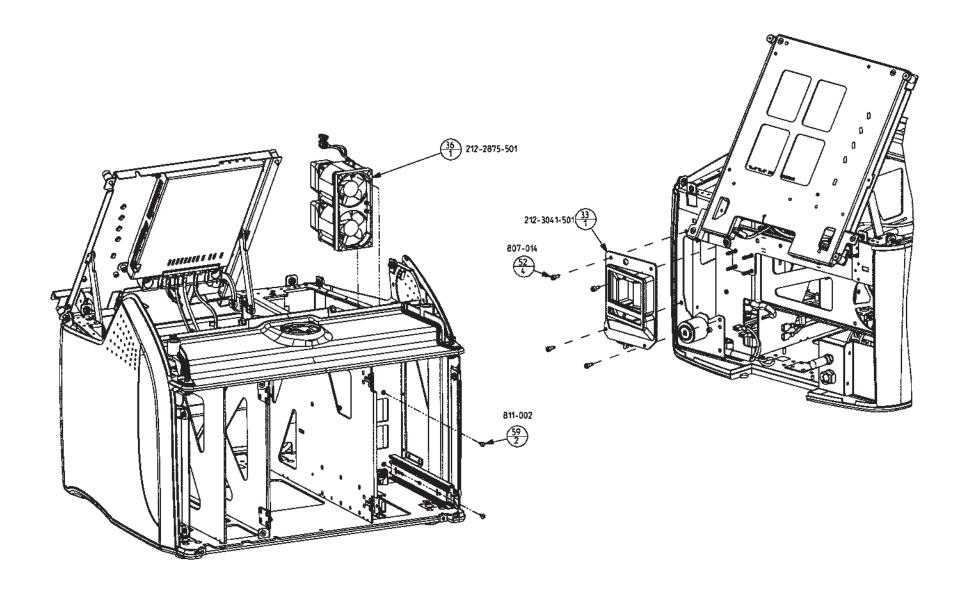






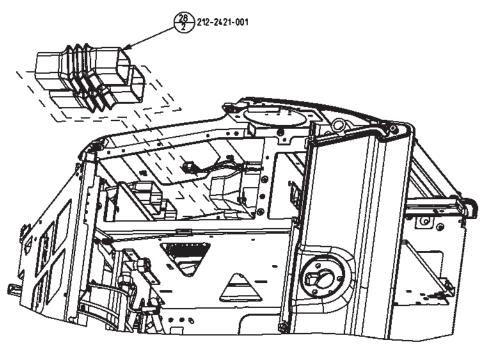


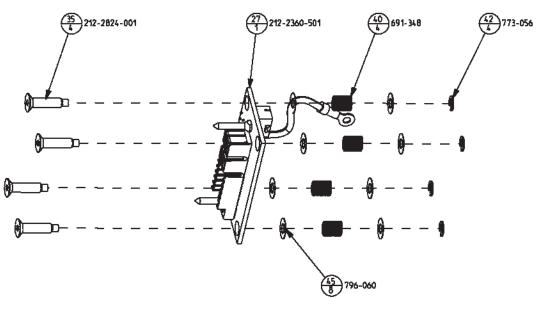




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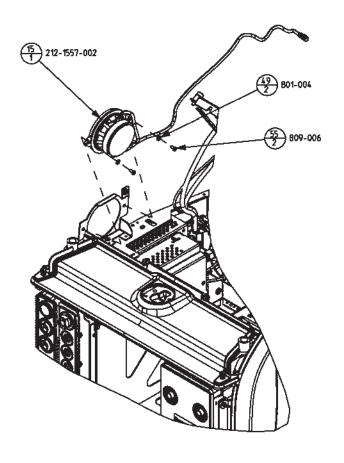


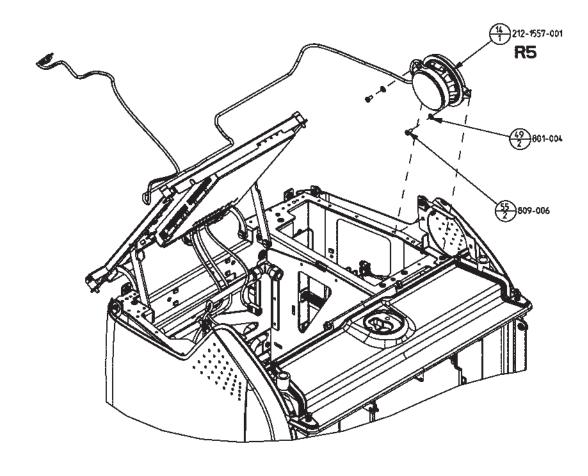




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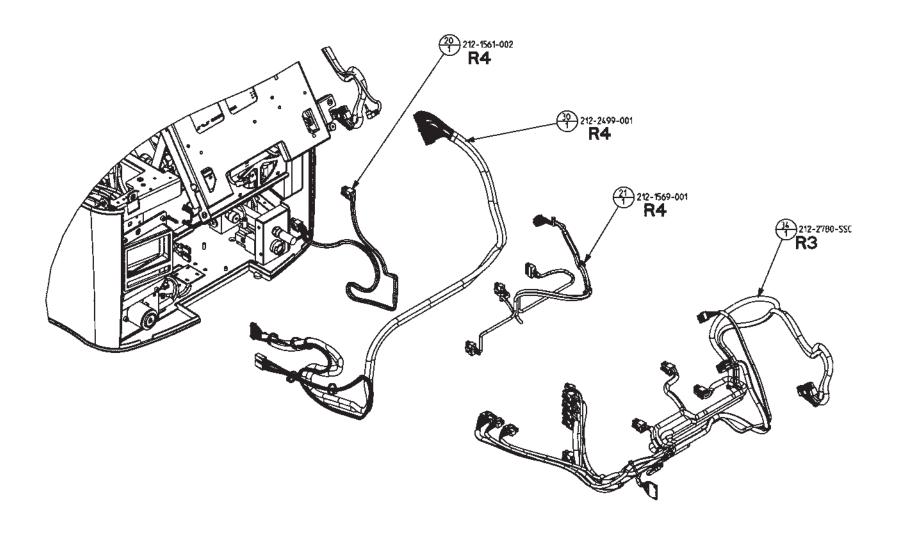


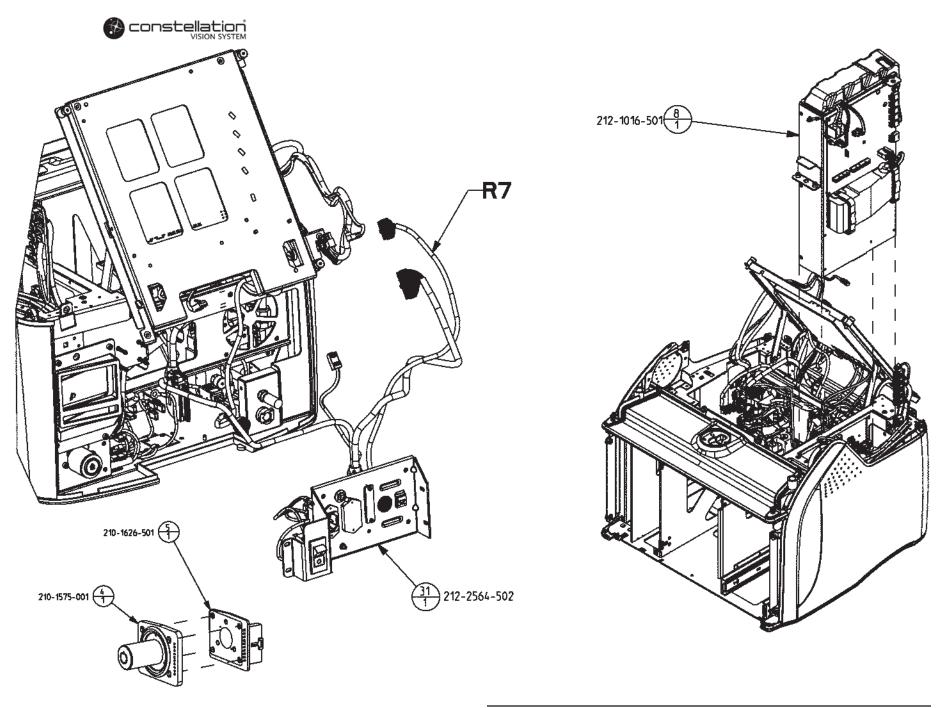




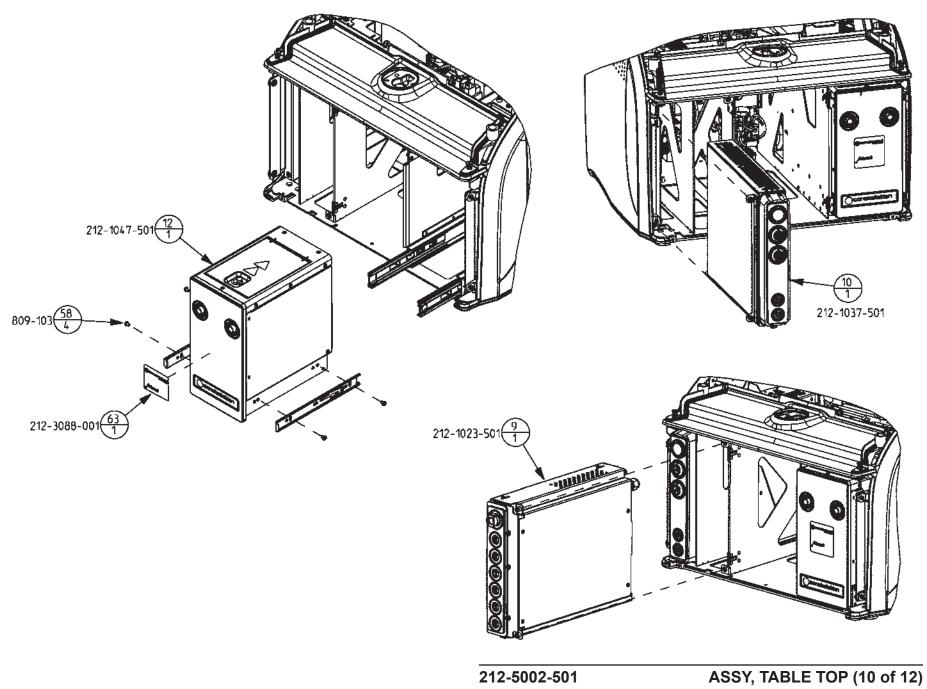
ASSY, TABLE TOP (7 of 12)



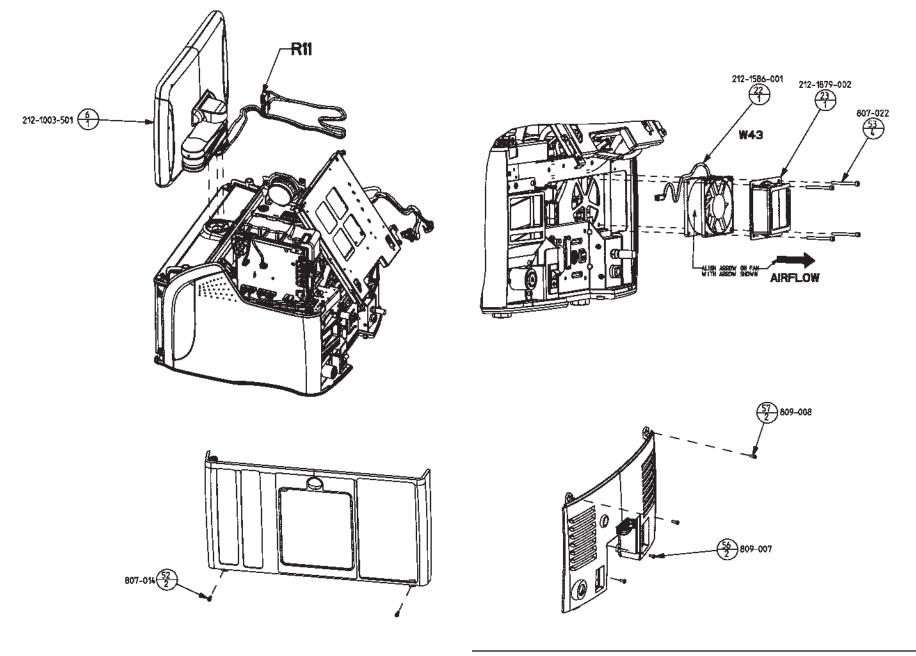






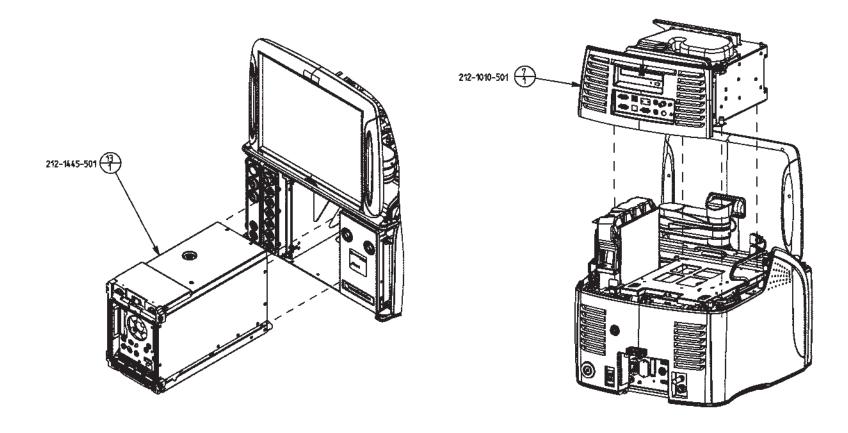






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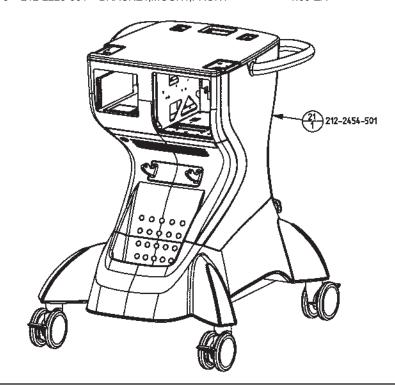






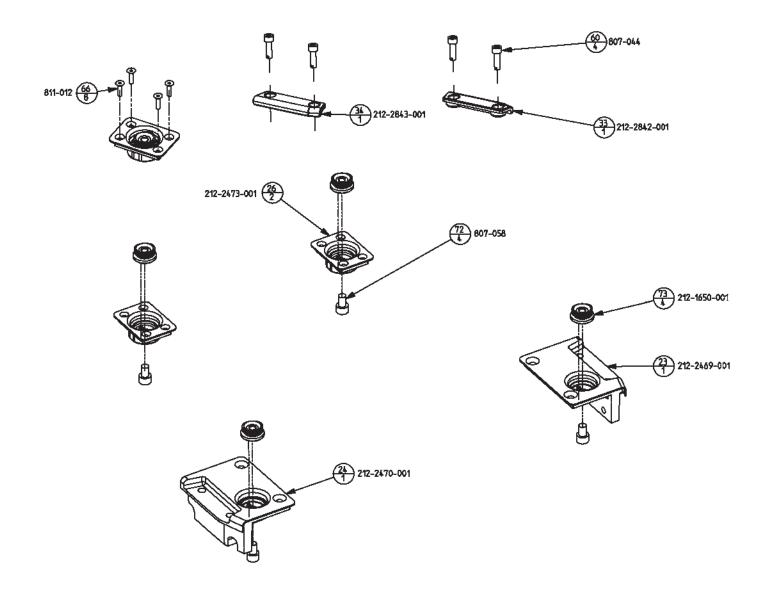
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|------|--------------|--------------------------------|---------|
| | 212-5003-501 | ASSY, BASE UNIT, PREMIUM | |
| 001 | 023-084 | CABLE ASSY,PWR CORD,12FT | 1.00 EA |
| 002 | 026-030 | CLAMP, CABLE, .312 DIA NYLON | 1.00 EA |
| 003 | 027-003 | CABLE TIE,.625X3.50L,NYLON | 7.00 EA |
| 004 | 027-009 | CABLE TIE,3.00X11.00L,NYLON | 9.00 EA |
| 005 | 054-278 | CONNECT,AC POWER,3 PRONG | 1.00 EA |
| 006 | 070-000 | POST,BINDING,M6X15 BRS/NKL | 1.00 EA |
| 007 | 212-1007-501 | ASSY,LASER | 1.00 EA |
| 800 | 212-1008-501 | ASSY,ILLUMINATOR,AUX | 1.00 EA |
| 009 | 212-1561-009 | CABLE ASSY,24V,DC W10 | 1.00 EA |
| 010 | 212-1642-002 | GROMMET,INTERCONNECT,CUT | 1.00 EA |
| 011 | 212-1646-501 | ASSY,BASE,SWITCH | 1.00 EA |
| 012 | 212-1678-001 | CABLE ASSY,FOOTSWITCH,W01 | 1.00 EA |
| 013 | 212-1727-501 | ASSY,PCB,INTERFACE BREAKOUT | 1.00 EA |
| 014 | 212-1957-001 | DUCT,INTERFACE,NGL | 1.00 EA |
| 015 | 212-1959-001 | BRACKET,REAR,INTERFACE CONN | 1.00 EA |
| 016 | 212-1996-001 | CABLE ASSY,NGL,REAR INTF | 1.00 EA |
| 017 | 212-2019-001 | CABLE ASSY, GROUND • EQUI W12 | 1.00 EA |
| 018 | 212-2048-501 | ASSY,PANEL,LASER REAR CART | 1.00 EA |
| 019 | 212-2164-501 | ASSY,POWER DISTRIBUTION,CART | 1.00 EA |
| 020 | 212-2342-501 | ASSY,BRACKET,UPPER CYL MTG | 1.00 EA |
| 021 | 212-2454-501 | ASSY,BASE,UNIT | 1.00 EA |
| 022 | 212-2456-001 | DUCT,OUTER,AUX ILLUM | 1.00 EA |
| 023 | 212-2469-001 | BRACKET,TRAY ARM,MACHINED | 1.00 EA |
| 024 | 212-2470-001 | BRACKET,IV POLE,MACHINED | 1.00 EA |
| 025 | 212-2472-501 | ASSY,PANEL, DUCT AUX ILLUM | 1.00 EA |
| 026 | 212-2473-001 | BRACKET,FOOT,TOP REAR | 2.00 EA |
| 027 | 212-2543-001 | WASHER,TAPERED,PCBA | 4.00 EA |
| 028 | 212-2665-501 | ASSY,PCB,INTERFACE EXTENDER | 1.00 EA |
| 029 | 212-2715-501 | ASSY,ACTUATOR,LATCH ILLUM | 1.00 EA |
| 030 | 212-2781-SSC | KIT,SSC,HARN ASSY BOT CNSL | 1.00 EA |
| 031 | 212-2832-001 | CABLE ASSY,GROUND,W37 | 1.00 EA |
| 032 | 212-2833-001 | CABLE ASSY,GROUND,W38 | 1.00 EA |
| 033 | 212-2842-001 | COVER,BRACKET,TRAY ARM RT | 1.00 EA |
| 034 | 212-2843-001 | COVER,BRACKET,TRAY ARM LT | 1.00 EA |
| 036 | 690-1121 | LABEL,GROUND | 1.00 EA |
| 037 | 691-347 | SPRING,CPRSN,.328ODX1.250 MW | 4.00 EA |
| 038 | 767-097 | NUT,HEX,4-40X.217X.066 | 2.00 EA |
| 039 | 796-131 | WASHER,FLAT,.228X.437X.030 | 4.00 EA |
| 040 | 796-137 | WASHER,FLAT,.218X.375X.062 NYL | 4.00 EA |
| 041 | 797-017 | WASHER,SPLT LK,.19X.33X.05 | 2.00 EA |
| 042 | 797-022 | WASHER,SPLT LK,.25X.49X.06 | 1.00 EA |
| 043 | 797-064 | WASHER,EXT LOCK.20X.41X.03 | 5.00 EA |
| 044 | 797-065 | WASHER,EXT LOCK.26X.51X.03 | 1.00 EA |
| 045 | 798-340 | WASHER,SHLDR,NO.6 .125 LG | 2.00 EA |
| 046 | 800-103 | WASHER,EXT LOCK,M3 | 4.00 EA |
| 047 | 801-003 | WASHER,FLAT,M3 | 4.00 EA |
| 048 | 801-004 | WASHER,FLAT,M4 | 7.00 EA |
| 049 | 801-006 | WASHER,FLAT,M6 | 6.00 EA |
| 050 | 801-039 | WASHER,GRN/YEL,.241ID X.655 OD | 1.00 EA |
| 051 | 803-006 | NUT,HEX,M6X1 | 2.00 EA |
| | | | |

| 052 | 805-425 | SETSCREW.SKT HD,FLT M4X4 | 1.00 EA |
|-----|--------------|------------------------------|---------|
| 053 | 807-002 | SCREW,CAP HD SKT,M3X6 | 2.00 EA |
| 054 | 807-004 | SCREW,CAP HD SKT,M3X10 | 8.00 EA |
| 055 | 807-013 | SCREW,CAP HD SKT,M4X8 | 3.00 EA |
| 056 | 807-014 | SCREW,CAP HD SKT,M4X10 | 7.00 EA |
| 057 | 807-015 | SCREW,CAP HD SKT,M4X12 | 6.00 EA |
| 058 | 807-017 | SCREW,CAP HD SKT,M4X20 | 4.00 EA |
| 059 | 807-043 | SCREW,CAP HD SKT,M6X16 | 4.00 EA |
| 060 | 807-044 | SCREW,CAP HD SKT,M6X20 | 4.00 EA |
| 063 | 809-007 | SCREW,BTN HD SKT,M4X10 | 1.00 EA |
| 064 | 809-103 | SCREW,BTN HD SKT,M4X6 | 8.00 EA |
| 065 | 811-002 | SCREW,FLAT HD SKT,M3X8 | 2.00 EA |
| 066 | 811-012 | SCREW,FLAT HD SKT,M4X16 | 8.00 EA |
| 067 | 811-032 | SCREW,FLAT HD SKT,M6X16 | 4.00 EA |
| 068 | 892-354 | ADHESIVE, LOCTITE 2440 BLUE | .00 EA |
| 069 | 212-2800-001 | SLIDE,DRAWER,7.9LGX7.9 | 2.00 EA |
| 070 | 212-2761-001 | BRACKET,COVER,REAR | 1.00 EA |
| 071 | 212-2837-501 | ASSY,PANEL,LASER REAR CART | 1.00 EA |
| 072 | 807-058 | SCREW,CAP HD SKT,M8X12 | 4.00 EA |
| 073 | 212-1650-001 | CAP,BASE | 4.00 EA |
| 074 | 212-2568-002 | FACEPLATE, NON LASER PAINTED | 1.00 EA |
| 075 | 212-2225-001 | BRACKET,MOUNT,FRONT | 1.00 EA |



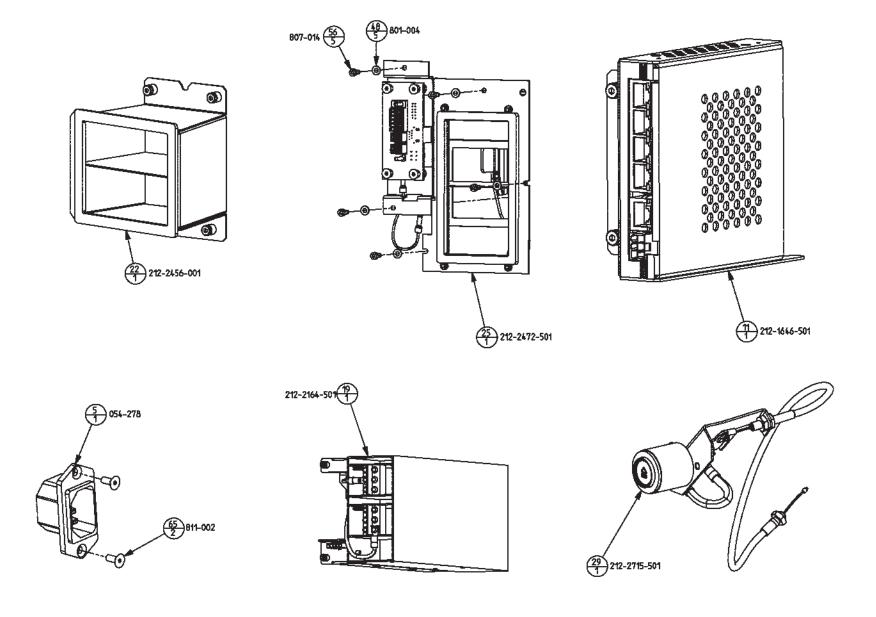
ASSY, BASE UNIT, PREMIUM (1 of 7)





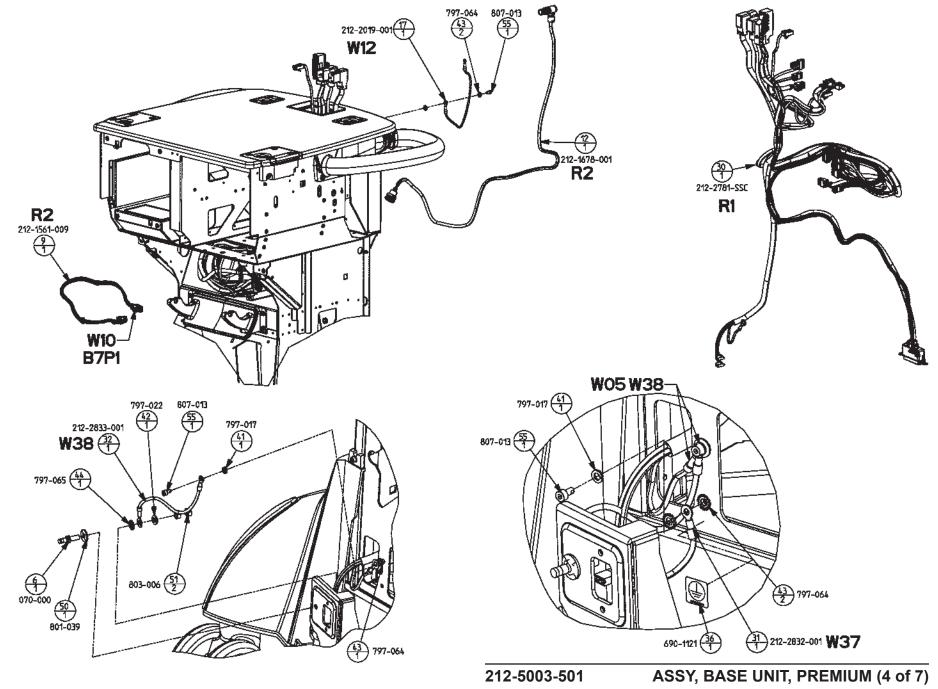
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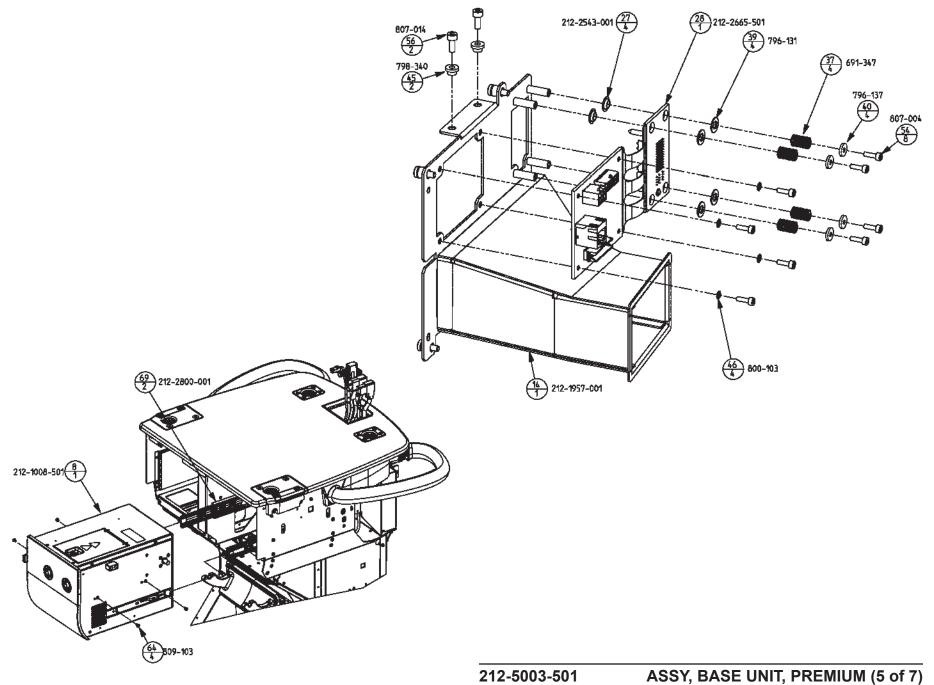


ASSY, BASE UNIT, PREMIUM (3 of 7)

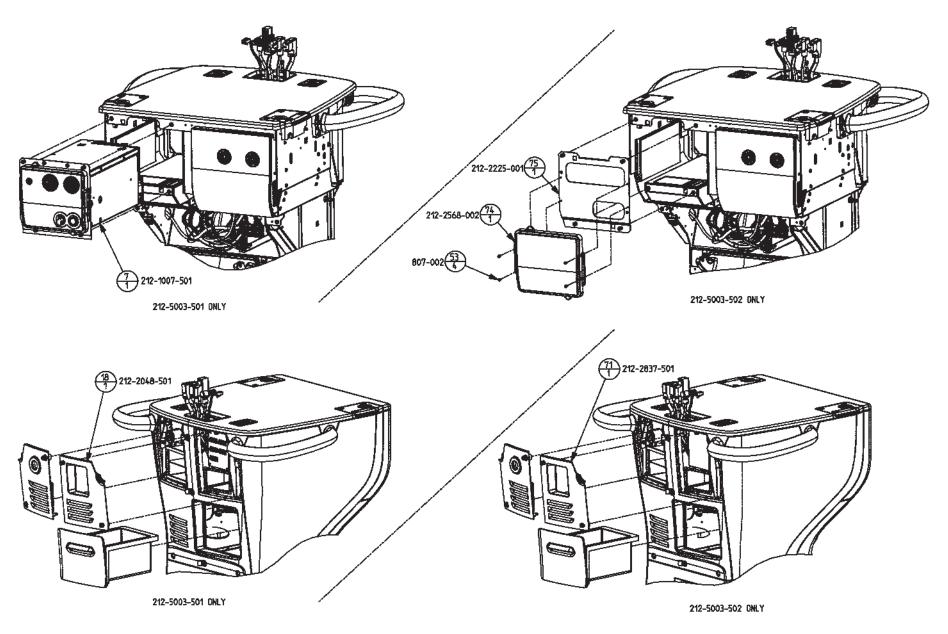








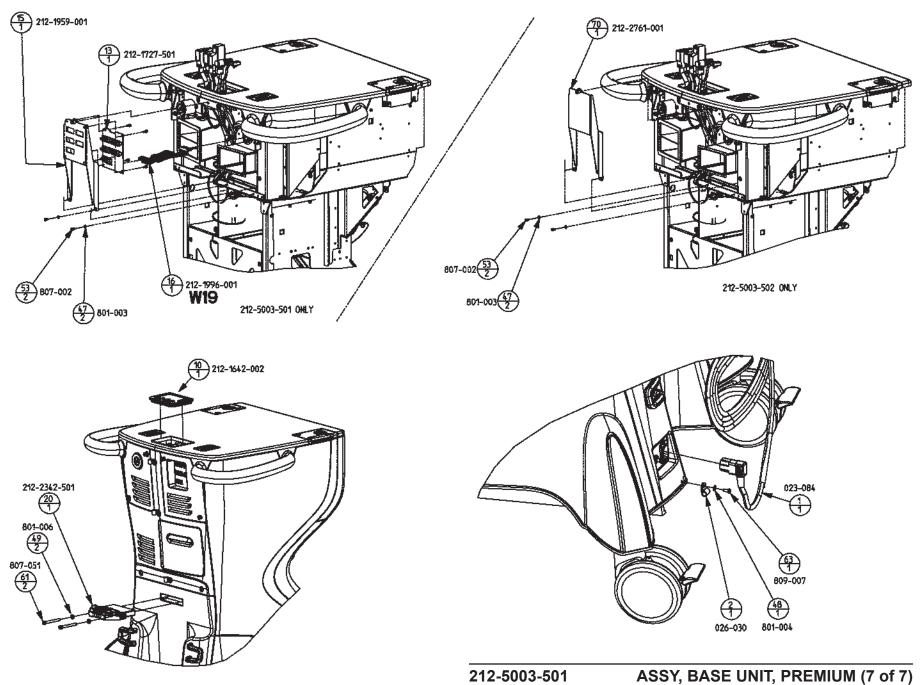




ASSY, BASE UNIT, PREMIUM (6 of 7)

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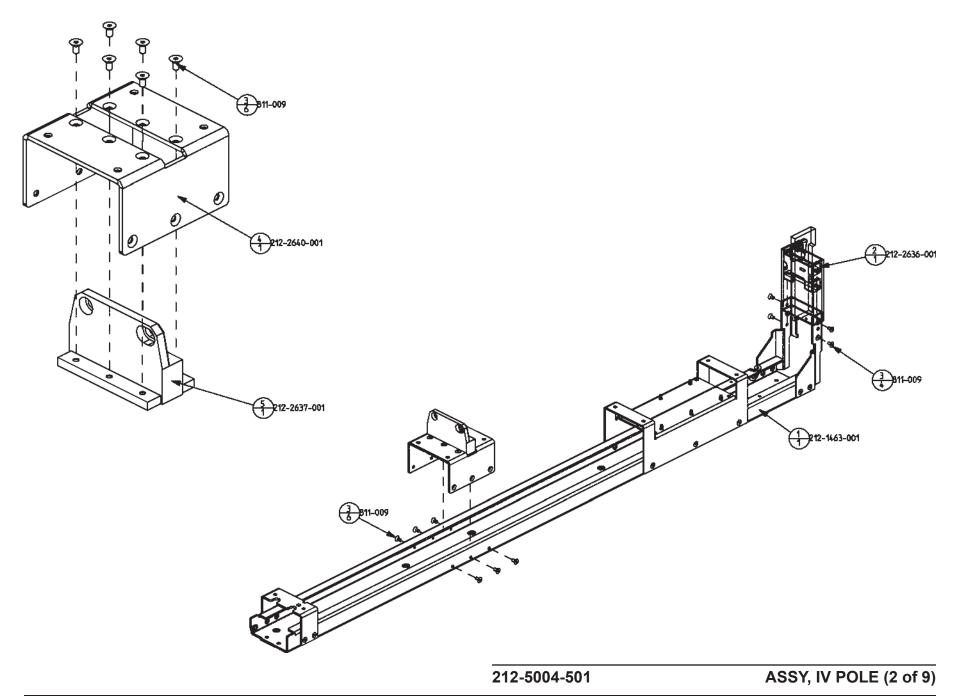




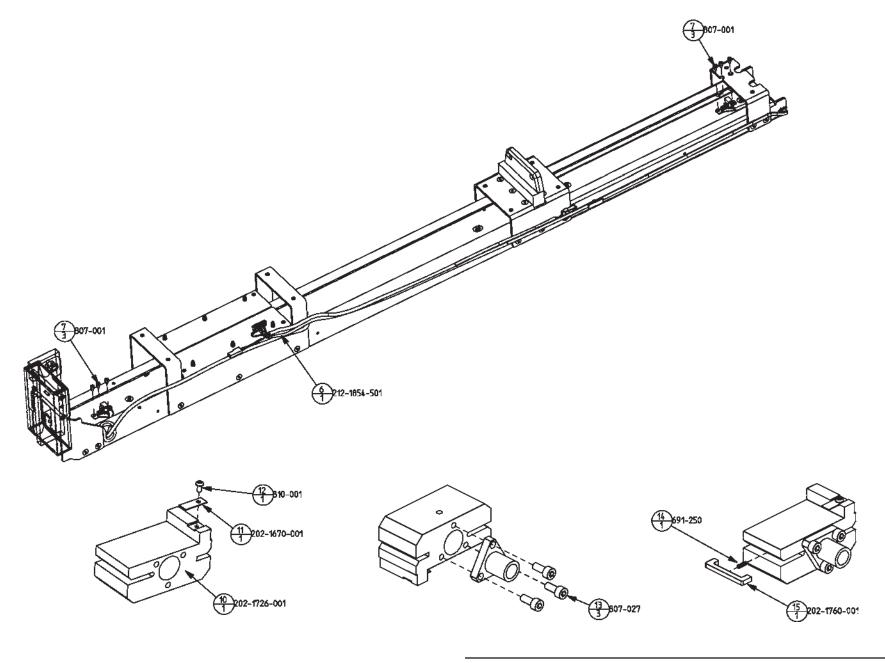


ITEM PART# **DESCRIPTION** QTY 212-5004-501 IV POLE 001 212-1463-001 FRAME.SUPPORT.IV POLE 1.00 EA 212-2438-001 BRACKET, IV POLE, LOW MOUNTING 1.00 EA 811-009 SCREW,FLAT HD SKT,M4X8 SST 23.0 EA 004 212-2640-001 **BRACKET, MOUNTING** 1.00 EA 005 212-2637-001 MOUNT, TOWER, UPPER 1.00 EA 212-1854-501 ASSY.CABLE.IV POLE SENSOR 1.00 EA 007 807-001 SCREW.CAP HD SKT.M3X5 SST 6.00 EA 800 026-091 CABLE, MOUNT, .75X.75 ABS WHT 4.00 EA 027-003 CABLE TIE,.625X3.50L,NYLON 009 7.00 EA 202-1726-001 GUIDE, NUT CARRIER, IV POLE 1.00 EA 010 202-1670-001 TARGET, SENSOR 1.00 EA 011 012 810-001 SCREW, BTN HD SKT, M3X6 BLK 2.00 EA 807-027 013 SCREW, CAP HD SKT, M5X12 SST 3.00 EA 691-250 SPRING, CPRSN, .31X.120 OD SST 1.00 EA 014 202-1760-001 PLATE, SLIDE CARRIER 1.00 EA 200-1744-001 GUIDE, FLANGE, BOTTOM 1.00 EA 016 811-020 SCREW.FLAT HD SKT.M5X12 SST 4.00 EA 017 202-1621-001 SCREW, LEAD, IV POLE 1.00 EA 018 SLEEVE, LDSCRW END, ACCURUS 1.00 EA 019 202-1778-001 773-034 1.00 EA 020 RING, RETAINING, .303 SHAFT 021 891-023 LUBRICANT, FLUOROCARBN GEL .00 OZ 022 202-1620-001 POLE, IV, ACCURUS 1.00 EA 023 805-052 SETSCREW,SKT HD,FLT M5X10 1.00 EA 025 200-1743-001 GUIDE, FLANGE, IV POLE 1.00 EA 026 200-1746-001 PLATE, MOUNTING, I/V POLE 1.00 EA 593-069 TAPE, VINYL, PRES-BOND .60 WIDE .00 FT 027 212-2486-001 1.00 EA 028 MOTOR ASSY.IV POLE.W/BRAKE 029 716-024 PULLEY, TIMING, 12 GROOVE 1.00 EA 805-029 030 SETSCREW,SKT HD,FLT M3X3 2.00 EA 031 892-042 ADHESIVE, THREADLOCKER, 242 .00 ML 701-019 BELT, TIMING, . 20 PITCH X9 CRCMF 032 1.00 EA 033 716-023 PULLEY.TIMING.36GROOVE 1.00 EA 034 805-050 SETSCREW,SKT HD,FLT M5X6 SST 2.00 EA 212-1481-501 ASSY,PCB,IV POLE 1.00 EA 212-1853-501 ASSY.CABLE.IV POLE INTERFACE 036 1.00 EA 212-2020-001 COVER.PCB.IV POLE 037 1.00 EA 212-1651-001 COVER.LOWER 1.00 EA 212-1483-002 039 PANEL, LOWER OUTER, POLE 1.00 EA 040 807-012 SCREW, CAP HD SKT, M4X6 SST 10.0 EA 212-1485-002 PANEL.UPPER OUTER.IV POLE 1.00 EA 042 212-1657-001 SWITCH.IV POLE 1.00 EA 043 212-1893-001 GASKET.TOP.IV POLE 1.00 EA 044 212-1484-002 PANEL, POLE, UPR INR TRAY PTD 1.00 EA 045 807-014 SCREW, CAP HD SKT, M4X10 SST 8.00 EA 046 212-1482-002 PANEL.LOWER INNER.POLE 1.00 EA 047 212-1894-001 GASKET, BOTTOM, IV POLE 1.00 EA 048 807-016 SCREW.CAP HD SKT.M4X16 SST 2.00 EA 049 212-1809-001 CAP, IV POLE 1.00 EA 212-1673-001 1.00 EA 050 HANGER ASSY, IV POLE 051 805-038 SETSCREW.SKT HD.FLT M4X3 SST 1.00 EA 212-5004-501 ASSY, IV POLE (1 of 9)





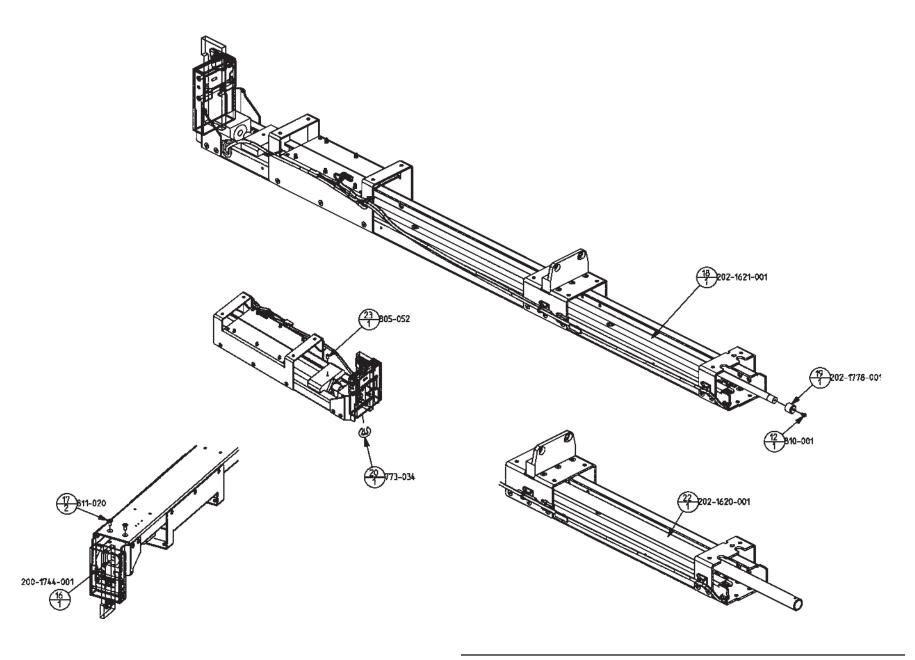




ASSY, IV POLE (3 of 9)

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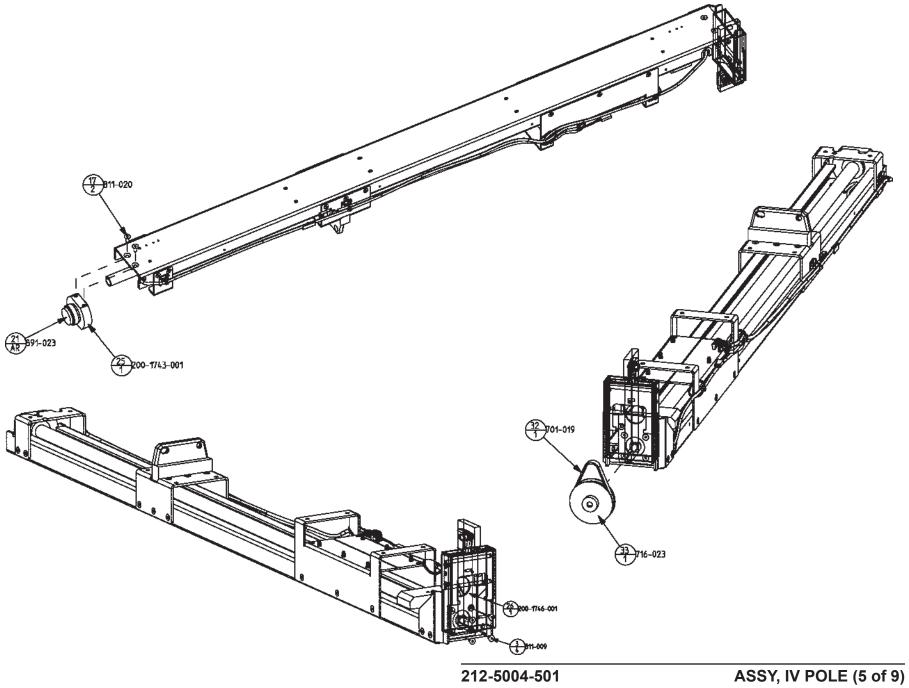


ASSY, IV POLE (4 of 9)

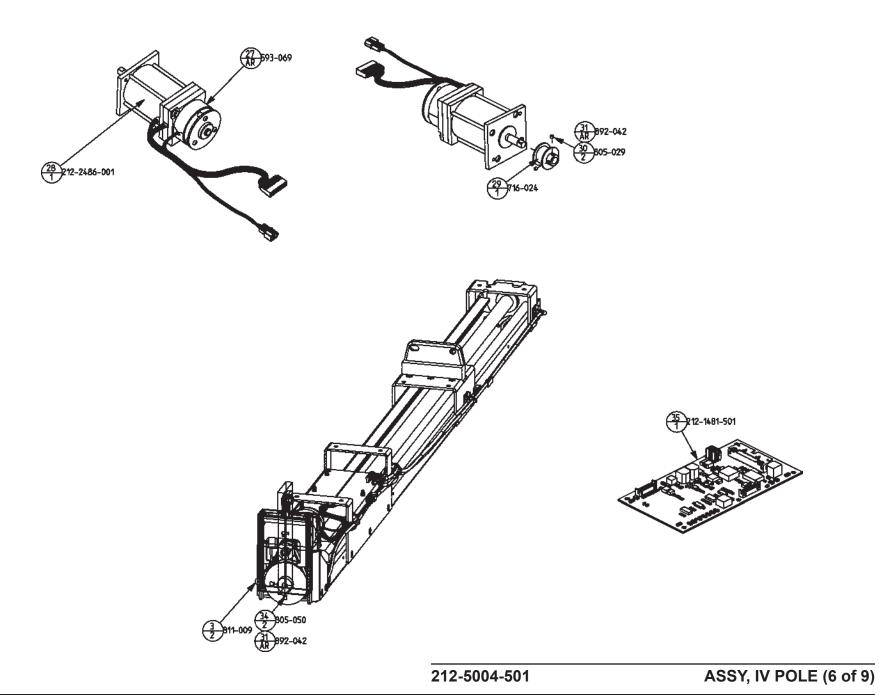
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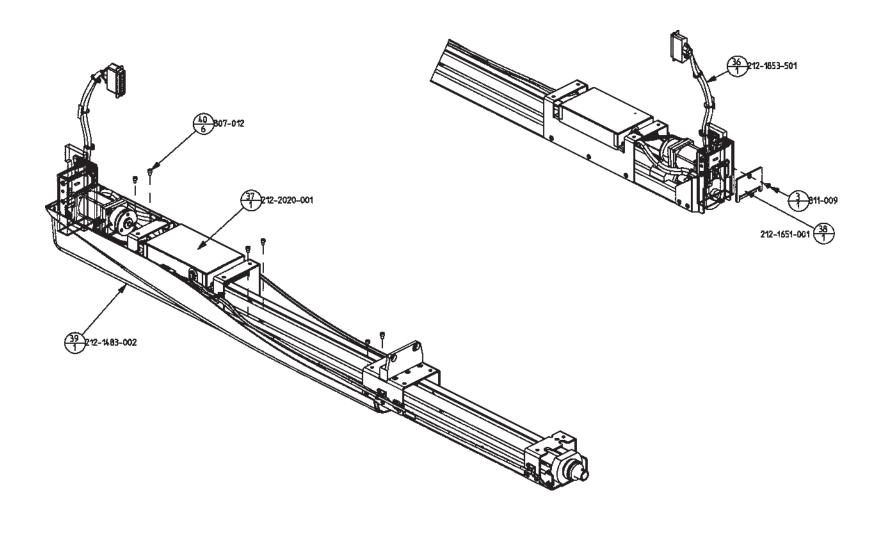






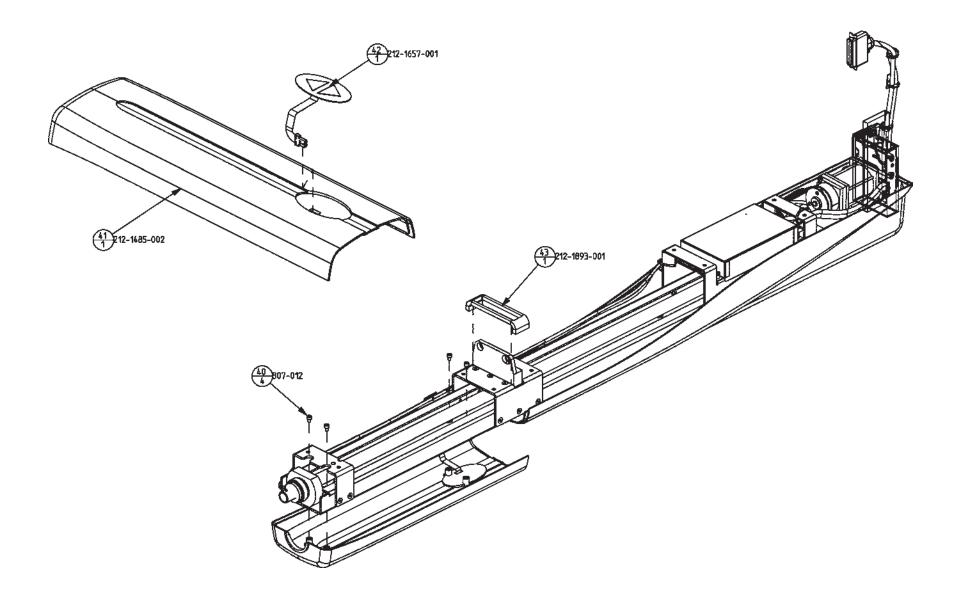






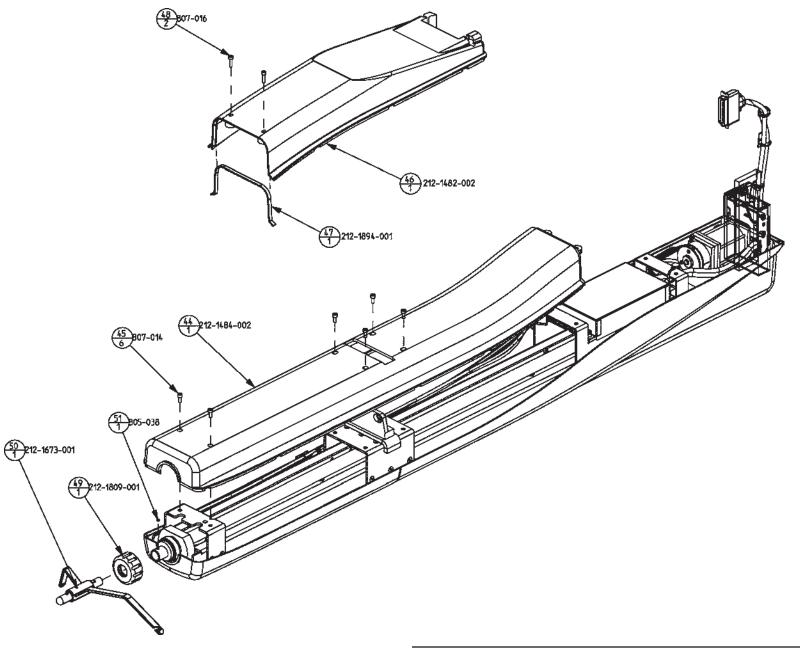
ASSY, IV POLE (7 of 9)





ASSY, IV POLE (8 of 9)





ASSY, IV POLE (9 of 9)



SECTION SEVEN ADDITIONAL INFORMATION

UNPACKING AND INSTALLATION

BASE CONSOLE

- 1. Cut two nylon bands securing top cover and remove.
- 2. Remove accessories (6) from foam insert and set aside (see Figure 7-1).

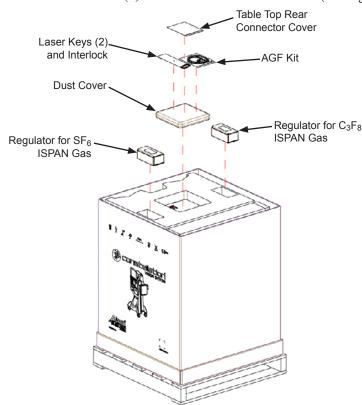


Figure 7-1. Base Console (Boxed) with Accessories

- 3. Remove accessory foam and wedge shaped foam and lift main box off the pallet.
- 4. Remove laser footswitch and illuminator lamp box from foam inserts on pallet.

- 5. Using at least two people, lift base console from foam packaging and pallet.
- 6. Remove all tape from front and rear of base console.
- 7. Install illuminator lamp into auxiliary illuminator.

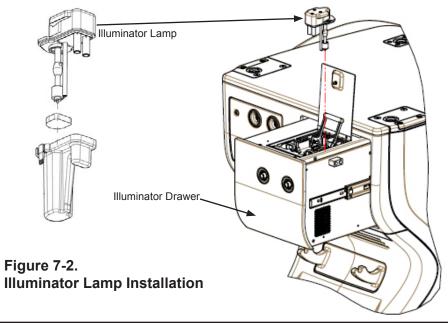
WARNING!

Wear safety glasses when handling illuminator lamps.

CAUTION

Do not touch lamp with bare hands.

- 7.1 Eject auxiliary illuminator module.
- 7.2 Remove cover from the lamp assembly.
- 7.3 Install lamp into auxiliary illuminator module.



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8. Remove cable grommet from top of base console and pull cabling into position to be connected to table top (see Figure 7-3).

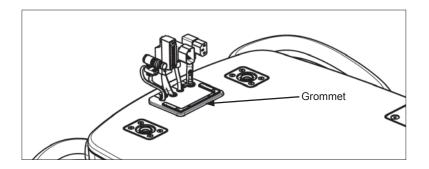


Figure 7-3. Grommet/Cabling from Base Console (shown with Table Top Installed)

TRAY ASSEMBLY

Note: The tray assembly can be installed on either side of the system; install per customer preference. Demo systems must have tray assembly installed on the left side (as you face the system). This procedure shows installation on the right side.

- 9. Remove the four ballasts and ballast tray from box.
- 10. Install two ballasts into tray using 6 mm hex bolts and partially slide ballast tray into guides in base console leaving enough room to install the remaining ballasts as shown in Figure 7-4. Install remaining ballasts.
- 11. Slide ballast tray into position and secure to base console using four 6 mm hex bolts and lock washers.



Figure 7-4. Ballast Installation

- 12 Remove tray arm assembly and tray tower from boxes.
- 13 Remove and discard bracket cover and two screws from side of base console (see Figure 7-5).

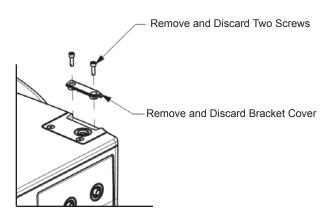


Figure 7-5. Bracket Removal



- 14 Attach upper part of tray arm tower to base console using two hex screws (see Figure 7-6).
- 15 Attach lower part of tray arm tower to base console using one hex screw and lock washer (see Figure 7-6).

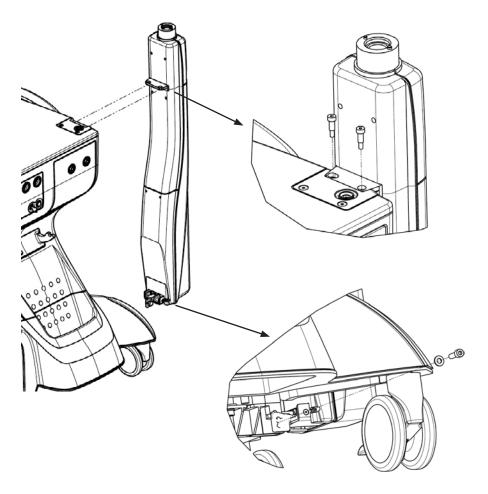


Figure 7-6. Tray Tower Installation

- 16 Refer to Fig 7-7. Remove skins from each side of the main tray arm joint (six 2.5 mm hex screws).
- 17 Loosen the 4 mm set screw on tray arm tower to allow tray arm joint to drop into place in tower.
- 18 Lower tray arm assembly onto tower so that holes on tray arm assembly fit into pins on tray arm tower.
- 19 Secure tray arm assembly to the tower using the 4 mm set screw.
- 20 Replace housing to each side of tray arm joint using six 2.5 mm hex screws.

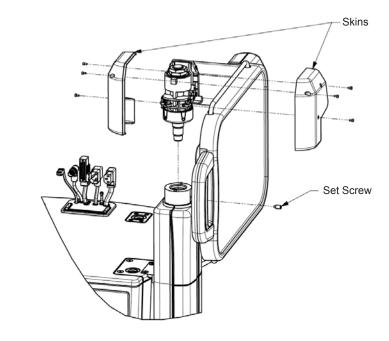


Fig 7-7. Attaching Tray Arm to Tray Tower



TABLE TOP

- 21. Cut two nylon bands securing top cover and remove.
- 22. Remove accessory bags and boxes from crate (see Figure 7-8).
 - **Dust Cover** WiFi Antenna > Stationary Hanger Barcode Scanner Holder Illuminator Lamp Remote Control Barcode Scanner Footswitch - Gas Supply Hose (N2/Air) - Ops Manual

- 23. Remove foam inserts and lift main box off pallet.
- 24. Using at least two people, lift Table Top from pallet and place on base console as shown in Figure 7-9. Ensure that four bolts extending from bottom of table top go into four holes in top of base console.

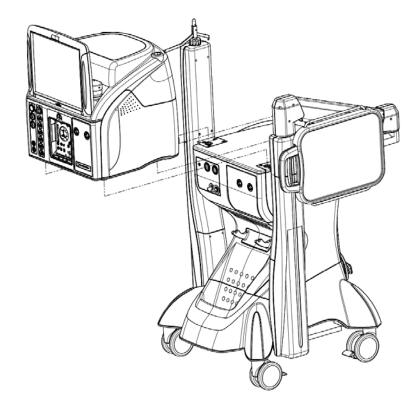


Figure 7-9. Table Top Placement on Base Console

Figure 7-8. Table Top (Boxed) with Accessories



25. Connect base console cables to table top as shown in Figure 7-10

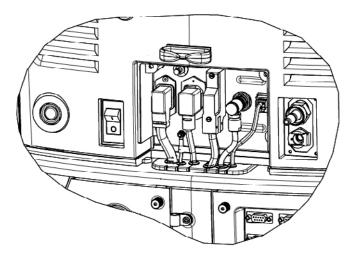


Figure 7-10. Table Top/Base Console Connections

- 26. Using the Table Top/Base Console Wrench, secure the table top to the base console by tightening the four bolts between the base and table top.
- 27. Attach cable cover (packaged with base console accessories) to rear of table top using two hex screws (see Figure 7-11).

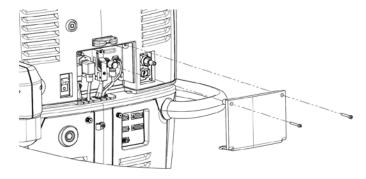


Figure 7-11. Rear Panel Connector Cover

28. Attach the stationary hangar and the barcode reader holder to the top cover (see Figure 7-12).

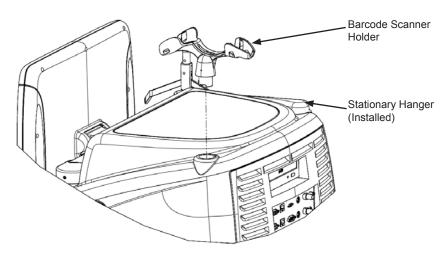


Figure 7-12. Installation of Barcode Scanner Holder and Stationary Hanger

- 29. Place the barcode reading in the holder and connect to the connector labeled with a barcode on the external connector panel.
- 30. Install illuminator lamp into table top illuminator (refer to auxiliary illuminator illustration in Figure 7-2).

WARNING!

Wear safety glasses when handling illuminator lamps.

CAUTION

Do not touch lamp with bare hands.

- 30.1 Eject table top illuminator module.
- 30.2 Remove cover from the lamp assembly.
- 30.3 Install lamp into auxiliary illuminator module.



- 31. Connect the *Constellation®* footswitch to the receptacle on the base console near the footswitch hangers.
- 32. Using the supplied pressure hose, connect the system to the preferred facility pressure source (see Figure 7-13). Additional fittings are supplied if required. Refer to the Maintenance section of this manual for instructions on changing the fittings.

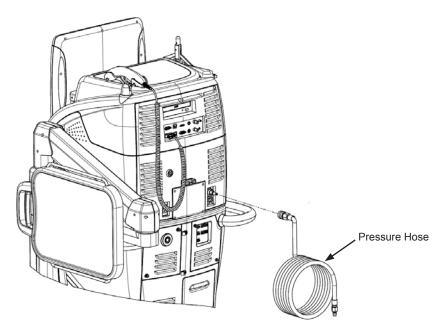


Figure 7-13. Pressure Hose Installation

33. Install ISPAN gas tubing as shown in Figure 7-14. Connect ends of tubing together. Place gas regulators into accessory drawer on rear of system.

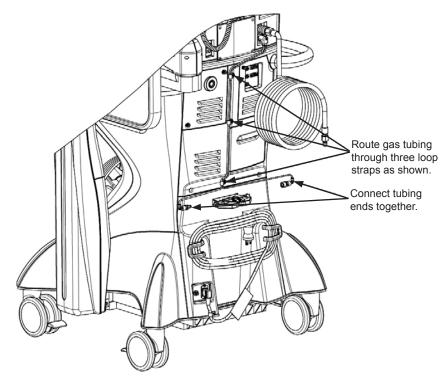


Figure 7-14. ISPAN Gas Tubing Installation